

S5048 and S7530 **Vector Network Analyzer**

Operating Manual First Edition



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INTRODUCTION

This Operating Manual contains design, specifications, functional overview, and detailed operation procedures for the Network Analyzer, to ensure effective and safe use of its technical capabilities by the user.

Maintenance and operation of the Analyzer should be performed by qualified engineers with basic experience in operating of microwave circuits and PC.

The following abbreviations are used in this Manual:

PC – Personal Computer

DUT - Device Under Test

IF – Intermediate Frequency

CW - Continuous Wave

SWR - Standing Wave Ratio

SAFETY INSTRUCTIONS

Carefully read the following safety instructions before putting the Analyzer into operation. Observe all the precautions and warnings provided in this Manual for all the phases of operation, service, and repair of the Analyzer.

The Analyzer should be used only by skilled and thoroughly trained personnel with the required skills and knowledge of safety precautions.

The Analyzer complies with INSTALLATION CATEGORY II as well as POLLUTION DEGREE 2 as defined in IEC61010–1.

The Analyzer is a MEASUREMENT CATEGORY I (CAT I) device. Do not use the Analyzer as a CAT II, III, or IV device.

The Analyzer is for INDOOR USE only.

The Analyzer has been tested as a stand-alone device and in combination with the accessories supplied by Copper Mountain Technologies, in accordance with the requirements of the standards described in the Declaration of Conformity. If the Analyzer is integrated with another system, compliance with related regulations and safety requirements are to be confirmed by the builder of the system.

Never operate the Analyzer in an environment containing flammable gasses or fumes.

Operators must not remove the cover or any other part of the housing. The Analyzer must not be repaired by the operator. Component replacement or internal adjustment must be performed by qualified maintenance personnel only.

Never operate the Analyzer if the power cable is damaged.

Never connect the test ports to A/C power mains.

Electrostatic discharge can damage the Analyzer whether connected to or disconnected from the DUT. Static charge can build up on your body and damage sensitive internal components of both the Analyzer and the DUT. To avoid damage from electric discharge, observe the following:

- Always use a desktop anti-static mat under the DUT.
- Always wear a grounding wrist strap connected to the desktop anti-static mat via daisy-chained 1 $M\Omega$ resistor.
- Connect the post marked = on the body of the Analyzer to the body of the DUT before you start operation.

Observe all general safety precautions related to operation of electrically energized equipment.

The definitions of safety symbols used on the instrument and in the Manual are listed below.

\triangle	Refer to the Manual if the instrument is marked with this symbol.
\sim	Alternating current.
	Direct current.
1	On (Supply).
0	Off (Supply).
7	A chassis terminal; a connection to the instrument's chassis, which includes all exposed metal surfaces.
WARNING procedure, practice, or condition that, if not co	
WARNING	This sign denotes a hazard. It calls attention to a procedure, practice, or condition that, if not correctly performed or adhered to, could result in injury or death to personnel.
CAUTION	procedure, practice, or condition that, if not correctly performed or adhered to, could result in injury or

1 GENERAL OVERVIEW

1.1 Description

The S5048/S7530 Network Analyzer is designed for use in the process of development, adjustment and testing of various electronic devices in industrial and laboratory facilities, including operation as a component of an automated measurement system. The Analyzer is designed for operation with an external PC, which is not supplied with the Analyzer.

1.2 Specifications

1.2.1 Basic Specifications

Table 1.1 Basic Specifications

1	2
Test ports	
S5048	2 N socket ports, 50Ω
S7530	2 N socket ports, 75Ω
Frequency range	
S5048	20 kHz to 4.8 GHz
S7530	20 kHz to 3.0 GHz
CW frequency accuracy	±5×10 ⁻⁶
Frequency setting resolution	10 Hz
Number of measurement points	1 to 200,001
Measurement bandwidth	10 Hz to 30 kHz
	(with 1/1.5/2/3/5/7 steps)
Dynamic range (IF bandwidth 10 Hz)	
From 20 kHz to 300 kHz:	100 dB, 110 dB typical
From 300 kHz to 4.8 GHz:	120 dB, 123 dB typical

Table 1.1 (continued)

1	2
Magnitude/phase transmission measurement accuracy ¹ , $ S_{11} $ and $ S_{22} $ less than -32 dB; $ S_{21} $ and $ S_{12} $ as follows:	
+5 dB to +10 dB	0.2 dB/2°
-50 dB to +5 dB	0.1 dB/1°
-70 dB to -50 dB	
From 20 kHz to 300 kHz:	2.5 dB/11°
From 300 kHz to 4.8 GHz (\$5048):	0.5 dB/3°
From 300 kHz to 3.0 GHz (\$7530):	0.5 dB/3°
-90 dB to -70 dB	
From 300 kHz to 4.8 GHz (S5048):	2.5 dB/11°
From 300 kHz to 3.0 GHz (\$7530):	2.5 dB/11°
Magnitude/phase reflection measurement accuracy 1 ; $ S_{11} $ and $ S_{22} $ as follows:	
-15 dB to 0 dB	0.4 dB/3°
-25 dB to -15 dB	1.0 dB/6°
-35 dB to -25 dB	3.0 dB/20°
Trace noise (IF bandwidth 3 kHz)	
From 20 kHz to 300 kHz:	0.005 dB RMS
From 300 kHz to 4.8 GHz (S5048):	0.002 dB RMS
From 300 kHz to 3.0 GHz (S7530):	0.002 dB RMS
Temperature dependence (per one degree of temperature variation)	0.02 dB

The specifications of the Analyzer apply over the temperature range of 23 °C ± 5 °C (unless otherwise specified) after 40 minutes of warming-up, with less than 1 °C deviation from the full two-port calibration temperature, at output power of -5 dBm, and IF bandwidth 10 Hz.

Connector type N, 50Ω :	
Effective directivity	46 dB
Effective source match	40 dB
Effective load match	46 dB
Connector type N, 75Ω :	
Effective directivity	46 dB
Effective source match	40 dB
Effective load match	46 dB
1	2
Uncorrected directivity	18 dB
Uncorrected output port match	22 dB
Output power level	-50 dBm to +5 dBm
Output power level accuracy	±1.0 dB
Output power resolution	0.05 dB
Harmonic distortion	-25 dBc
Non-harmonic spurious	-30 dBc
Uncorrected input port match	22 dB
Damage level	23 dBm
Damage DC voltage	35 V
Receiver noise floor (IF bandwidth 10 Hz)	
From 20 kHz to 300 kHz:	-95 dBm
From 300 kHz to 4.8 GHz (S5048):	-115 dBm
From 300 kHz to 3.0 GHz (S7530):	-115 dBm
Measurement time per point	200 μs
Source to receiver switchover time	10 ms
External frequency reference	10 MHz
External frequency reference input level	$2 dBm \pm 3 dB$
External frequency reference input impedance	50 Ω
Frequency reference input/output connector type	BNC female
Output reference signal level into 50Ω	$3 \text{ dBm} \pm 2 \text{ dB}$
Warm-up time, minimum	40 minutes

Power supply, external DC	9-15 V
Power consumption, external DC	10 W
Dimensions LxWxH	267x160x44 mm

Table 1.1 (continued)

1	2
Weight	1.3 kg
Operating conditions:	
– environmental temperature	5 °C to 40 °C
– humidity at 25 °C	90%
– atmospheric pressure	84 to 106.7 kPa

1.2.2 Measurement Capabilities

Measured parameters	$S_{11}, S_{21}, S_{12}, S_{22}$					
	Absolute power of the reference and received signals at the port.					
Number of measurement channels	Up to 16 logical channels. Each logical channel is represented on the screen as an individual channel window. A logical channel is defined by such stimulus signal settings as frequency range, number of test points, power level, etc.					
Data traces	Up to 16 data traces can be displayed in each channel window. A data trace represents one of the following parameters of the DUT: S-parameters, response in the time domain, or input power response.					
Memory traces	Each of the 16 data traces can be saved into memory for further comparison with the current values.					
Data display formats	Logarithmic magnitude, linear magnitude, phase, expanded phase, group delay, SWR, real part, imaginary part, Smith chart format and polar format.					
Sweep setup features						
Sweep type	Linear frequency sweep, logarithmic frequency sweep, and segment frequency sweep, when the stimulus power is a fixed value; and linear power sweep when frequency is a fixed value.					
Measured points per sweep	From 2 to 200001.					
Segment sweep	A frequency sweep within several user-defined segments. Frequency range, number of sweep points, source power, and IF bandwidth can be set for each segment.					
Power settings	Source power from -50 dBm to +5 dBm with resolution of 0.05 dB. In frequency sweep mode the power slope can be set to up to 2 dB/GHz to compensate high frequency attenuation in cables.					
Sweep trigger	Trigger modes: continuous, single, hold. Trigger					

Trace display functions						
Trace display	Data trace, memory trace, or simultaneous data and memory traces.					
Trace math	Data trace modification by math operations: addition, subtraction, multiplication or division of measured complex values and memory data.					
Autoscaling	Automatic selection of scale division and reference level value to have the trace most effectively displayed.					
Electrical delay	Calibration plane compensation for delay in the test setup, or for electrical delay in a DUT during measurements of deviation from linear phase.					
Phase offset	Phase offset in degrees.					
Accuracy enhancement						
Calibration	Calibration of a test setup (which includes the Analyzer, cables, and adapters) significantly increases the accuracy of measurements. Calibration allows for correction of errors caused by imperfections in the measurement system: system directivity, source and load match, tracking, and isolation.					
Calibration methods	The following calibration methods of various sophistication and accuracy enhancement are available:					
	 reflection and transmission normalization; 					
	• full one-port calibration;					
	one-path two-port calibration					
	• full two-port calibration;					
	■ TRL calibration.					
Reflection and transmission normalization	The simplest calibration method. It provides limited accuracy.					
Full one-port calibration	Method of calibration performed for one-port reflection measurements. It ensures high accuracy.					

One-path two-port calibration	Method of calibration performed for reflection and one-way transmission measurements, for example for measuring S_{11} and S_{21} only. It ensures high accuracy for reflection measurements, and reasonable accuracy for transmission measurements.						
Full two-port calibration	Method of calibration performed for full S-parameter matrix measurement of a two-port DUT. It ensures high accuracy.						
TRL calibration	Method of calibration performed for full S-parameter matrix measurement of a two-port DUT. LRL and LRM types of this calibration are also supported. In ensures higher accuracy than a two-port calibration.						
Mechanical calibration kits	The user can select one of the predefined calibration kits of various manufacturers or define additional calibration kits.						
Electronic calibration modules	Copper Mountain automatic calibration modules make the Analyzer calibration faster and easier than traditional mechanical calibration.						
Sliding load calibration standard	The use of sliding load calibration standard allows significant increase in calibration accuracy at high frequencies compared to a fixed load calibration standard.						
Unknown thru calibration standard	The use of an arbitrary reciprocal two-port device instead of a zero-length thru during a full two-port calibration allows for calibration of the test setup for measurements of non-insertable devices.						
Defining of calibration standards	Different methods of calibration standard definition are available:						
	 standard definition by polynomial model 						
	 standard definition by data (S-parameters). 						
Error correction interpolation	When the user changes settings such as start/stop frequencies and number of sweep points, compared to the settings of calibration, interpolation or extrapolation of the calibration coefficients will be applied.						

Supplemental calibration methods						
Power calibration	Method of calibration, which allows for maintaining more stable power levels at the DUT input. An external power meter should be connected to the USB port directly or via USB/GPIB adapter. Method of calibration which calibrates the receiver gain at absolute signal power measurement.					
Receiver calibration						
Marker functions						
Data markers	Up to 16 markers for each trace. A marker indicates the stimulus value and measurement result at a given point of the trace.					
Reference marker	Enables indication of any maker value as relative to the reference marker.					
Marker search	Search for max, min, peak, or target values on a trace.					
Marker search additional features	User-definable search range. Available as either a tracking marker, or as a one-time search.					
Setting parameters by markers	Setting of start, stop and center frequencies from the marker frequency, and setting of reference level by the measurement result of the marker.					
Marker math functions	Statistics, bandwidth, flatness, RF filter.					
Statistics	Calculation and display of mean, standard deviation and peak-to-peak in a frequency range limited by two markers on a trace.					
Bandwidth	Determines bandwidth between cutoff frequency points for an active marker or absolute maximum. The bandwidth value, center frequency, lower frequency, higher frequency, Q value, and insertion loss are displayed.					
Flatness	Displays gain, slope, and flatness between two markers on a trace.					
RF filter Displays insertion loss and peak-to-peak rip passband, and the maximum signal magnit stopband. The passband and stopband are of two pairs of markers.						

Data analysis						
Port impedance conversion	The function converts S-parameters measured at 50 Ω port (75 Ω in the case of S7530) into values which would be found if measured at a test port with arbitrary impedance.					
De-embedding	The function allows mathematical exclusion of the effects of the fixture circuit connected between the calibration plane and the DUT. This circuit should be described by an S-parameter matrix in a Touchstone file.					
Embedding	The function allows mathematical simulation of the DUT parameters after virtual integration of a fixture circuit between the calibration plane and the DUT. This circuit should be described by an S-parameter matrix in a Touchstone file.					
S-parameter conversion	The function allows conversion of the measured S-parameters to the following parameters: reflection impedance and admittance, transmission impedance and admittance, and inverse S-parameters.					
Time domain transformation	The function performs data transformation from frequency domain into response of the DUT to various stimulus types in time domain. Modeled stimulus types: bandpass, lowpass impulse, and lowpass step. Time domain span is set by the user arbitrarily from zero to maximum, which is determined by the frequency step. Various window shapes allow optimizing the tradeoff between resolution and level of spurious sidelobes.					
Time domain gating	The function mathematically removes unwanted responses in time domain, allowing for obtaining frequency response without the influence of the fixture elements. The function applies a reverse transformation back to the frequency domain from the user-defined span in the time domain. Gating filter types: bandpass or notch. For better tradeoff between gate resolution and level of spurious sidelobes the following filter shapes are available: maximum, wide, normal and minimum.					

Scalar mixer / converter measurements	The scalar method allows measurement of scalar transmission S-parameters of mixers and other devices having different input and output frequencies. No external mixers or other devices are required. The scalar method employs port frequency offset when there is difference between receiver frequency and source frequency.					
Vector mixer / converter measurements	The vector method allows measuring of the mixe transmission S-parameter magnitude and phase. The method requires an external mixer and an LC common to both the external mixer and the mixe under test.					
Scalar mixer / converter calibration	The most accurate method of calibration applied for measurements of mixers in frequency offset mode. The OPEN, SHORT, and LOAD calibration standard are used. An external power meter should be connected to the USB port directly or via USB/GPIF adapter.					
Vector mixer /converter calibration	Method of calibration applied for vector mixe measurements. The OPEN, SHORT and LOAL calibration standards are used.					
Automatic adjustment of frequency offset	The function performs automatic frequency offse adjustment when scalar mixer / converte measurements are performed to compensate for LC frequency inaccuracies internal to the DUT.					
Other features						
Familiar graphical user interface	Graphical user interface based on the Window operating system ensures fast and easy Analyze operation by the user.					
Analyzer control	Using a personal computer.					
Printout/saving of traces	The traces and data printout function has a preview feature. Previewing, saving and printing can be performed using MS Word, Image Viewer fo Windows, or the Analyzer Print Wizard.					

Remote control

COM/DCOM

Remote control over COM/DCOM. COM automation runs the user program on an Analyzer PC. DCOM automation runs the user program on a LANnetworked PC.

1.3 Ordering Information

The Analyzer is designed for use with an external computer with keyboard and monitor, none of which are included. The Analyzer consists of the Analyzer Unit with connector ports of Type N or Type N 75, in accordance with GOST 51914-2002 PB. The devices are powered by an external source, which is also not included.

The parts lists of the S5048 and S7530 Analyzers are indicated in Tables 1.1 and 1.2, respectively.

Table 1.1 Parts list for S5048

Name	Part number	Count
Measuring unit	IB5048.1	1
USB cable	_	1
USB flash memory containing software and instruction manual	RE 6687–102–21477812– 2013	1
		1
Form	FD 6687–102–21477812– 2013	1

Table 1.2 Parts list for S7530

Name	Part number	Count
Measuring unit	IB7530.1	1
USB cable	-	1
USB flash memory containing software and instruction manual	RE 6687–102–21477812–2013	1 1
Form	FD 6687–102–21477812–2013	1

1.4 Principle of Operation

The block diagram of the Analyzer is represented in figure 1.1.

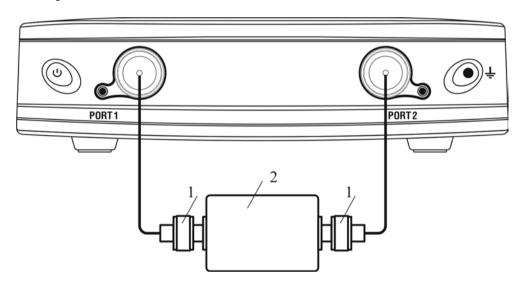
The Analyzer Unit consists of a source oscillator, local oscillator, source power attenuator, and a switch connecting the source signal to two directional couplers, which are connected to the Port 1 and Port 2 connectors. The incident and reflected waves from the directional couplers are passed into the mixers, where they are converted to first IF (0.4 MHz), and are passed further to the 4-Channel receiver. The 4-Channel

receiver, after filtering, digitally encodes the signal and supplies it for further processing (filtration, phase difference estimation, magnitude measurement) by the signal processor. The IF measurement filters are digital and have bandwidths of between 10 Hz and 30 kHz. Either port of the Analyzer can be a source of the tested signal as well as a receiver of the signal transferred thought the DUT. If port 1 is a source, port 2 will be a receiver. The definition "incident and reflected" wave is correct for the port when it is a source of the test signal. The combination of the assemblies of directional couplers, mixers and 4-Channel receiver forms four similar signal receivers.

An external PC controls the operation of the components of the Analyzer. To perform the S-parameter measurement, the Analyzer supplies the source signal of the assigned frequency from one of the ports to the DUT, then measures magnitude and phase of the signals transmitted and reflected by the DUT, and after that compares these results to the magnitude and phase of the source signal.

1.5 Typical Measurement

A typical connection diagram of the Analyzer to the DUT is shown in Figure 1.1. In this configuration, complex reflection coefficients S11 and S22 can be measured, as well as complex transmission coefficients S21 and S12 of the DUT.



1 – Measurement cables 2 – Device Under Test (DUT)

Figure 1.1. Typical connection diagram.

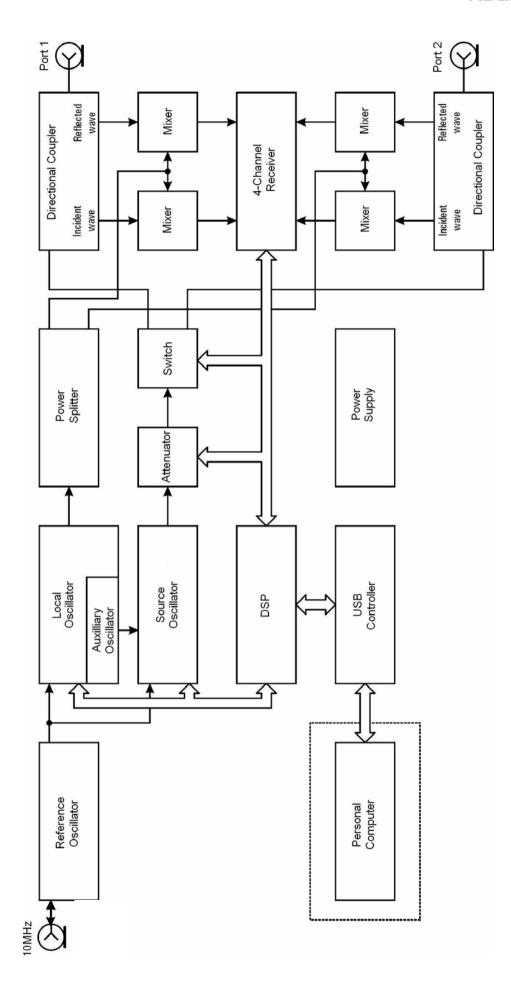


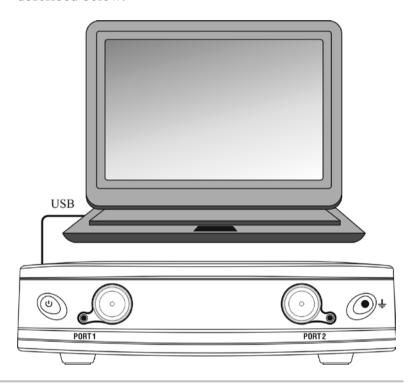
Figure 1.1 S5048/S7530 Network Analyzer block diagram

2 PREPARATION FOR USE

2.1 General Information

Unpack the Analyzer and other accessories. Connect the Analyzer to a 100 VAC to 240 VAC 50/60 Hz power source by means of the external power supply supplied with the instrument. Connect the USB-port of your Analyzer to the PC using the USB Cable supplied in the package. Install the software (supplied on the USB drive) onto your PC. The software installation procedure is described below in section 2.2.

Connect the Analyzer to a PC using the USB cable supplied. Install the PC software from the included USB drive. The procedure for installing the software is described below.



Warm-up the Analyzer for 40 minutes after power-on.

Assemble the test setup using cables, connectors, fixtures, etc, which allow DUT connection to the Analyzer.

Perform calibration of the Analyzer. Calibration procedure is described in section 5.

2.2 Software Installation

Connect the Analyzer to your PC via USB interface and install the S5048/S7530 software using the USB drive supplied with the instrument.

Minimal system requirements for the PC	WINDOWS 2000/XP/VISTA/7 1.5 GHz Processor			
	1 GB RAM			
	USB 2.0 High Speed			

The supplied CD contains the following software.

CD contents	Setup_S5048_vX.X.exe ¹ or Setup_S7530_vX.X.exe installer file
	folder Driver contains the driver
	folder Doc contains documentation

The procedure of the software installation is broken up into two steps. The first one is the driver installation. The second step comprises installation of the program, documentation and other files.

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 $^{^{1}}$ X.X – program version number

Driver installation

Connect the Analyzer to your PC via the supplied USB cable. It is allowed to connect the USB cable to the running PC.

Turn on and boot the PC, if it is off.

Turn the Analyzer on by the Power key on the front panel.

When you connect the Analyzer to the PC for the first time, Windows will automatically detect the new USB device and will open the USB driver installation dialog (Windows 2000/XP/VISTA).In Windows 7, open the USB driver installation dialog as follows: *Start > Control Panel > Device Manager*. Make the right mouse click on the *Unknown Device* line and select *Update Drivers*.

In the USB driver installation dialog, click on *Browse* and specify the path to the driver files, which are contained in the \DRIVER folder on the CD and on hard drive in analyzer software folder.

When the driver is installed, the new USB device will appear in the system.

Program and other files installation

Run the **Setup_S5048_vX.X.exe** or **Setup_S57530_vX.X.exe** installer file from the CD. Follow the instructions of the installation wizard.

2.3 Front Panel

The front view of the Analyzer is shown in figure 2.1. The front panel is equipped with the following parts:

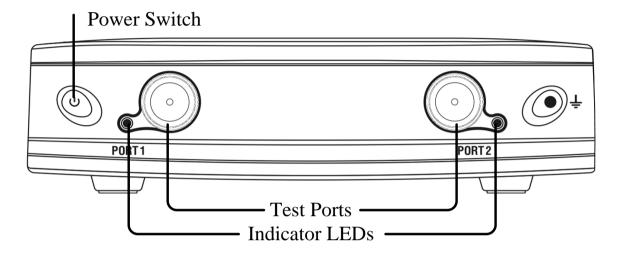
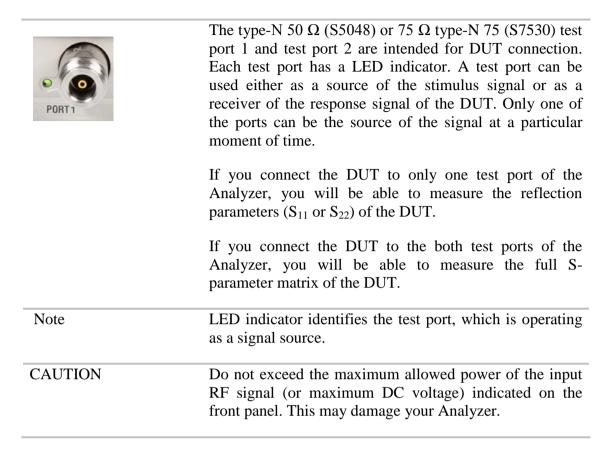


Figure 2.1. Analyzer front panel

2.3.1 Power Switch

	Switches the power supply of the Analyzer on and off. You can turn your Analyzer on/off at any time. After power-on of the Analyzer connected to PC, the program will begin uploading embedded firmware into the instrument. The uploading process will take 10 sec.; after that the Analyzer will be ready for operation.
Note	When you turn on your Analyzer for the first time, the USB driver will be installed onto the PC. The driver installation procedure is described in section 2.2. Some computers may require re-installation of the driver in case of change of the USB port.

2.3.2 Test Ports



2.4 Rear Panel

The rear view of the Analyzer is shown in figure 2.2. Descriptions of the elements of the rear panel is provided below the figure.

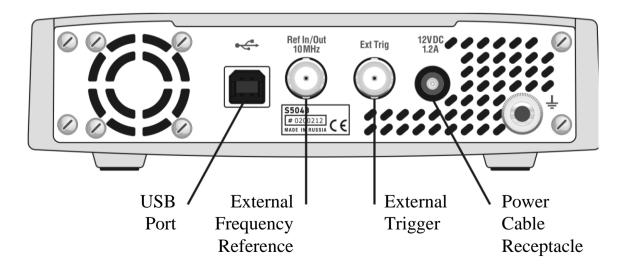


Figure 2.2 Analyzer rear panel

2.4.1 Power Cable Receptacle

Please connect an external DC power supply voltage from 9 to 15 V. The power supply can be powered by a battery, including a vehicle battery, through an appropriate vehicle power cable.

2.4.2 External Trigger Signal Input Connector

This connector allows the user to connect an external trigger source. Connector type is BNC female. TTL compatible inputs of 3 V to 5 V magnitude have up to 1 μ s pulse width. Input impedance at least 10 μ C.

2.4.3 External Reference Frequency Connector

External reference frequency is 10 MHz, input level is 2 dBm \pm 3 dB, input impedance 50 Ω . Output reference signal level is 3 dBm \pm 2 dB into 50 Ω impedance. Connector type is BNC female.

2.4.4 USB 2.0 High Speed

The USB port is intended for connection to computer.

3 GETTING STARTED

This section represents a sample session of the Analyzer. It describes the main techniques of measurement of reflection coefficient parameters of the DUT. SWR and reflection coefficient phase of the DUT will be analyzed.

For reflection coefficient measurement only one test port of the Analyzer is used. The instrument sends the stimulus to the input of the DUT and then receives the reflected wave. Generally in the process of this measurement the output of the DUT should be terminated with a LOAD standard. The results of these measurements can be represented in various formats.

Typical circuit of reflection coefficient measurement is shown in figure 3.1.

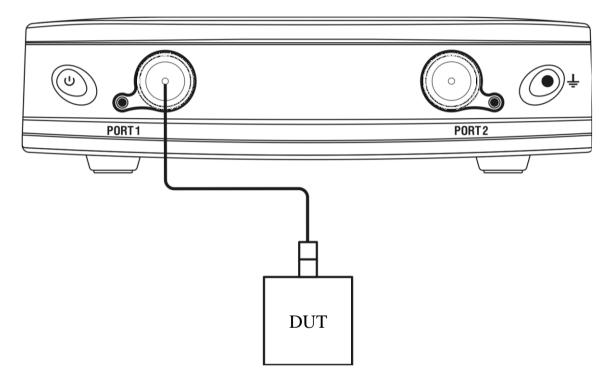


Figure 3.1 Reflection measurement circuit

To measure SWR and reflection coefficient phases of the DUT, in the given example you should go through the following steps:

- Prepare the Analyzer for reflection measurement;
- Set stimulus parameters (frequency range, number of sweep points);
- Set IF bandwidth:
- Set the number of traces to 2, assign measured parameters and display format to the traces;
- Set the scale of the traces;

Perform	calibration	of	the	Analyzer	for	reflection	coefficient
measure	ment;						

■ Analyze SWR and reflection coefficient phase using markers.

Note

In this section the control over Analyzer is performed by the softkeys located in the right-hand part of the screen. The Analyzer also allows the user to perform quick control by the mouse (See section 4.3).

3.1 Analyzer Preparation for Reflection Measurement

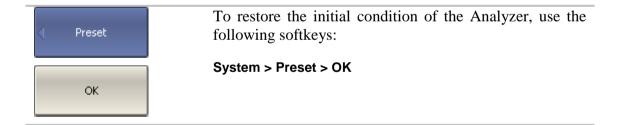
Turn on the Analyzer and warm it up for the period of time stated in the specifications.

Ready state features	The bottom line of the screen displays the instrument status bar. It should read Ready . Above this bar, the channel status bar is located. The sweep indicator in the left-hand part of this bar should display a progress.
	left-hand part of this bar should display a progress.

Connect the DUT to Port 1 of the Analyzer. Use the appropriate cables and adapters for connection of the DUT input to the Analyzer test port. If the DUT input is type-N (male), you can connect the DUT directly to the port.

3.2 Analyzer Presetting

Before you start the measurement session, it is recommended to reset the Analyzer into the initial (known) condition. The initial condition setting is described in Appendix 1.



3.3 Stimulus Setting

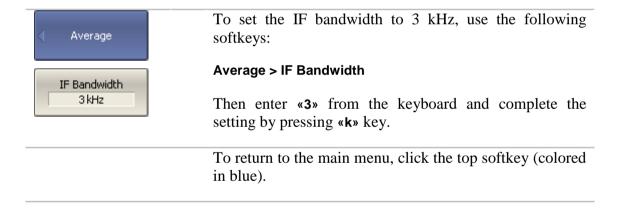
After you have restored the preset state of the Analyzer, the stimulus parameters will be as follows: frequency range from 20 kHz to 4.8 GHz in the case of S5048, or 20 kHz to 3.0 GHz in the case of S7530. The preset sweep type is linear, number of sweep points is 201, and power level is 0 dBm.

For the current example, set the frequency range to from 10 MHz to 3 GHz.

< Stimulus	To set the start frequency of the frequency range to 10 MHz, use the following softkeys:
Start 10 MHz	Stimulus > Start
	Then enter «1» , «0» from the keyboard. Complete the setting by pressing «M» key.
Stop 3 GHz	To set the stop frequency of the frequency range to 3 GHz, use the following softkeys:
	Stimulus > Stop
	Then enter «3» from the keyboard. Complete the setting by pressing «G» key.
	To return to the main menu, click the top softkey (colored in blue).

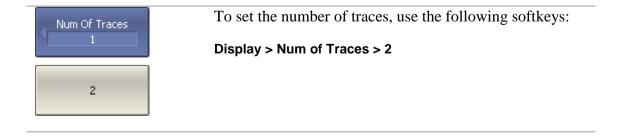
3.4 IF Bandwidth Setting

For the current example, set the IF bandwidth to 3 kHz.



3.5 Number of Traces, Measured Parameter and Display Format Setting

In the current example, two traces are used for simultaneous display of the two parameters (SWR and reflection coefficient phase).



To return to the main menu, click the top softkey (colored in blue).

Before assigning the measurement parameters of a trace, first activate the trace.

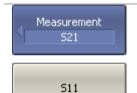


To activate the second trace, use the following softkeys:

Display > Active Trace/Channel > Active Trace > 2

To return to the main menu, click the top softkey (colored in blue).

Assign S_{11} -parameter to the second trace. To the first trace this parameter is already assigned by default.



To assign a parameter to the trace, use the following softkeys:

Measurement > S11

Then assign SWR display format to the first trace and reflection coefficient phase display format to the second trace.



To set the active trace display format, use the following softkeys:

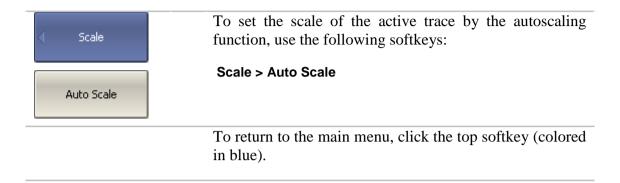
Format > SWR (for the first trace),

Format > Phase (for the second trace).

To return to the main menu, click the top softkey (colored in blue).

3.6 Trace Scale Setting

For a convenience in operation, change the trace scale using automatic scaling function.



3.7 Analyzer Calibration for Reflection Coefficient Measurement

Calibration of the whole measurement setup, which includes the Analyzer, cables and other devices, supporting connection to the DUT, allows to considerably enhance the accuracy of the measurement.

To perform full 1-port calibration, you need to prepare the kit of calibration standards: OPEN, SHORT and LOAD. Such a kit has its description and specifications of the standards. To perform proper calibration, you need to select in the program the correct kit type.

In the process of full 1-port calibration, connect calibration standards to the test port one after another, as shown in figure 3.2.

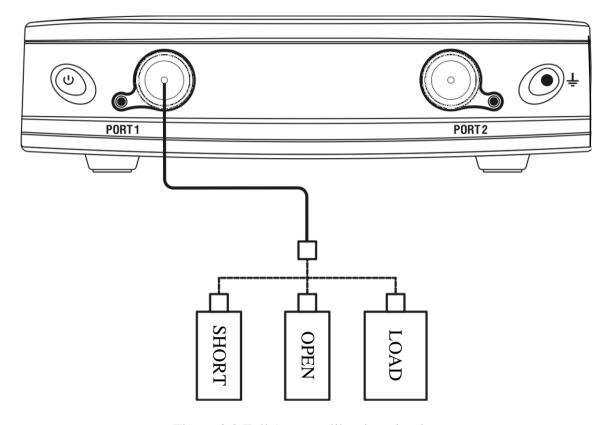
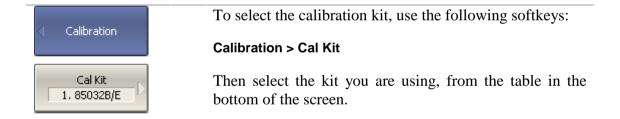
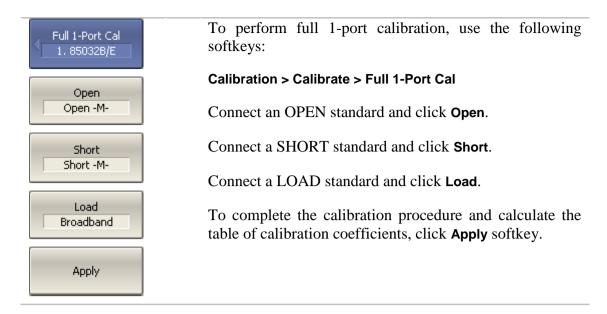


Figure 3.2 Full 1-port calibration circuit

In the current example, an Agilent 85032E calibration kit is used.



To perform full 1-port calibration, execute measurements of the three standards. After that the table of calibration coefficients will be calculated and saved into the memory of the Analyzer. Before you start calibration, disconnect the DUT from the Analyzer.



Then connect the DUT to the Analyzer port again.

3.8 SWR and Reflection Coefficient Phase Analysis Using Markers

This section describes how to determine the measurement values at three frequency points using markers. The Analyzer screen view is shown in figure 3.3. In the current example, a reflection standard of SWR = 1.2 is used as a DUT.

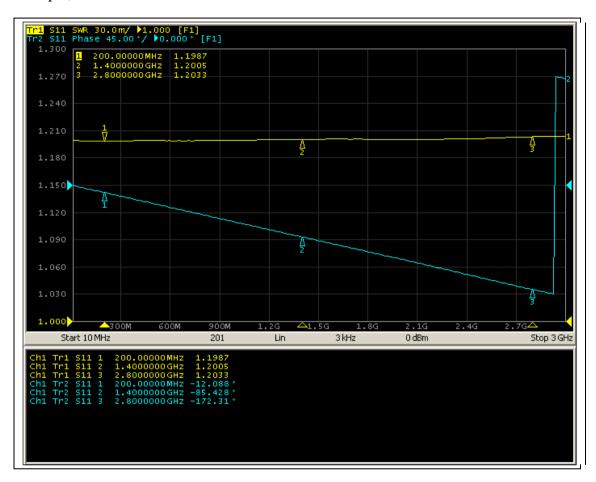
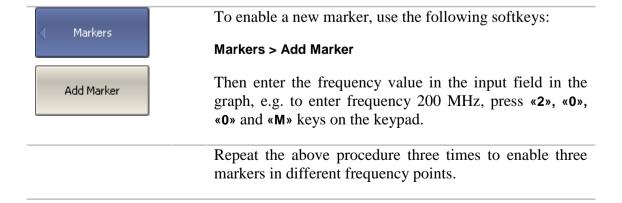


Figure 3.3 SWR and reflection coefficient phase measurement example



By default only active trace markers are displayed on the screen. To enable display of two traces simultaneously, first activate the marker table.

To open the marker table, use the following softkeys:

Marker Properties

Marker Table

Marker Table

4 MEASUREMENT CONDITIONS SETTING

4.1 Screen Layout and Functions

The screen layout is represented in figure 4.1. In this section you will find detailed description of the softkey menu bar, menu bar, and instrument status bar. The channel windows will be described in the following section.

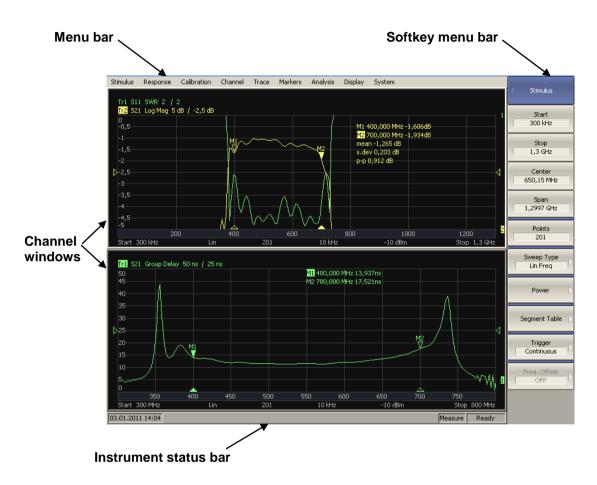


Figure 4.1 Analyzer screen layout

4.1.1 Softkey Menu Bar

The softkey menu bar in the right-hand side of the screen is the main menu of the program.

Note	The top line of the screen represents the menu bar, which enables you direct access to the submenus of the softkey
	menu. This menu is an auxiliary one and can be hidden.

The softkey menu bar consists of panels, which appear one instead of the other. Each panel represents one of the submenus of the softkey menu. All the panels are integrated into multilevel menu system and allow access to all the functions of the Analyzer.

You can manipulate the menu softkeys using a mouse.

Also you can navigate the menu by $\langle \uparrow \rangle$, $\langle \downarrow \rangle$, $\langle \leftarrow \rangle$, $\langle \leftarrow$

The types of the softkeys are described below:

< Stimulus	The top softkey is the menu title key. It enables you to return to the upper level of the menu. If it is displayed in blue you can use keyboard to navigate within the softkey menu.
Maximum	If the softkey is highlighted in dark gray, pressing «Enter» key on the keyboard will activate the function of this softkey. You can shift the highlight from key to key using « ↑» and « ↓» arrows on the keyboard.
Minimum	A large dot on the softkey indicates the current selection in a list of alternative settings.
√ Bandwidth	A check mark in the left part of the softkey indicates the active function, which you can switch on/off.
Peak [>	The softkey with a right arrow enables the access to the lower level of the menu.
S11	The softkey with a text field allows for the selected function indication.
Start 300 kHz	The softkey with a value field allows for entering/selection of the numerical settings.
	This navigation softkey appears when the softkey menu overflows the menu screen area. Using this softkey you can scroll down and up the softkey menu.

To navigate in the softkey menu, you can also (additionally to $\langle \uparrow \rangle$, $\langle \downarrow \rangle$) use $\langle \leftarrow \rangle$, $\langle \leftarrow \rangle$

- «←» key brings up the upper level of the menu;
- «→» key brings up the lower level of the menu, if there is a highlighted softkey with a right arrow;
- «Esc» key functions similar to «←» key;
- «Home» key brings up the main menu.

Note

The above keys of the keyboard allow navigation in the softkey menu only if there is no any active entry field. In this case the menu title softkey is highlighted in blue.

4.1.2 Menu Bar



Figure 4.2 Menu bar

The menu bar is located at the top of the screen. This menu is an auxiliary one and enables you direct access to the submenus of the main menu. Also it contains the functions of the most frequently used softkeys. You can hide the menu bar to gain more screen space for the graph area. The menu bar is controlled by the mouse.

Note To hide the menu bar, use the following softkeys:

Display > Properties > Menu Bar

4.1.3 Instrument Status Bar



Figure 4.3 Instrument status bar

The instrument status bar is located at the bottom of the screen.

Table 4.1 Messages in the instrument status bar

adie 4.1 Wessages III die Histument status dai		
Field Description	Message	Instrument Status
	Not Ready	No communication between DSP and computer.
DSP status	Loading	DSP program is loading.
	Ready	DSP is running normally.
	Meas	A sweep is in progress.
	Hold	A sweep is on hold.
Sweep status	Ext	Waiting for trigger, which is set to "External".
	Man	Waiting for trigger, which is set to "Manual".
	Bus	Waiting for trigger, which is set to "Bus".
Calibration	Calibration	Calibration standard measurement is in progress.
RF signal	RF output Off	Stimulus signal output is turned off.
External reference frequency	ExtRef	External reference frequency input (10 MHz) is turned on.
Display update	Update Off	Display update is turned off.
System correction status	Sys Corr OFF	System correction is turned off (see section 8.4).
Factory calibration	PC Error	ROM error of power calibration.
error	RC Error	ROM error of system calibration.
External power meter status	Power Meter: message	When external power meter is connected to the Analyzer via USB the following messages are displayed: connection, connection error, ready, measurement, zero setting, zero setting error

4.2 Channel Window Layout and Functions

The channel windows display the measurement results in the form of traces and numerical values. The screen can display up to 16 channel windows simultaneously. Each window corresponds to one logical channel. A logical channel can be represented as a separate analyzer with the following settings:

- Stimulus signal settings (frequency range, power level, sweep type);
- IF bandwidth and averaging;
- Calibration.

Physical analyzer processes the logical channels in succession.

In turn each channel window can display up to 16 traces of the measured parameters. General view of the channel window is represented in figure 4.4.

Figure 4.4 Channel window

4.2.1 Channel Title Bar

The channel title feature allows you to enter your comment for each channel window. You can hide the channel title bar to gain more screen space for graph area.

Channel title bar on/off switching	To show/hide the channel title bar, use the following softkeys:
	Display > Title Label
Channel title editing	You can access the channel title edit mode by using the following softkeys:
	Display > Edit Title Label
	You can also make it by mouse clicking on the title area in the channel title bar.

4.2.2 Trace Status Field

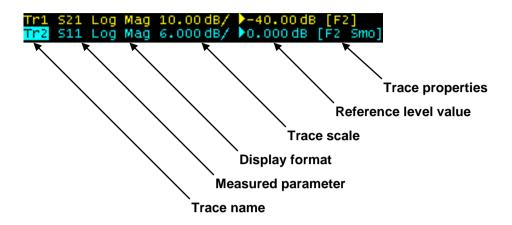


Figure 4.5 Trace status field

The trace status field displays the name and parameters of a trace. The number of lines in the field depends on the number of active traces in the channel.

Note	Using the trace status field you can easily modify the
	trace parameters by the mouse (as described in section
	4.3).

Each line contains the data on one trace of the channel:

- Trace name from **«Tr1»** to **«Tr16»**. The active trace name is highlighted in inverted color;
- Measured parameter: **S11**, **S21**, **S12**, **S22**, or absolute power value: **A(n)**, **B(n)**, **R1(n)**, **R2(n)**;
- Display format, e.g. «Log Mag»;
- Trace scale in measurement units per scale division, e.g. «10.0 dB/»;
- Reference level value, e.g. **«►0.00 dB»**, where **«►»** is the symbol of the reference level;
- Trace status is indicated as symbols in square brackets (See table 4.2).

Table 4.2 Trace status symbols definition

Table 4.2 Trace status symbols definition		
Status	Symbols	Definition
	RO	OPEN response calibration
	RS	SHORT response calibration
	RT	THRU response calibration
Error Correction	OP	One-path 2-port calibration
	F1	Full 1-port calibration
	F2	Full 2-port and TRL calibration
	SMC	Scalar mixer calibration
Other	RC	Receiver calibration
Calibrations	PC	Power calibration
	Z 0	Port impedance conversion
Data Analysis	FD	Fixture de-embedding
Data Allarysis	FE	Fixture embedding
	PExt	Port extension
	No indication	Data trace
Trace Display	D&M	Data and memory traces
Trace Display	M	Memory trace
	Off	Data and memory traces – off
	D+M	Data + Memory
Math Operations	D-M	Data – Memory
watii Operations	D*M	Data * Memory
	D/M	Data / Memory
Electrical Delay	Del	Electrical delay other than zero
Smoothing	Smo	Trace smoothing
Gating	Gat	Time domain gating
	Zr	Reflection impedance
	Zt	Transmission impedance
	Yr	Reflection admittance
Conversion	Yt	Transmission admittance
Conversion	1/S	S-parameter inversion
	Ztsh	Transmission-shunt impedance
	Ytsh	Transmission-shunt admittance
	Conj	Conjugation
,		

4.2.3 Graph Area

The graph area displays the traces and numeric data.

Figure 4.6 Graph area

Reference line position

The graph area contains the following elements:

- Vertical graticule label displays the vertical axis numeric data for the active trace. You can set the display of the data for all the traces or hide the vertical graticule label to gain more screen space for the trace display.
- Horizontal graticule label displays stimulus axis numeric data (frequency, power level or time). You can also hide the horizontal graticule label to gain more screen space for the trace display.
- Reference level position indicates the reference level position of the trace.
- Markers indicate the measured values in different points on the active trace. You can enable display of the markers for all the traces simultaneously.
- Marker functions: *statistics*, *bandwidth*, *flatness*, *RF filter*.
- *Trace number* allows trace identification when printed out in black and white.
- Current stimulus position indication appears when sweep duration exceeds 1.5 sec.

Note Using the graticule labels, you can easily modify all the trace parameters by the mouse (as described in section 4.3).

4.2.4 Trace Layout in Channel Window

If the number of the displayed traces is more than one, you can rearrange the traces to your convenience. You can select display of all the traces in one graph (See figure 4.6) or display of each trace in its individual graphs (See figure 4.7).

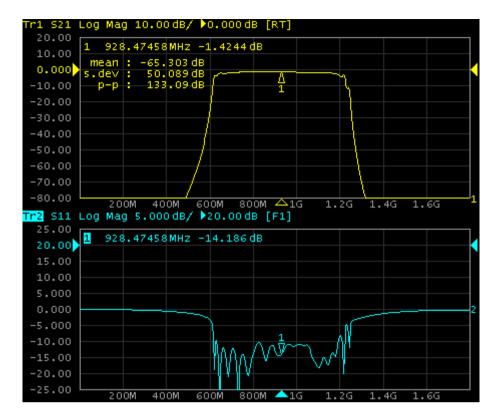


Figure 4.7 Two traces in one channel window (sample)

4.2.5 Markers

The markers indicate the stimulus values and the measured values in selected points of the trace (See figure 4.8).

Figure 4.8 Markers

The markers are numbered from 1 to 15. The reference marker is indicated with R symbol. The active marker is indicated in the following manner: its number is highlighted in inverse color, the indicator on the trace is located above the trace, the stimulus indicator is fully colored.

4.2.6 Channel Status Bar

The channel status bar is located in the bottom part of the channel window. It contains the following elements:

Figure 4.9 Channel status bar

- Sweep progress field displays a progress bar when the channel data are being updated.
- *Error correction* field displays the integrated status of error correction for S-parameter traces. The values of this field are represented in table 4.3.
- Receiver correction field displays the integrated status of receiver correction for absolute power measurement traces. The values of this field are represented in table 4.4.
- Power correction field displays the integrated status of power correction for all the traces. The values of this field are represented in table 4.5.
- Port extension field displays the integrated status of execution of this function for S-parameter traces. If the function is enabled for all the traces, you will see black characters on gray background. If the function is enabled just for some of the traces, you will see white characters on red background.
- Fixture simulation field displays the integrated status of execution of this function for S-parameter traces. Fixture simulation includes the following operations: Z0 conversion, embedding, de-embedding. If the function is enabled for all the traces, you will see black characters on gray background. If the function is enabled just for some of the traces, you will see white characters on red background.
- *Stimulus start* field allows for display and entry of the start frequency or power, depending on the sweep type. This field can be switched to indication of stimulus center frequency, in this case the word **Start** will change to **Center**.
- Sweep points field allows for display and entry of the number of sweep points. The number of sweep points can be set from 2 to 200001.
- Sweep type field allows for display and selection of the sweep type. The values of this field are represented in table 4.6.
- *IF bandwidth* field allows for display and setting of the IF bandwidth. The values can be set from 10 Hz to 30 kHz.

- Power level field allows for display and entry of the port output power. In power sweep mode the field switches to indication of CW frequency of the source.
- Averaging status field displays the averaging status if this function is enabled. The first number is the averaging current counter value, the second one is the averaging factor.
- Stimulus stop field allows for display and entry of the stop frequency or power, depending on the sweep type. This field can be switched to indication of stimulus span, in this case the word **Stop** will change to **Span**.

Table 4.3 Error correction field

Symbol	Definition	Note
Cor	Error correction is enabled. The stimulus settings are the same for the measurement and the calibration.	all the traces – black characters on gray
C?	Error correction is enabled. The stimulus settings are not the same for the measurement and the calibration. Interpolation is applied.	background. If the function is active only for some of the traces (other traces are not calibrated) – white
CI	Error correction is enabled. The stimulus settings are not the same for the measurement and the calibration. Extrapolation is applied.	characters on red background.
Off	Error correction is turned off.	For all the traces. White
	No calibration data. No calibration was performed.	characters on red background.

Table 4.4 Receiver correction field

Symbol	Definition	Note
RC	Receiver correction is enabled. The stimulus settings are the same for the measurement and the calibration.	all the traces – black characters on gray
RC?	Receiver correction is enabled. The stimulus settings are not the same for the measurement and the calibration. Interpolation is applied.	background. If the function is active only for some of the traces (other traces are not calibrated) – white
RC!	Receiver correction is enabled. The stimulus settings are not the same for the measurement and the calibration. Extrapolation is applied.	characters on red background.

Table 4.5 Power correction field

Symbol	Definition	Note
PC	Power correction is enabled. The stimulus settings are the same for the measurement and the calibration.	all the traces – black characters on gray
PC?	Power correction is enabled. The stimulus settings are not the same for the measurement and the calibration. Interpolation is applied.	background. If the function is active only for some of the traces (other traces are not calibrated) – white
PC!	Power correction is enabled. The stimulus settings are not the same for the measurement and the calibration. Extrapolation is applied.	characters on red background.

Table 4.6 Sweep types

Symbol	Definition
Lin	Linear frequency sweep.
Log	Logarithmic frequency sweep.
Segm	Segment frequency sweep.
Pow	Power sweep.

4.3 Quick Channel Setting Using Mouse

This section describes the mouse manipulations, which will enable you to set the channel parameters fast and easy. In a channel window, over the field where a channel parameter can be modified, the mouse pointer will change its form to indicate the edit mode. Apart from that in text and numerical fields the edit mode will be indicated by the «underline» symbol appearance.

Note

The mouse manipulations described in this section will help you to perform the most frequently used settings only. All the channel functions can be accessed via the softkey menu.

4.3.1 Active Channel Selection

You can select the active channel when two or more channel windows are open. The border line of the active window will be highlighted in light color. To activate another window, make a mouse click within its area.

4.3.2 Active Trace Selection

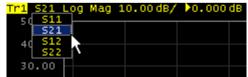


You can select the active trace if the active channel window contains two or more traces. The active trace name will

be highlighted in inverted color. To activate a trace, make a mouse click on the required trace status line, or on the trace curve or the trace marker.

4.3.3 Measured Data Setting

To assign the measured parameters $(S_{11}, S_{21}, S_{12} \text{ or } S_{22})$ to a trace, make a mouse click



on the S-parameter name in the trace status line and select the required parameter in the drop-down menu.

4.3.4 Display Format Setting



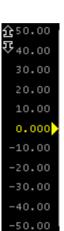
To select the trace display format, make a mouse click on the display format name in the trace status line and select the required format in the drop-down menu.

4.3.5 Trace Scale Setting

The trace scale means the vertical scale division value, which can be set by two methods.



The first method: make a mouse click on the trace scale field in the trace status line and enter the required numerical value.



The second method: move the mouse pointer over the vertical scale until the pointer form becomes as shown in the figure. Locate the pointer in the top or bottom parts of the scale, at approximately 10% of the scale height from the top or bottom of the scale. Press left button of the mouse and holding it drag the pointer from the scale center to enlarge the scale, or to the center of the scale to reduce the scale.

4.3.6 Reference Level Setting

The value of the reference level, which is indicated on the vertical scale by **«►»** and **«◄»** symbols, can be set by two methods.

Tri 521 Log Mag 10.00 dB/ p The first method: make a mouse click on the reference level field in the trace status line and enter the required numerical value.



50.00

The second method: move the mouse pointer over the vertical scale until the pointer form becomes as shown in the figure. Locate the pointer in the center part of the scale. Press left button of the mouse and holding it drag the pointer up the scale to increase the reference level value, or down the scale to reduce the value.

4.3.7 Reference Level Position

The reference level position, indicated on the vertical scale by «►» and «◄» symbols,

50.00 40.00 30.00 20.00 10.00 -10.00 -20.00 -30.00 -40.00

50.00

can be set in the following way. Locate the mouse pointer on a reference level symbol until it becomes as shown in the figure. Then drag and drop the reference level symbol to the desired position.

4.3.8 Sweep Start Setting

Move the mouse pointer over the stimulus scale until it becomes as shown in the figure.



Locate the mouse pointer in the left part of the scale, at approximately 10% of the scale length from the left. Press left button of the mouse and

holding it drag the pointer to the right to increase the sweep start value, or to the left to reduce the value.

4.3.9 Sweep Stop Setting



Move the mouse pointer over the stimulus scale until it becomes as shown in the figure. Locate the mouse pointer in the right part of the scale, at

approximately 10% of the scale length from the right. Press left button of the mouse and holding it drag the pointer to the right to increase the sweep stop value, or to the left to reduce the value.

4.3.10 Sweep Center Setting



Move the mouse pointer over the stimulus scale until it becomes as shown in the figure. Locate the mouse pointer in the center part of the scale.

Press left button of the mouse and holding it drag the pointer to the right to increase the sweep center value, or to the left to reduce the value.

4.3.11 Sweep Span Setting



Move the mouse pointer over the stimulus scale until it becomes as shown in the figure. Locate the mouse pointer in the center part of the scale,

at approximately 20% of the scale length from the right. Press left button of the mouse and holding it drag the pointer to the right to increase the sweep span value, or to the left to reduce the value.

4.3.12 Marker Stimulus Value Setting

The marker stimulus value can be set by drag operation or by entering the value using numerical keys of the keyboard.





To drag the marker, first move the mouse pointer on one of the marker indicators until it becomes as shown in the figures.

To enter the numerical value of the stimulus, first activate its field in the marker data line by a mouse click.

4.3.13 Switching between Start/Center and Stop/Span Modes





Stop 3.2 GHz To switch between the modes Start/Center and Stop/Span, make a mouse click in the respective

field of the channel status bar. Label Start will be changed with Center, and label Stop will be changed with Span. The layout of the stimulus scale will be changed correspondingly.

4.3.14 Start/Center Value Setting



To enter the Start/Center values, activate the respective field in the channel status bar by a mouse click on the numerical value.

4.3.15 Stop/Span Value Setting



To enter the **Stop/Span** values, activate the respective field in the channel status bar by a mouse click on the numerical value.

4.3.16 Sweep Points Number Setting



To enter the number of sweep points, activate the respective field in the channel status bar by a mouse click on the numerical value.

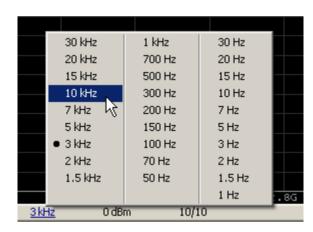
4.3.17 Sweep Type Setting

To set the sweep type, click on the respective field in the channel status bar and select the required type in the drop-down menu.

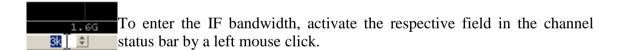


4.3.18 IF Bandwidth Setting

IF bandwidth can be set by selection in the drop-down menu or by entering the value using numerical keys of the keyboard.



To activate the drop-down menu, make a right mouse click on the IF bandwidth field in the channel status bar.



4.3.19 Power Level / CW Frequency Setting

To enter the **Power Level/CW Frequency**, activate the respective field in the channel status bar by a mouse click on the numerical value. The parameter displayed in the field depends on the current sweep type: in frequency sweep mode you can enter CW frequency value.

4.4 Channel and Trace Display Setting

The Analyzer supports 16 channels, which allow measurements with different stimulus parameter settings. The parameters related to a logical channel are listed in table 4.7.

4.4.1 Channel Window Allocating

A channel is represented on the screen as an individual channel window. The screen can display from 1 to 16 channel windows simultaneously. By default one channel window opens. If you need to open two or more channel windows select one of the layouts shown below.

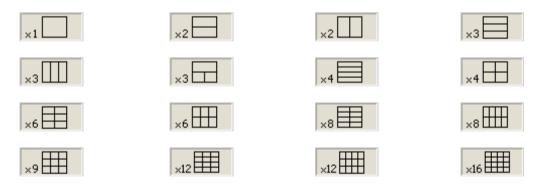


To set the channel window layout, use the following softkeys:

Display > Allocate Channels

Then select the required number and layout of the channel windows in the menu.

The available options of number and layout of the channel windows on the screen are as follows:



In accordance with the layouts, the channel windows do not overlap each other. The channels open starting from the smaller numbers.

Note

For each open channel window, you should set the stimulus parameters, make other settings, and perform calibration.

Before you start a channel parameter setting or calibration, you need to select this channel as active.

The measurements are executed for open channel windows in succession. Measurements for hidden channel windows are not executed.

4.4.2 Number of Traces Setting

Each channel window can contain up to 16 different traces. Each trace is assigned the measured parameter (S-parameter), display format and other parameters. The parameters related to a trace are listed in table 4.8.

The traces can be displayed in one graph, overlapping each other, or in separate graphs of a channel window. The trace settings are made in two steps: trace number setting and trace layout setting in the channel window. By default a channel window contains one trace. If you need to enable two or more traces, set the number of traces as described below.



To set the number of the traces, use the following softkeys:

Display > Num Of Traces

Then select the number of traces from the menu.

All the traces are assigned their individual names, which cannot be changed. The trace name contains its number. The trace names are as follows: **Tr1**, **Tr2** ... **Tr16**.

Each trace is assigned some initial settings: measured parameter, format, scale, and color, which can be modified by the user.

- By default the measured parameters are set in the following succession: S_{11} , S_{21} , S_{12} , S_{22} . After that the measurements repeat in cycles.
- By default the display format for all the traces is set to logarithmic magnitude (dB).
- The scale parameters by default are set as follows: division is set to 10 dB, reference level value is set to 0 dB, reference level position is in the middle of the graph.
- The trace color is determined by its number. You can change the color for all the traces with the same number.

Note

Full cycle of trace updating depends on the S-parameters measured and the calibration method. The full cycle can consist of one sweep of Port 1 or Port 2 being a source, or can include two successive sweeps, of Port 1 then of Port 2. For example, to have two traces (S_{11} and S_{22}) measured, two successive sweeps will be performed. Two successive sweeps are also performed during full 2-port calibration, independently of the number of the traces and S-parameters measured.

4.4.3 Trace Allocating

By default all the traces are displayed in channel window, overlapping each other. If you need to display the traces in separate graphs, set the number and layout of the graphs in the channel window as shown below.



To allocate the traces in a channel window, use the following softkeys:

Display > Allocate Traces

Then select the required number and layout of the separate trace graphs in the menu.

The available options of number and layout of the trace graphs of one channel window are as shown in section 4.4.1.

Compared to channel windows, number and layout of the trace graphs are not correlated. Number of traces and number of graphs are set independently.

- If the number of traces and the number of graphs are equal, all the traces will be displayed separately, each in its individual graph.
- If the number of traces is greater than the number of graphs, traces will be assigned successively (beginning from the smallest trace number) to the available graphs. When all the graphs become occupied, the process will continue from the first graph (the following in succession traces will be added in the graphs).
- If the number of traces is smaller than the number of graphs, empty graphs will be displayed.

If two or more traces are displayed in one graph, the vertical scale will be shown for the active trace.

	wing the vertical
graticule label for all the traces in the this feature is set to off. For details see	0 1

If two or more traces are displayed in one graph, the markers' data will be shown for the active trace.

Note	To display the marker data for all the traces
	simultaneously, there are two options: use marker table
	feature (See section 6.1.6.2) or deactivate identification of
	the active trace marker only, which is set by default (See section 6.1.6.4).

Stimulus axis is the same for all the traces of the channel, except for the conditions when time domain transformation is applied to some of the traces. In this case the displayed stimulus axis will refer to the active trace.

Table 4.7 Channel parameters

N	Parameter Description	
1	Sweep Type	
2	Sweep Range	
3	Number of Sweep Points	
4	Stimulus Power Level	
5	Power Slope Feature	
6	CW Frequency	
7	Segment Sweep Table	
8	Trigger Mode	
9	IF Bandwidth	
10	Averaging	
11	Calibration	
12	Fixture Simulator	

Table 4.8 Trace parameters

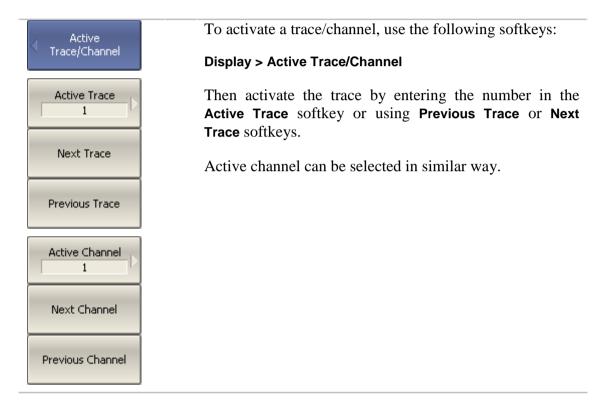
N	Parameter Description
1	Measured Parameter (S–parameter)
2	Display Format
3	Reference Level Scale, Value and Position
4	Electrical Delay, Phase Offset
5	Memory Trace, Math Operation
6	Smoothing
7	Markers
8	Time Domain
9	Parameter Transformation
10	Limit Test

4.4.4 Trace/Channel Activating

The control commands selected by the user are applied to the active channel or the active trace, respectively.

The border line of the active channel window is highlighted in light color. The active trace belongs to the active channel and its title is highlighted in inverse color.

Before you set a channel or trace parameters, first you need to activate the channel or trace, respectively.



4.4.5 Active Trace/Channel Window Maximizing

When there are several channel windows displayed, you can temporarily maximize the active channel window to full screen size. The other channel windows will be hidden, but this will not interrupt the measurements in those channels.

Similarly, when there are several traces displayed in a channel window, you can temporarily maximize the active trace. The other traces will be hidden, but this will not interrupt the measurements of those traces.

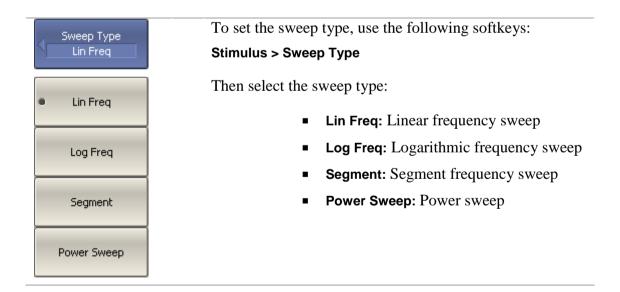
Active Trace/Channel	To enable/disable active channel maximizing function, use the following softkeys:
	Display > Active Trace/Channel > Active Channel
Maximize Channel	To enable/disable active trace maximizing function, use the following softkeys:
Maximize Trace	Display > Active Trace/Channel > Active Trace
Note	Channel and trace maximizing function can be controlled by a double mouse click on the channel/trace.

4.5 Stimulus Setting

The stimulus parameters are set for each channel. Before you set the stimulus parameters of a channel, make this channel active.

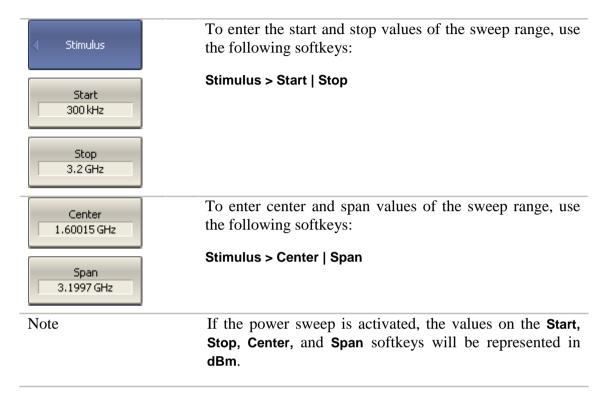
Note	To make the measurement more accurate, perform
	measurements with the same stimulus settings as were used for the calibration.

4.5.1 Sweep Type Setting



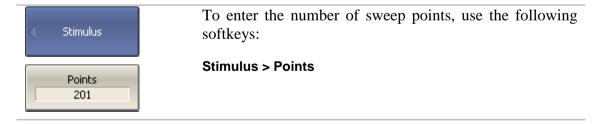
4.5.2 Sweep Span Setting

The sweep range should be set for linear and logarithmic frequency sweeps (Hz) and for linear power sweep (dBm). The sweep range can be set as Start / Stop or Center / Span values of the range.



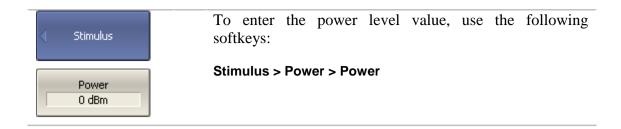
4.5.3 Sweep Points Setting

The number of sweep points should be set for linear and logarithmic frequency sweeps, and for linear power sweep.



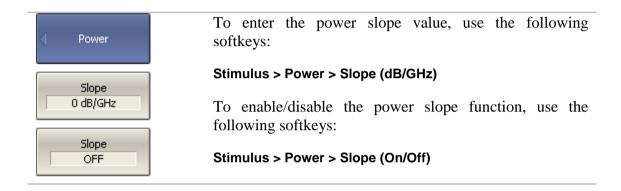
4.5.4 Stimulus Power Setting

The stimulus power level should be set for linear and logarithmic frequency sweeps. For the segment sweep type, the method of power level setting described in this section can be used only if the same power level is set for all the segments of the sweep. For setting of individual power level for each segment see section 4.5.8.



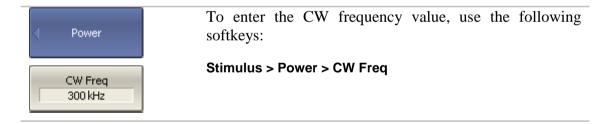
4.5.5 Power Slope Feature

The power slope feature allows for compensation of power attenuation with the frequency increase, in the fixture wire. The power slope can be set for linear, logarithmic and segment frequency sweeps.



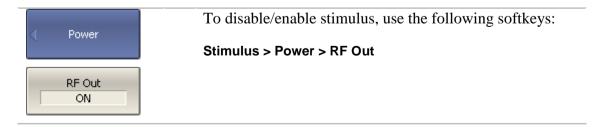
4.5.6 CW Frequency Setting

CW frequency setting determines the source frequency for the linear power sweep.



4.5.7 RF Out Function

RF Out function allows temporary disabling of stimulus signal. While the stimulus is disabled the measurements cannot be performed.

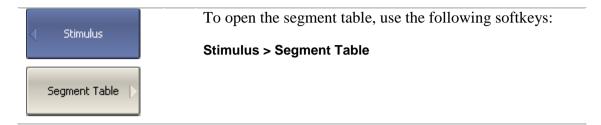


Note

RF Out function is applied to the whole Analyzer, not to some channels. The indication about it will appear in the instrument status bar (See section 4.1.3).

4.5.8 Segment Table Editing

Segment table determines the sweep rule when segment sweep is activated.

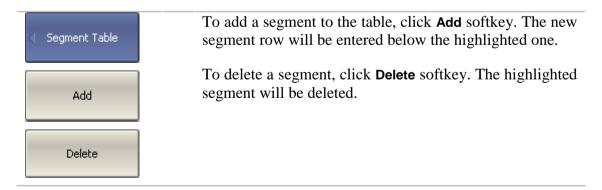


When you switch to the **Segment Table** submenu, the segment table will open in the lower part of the screen. When you exit the **Segment Table** submenu, the segment table will become hidden.

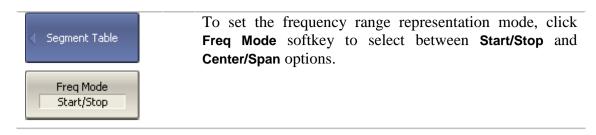
The segment table layout is shown below. The table has three mandatory columns: frequency range and number of sweep points, and three columns, which you can enable/disable: IF bandwidth, power level and delay time.

	Start	Stop	Points	IFBW	Power	
1	300 kHz	800MHz	11	100 Hz	10 dBm	
2	800 M Hz	1.12 GHz	51	3 kHz	0 dBm	
3	1.12 GHz	1.99GHz	101	30 kHz	-10 dBm	
4	1.99GHz	2.28GHz	51	3 kHz	0 dBm	
5	2.28GHz	3.2 GHz	11	100 Hz	10 dBm	
1					Total Points:	225

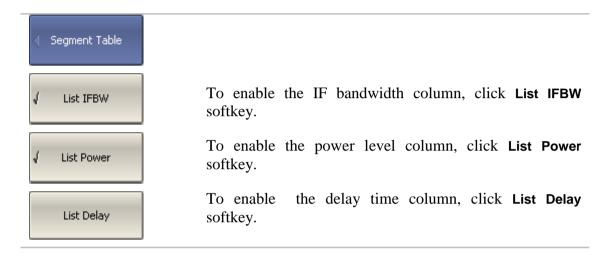
Each row describes one segment. The table can contain one or more rows, up to 20001 (the total number of sweep points of all the segments).



For any segment it is necessary to set the mandatory parameters: frequency range and number of sweep points. The frequency range can be set either as Start / Stop, or as Center / Span.



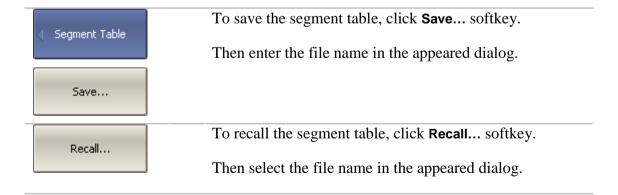
For any segment you can enable the additional parameter columns: IF bandwidth, power level, and delay time. If such a column is disabled, the corresponding value set for linear sweep will be used (same for all the segments).



To set a parameter, make a mouse click on its value field and enter the value. To navigate in the table you can use the keys of the keyboard.

Note	The adjacent segments do not overlap in the frequency domain.

The segment table can be saved into *.lim file to a hard disk and later recalled.



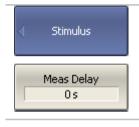
Segment sweep graph has two methods of frequency axis representation. The axis can display the frequencies of the measurement points. For some cases it can be helpful to have the frequency axis displayed in sequential numbers of the measurement points.



To set the frequency axis display mode, click **Segment Display** softkey and select **Freq Order** or **Base Order** option.

4.5.9 Measurement Delay

Measurement delay function allows to add additional time interval at each measurement point between the moment when the source output frequency becomes stable and the moment of measurement start. This capability can be useful for measurements in narrowband circuits with transient period longer than the measurement in one point.



To set the time of measurement delay, use the following softkeys:

Stimulus > Meas Delay

4.6 Trigger Setting

The *trigger mode* determines the sweep actuation of the channel at a *trigger signal* detection. A channel can operate in one of the following three trigger modes:

- Continuous a sweep actuation occurs every time a trigger signal is detected;
- Single one sweep actuation occurs at one trigger signal detection after the mode has been enabled, after the sweep is complete the channel turns to hold mode;
- Hold sweep actuation is off in the channel, the trigger signals do not affect the channel.

The trigger signal influences the whole Analyzer and controls the trigging of all the channels in the following manner. If more than one channel windows are open, the trigger activates the successive measurement of all the channels, which are not in hold mode. Before the measurement of all the channels is complete, all the new triggers will be ignored. When the measurement of all the channels is complete, if there is as least one channel in continuous trigger mode, the Analyzer will turn to waiting for a trigger state.

The *trigger source* can be selected by the user from the following four available options:

- Internal the next trigger signal is generated by the Analyzer on completion of each sweep;
- External the external trigger input is used as a trigger signal source:
- Manual the trigger signal is generated by pressing the corresponding softkey.
- Bus the trigger signal is generated by a command communicated from an external computer from a program controlling the Analyzer via COM/DCOM.

Trigger	To set the trigger mode, use the following softkeys:
Continuous	Stimulus > Trigger
Hold	Then select the required trigger mode:
	■ Hold
Single	■ Single
	Continuous
Continuous	
Hold All Channels	Hold All Channels and Continuous All Channels softkeys turn all the channels to the respective mode.
Continuous All Channels	
Restart	Restart softkey aborts the sweep and returns the trigger system to the waiting for a trigger state.
Trigger	Trigger softkey generates the trigger in manual trigger mode.
Trigger Source	To set the trigger source, use the following softkeys:
Internal	Stimulus > Trigger > Trigger Source
Internal	Then select the required trigger source:
	■ Internal
External	■ External
	■ Manual ■ Bus
Manual	- Duo
Bus	

4.7 Measurement Parameters Setting

4.7.1 S-Parameters

For high-frequency network analysis the following terms are applied: incident, reflected and transmitted waves, transferred in the circuits of the setup (See figure 4.10).

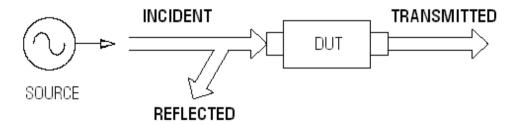


Figure 4.10

Measurement of magnitude and phase of incident, reflected and transmitted signals allow to determine the S-parameters (scattered parameters) of the DUT. An S-parameter is a relation between the complex magnitudes of the two waves:

$$S_{mn} = \frac{transmitted \ wave \ at \ Port \ m}{incident \ wave \ at \ Port \ n}$$

The Analyzer allows measurement of the full scattering matrix of a 2-port DUT:

$$\mathbf{S} = \begin{bmatrix} S_{11} & S_{12} \\ S_{21} & S_{22} \end{bmatrix}$$

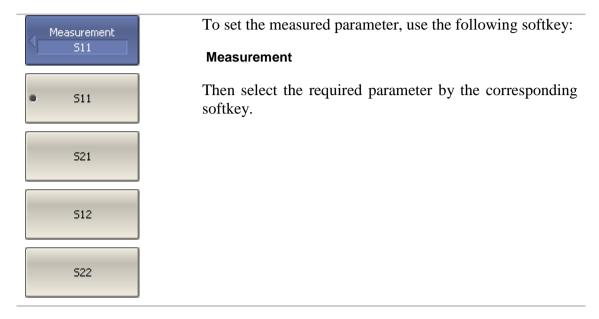
To measure the full scattering matrix, you do not need to change the connection of the DUT to the Analyzer.

For the measurement of S_{11} , S_{21} parameters, test Port 1 will operate as a signal source. The incident and reflected waves will be measured by Port 1. The transmitted wave will be measured by Port 2.

For the measurement of S_{12} , S_{22} parameters, test Port 2 will operate as a signal source. The incident and reflected waves will be measured by Port 2. The transmitted wave will be measured by Port 1.

4.7.2 S-Parameter Setting

A measured parameter $(S_{11},\,S_{21},\,S_{12}\,,\,S_{22})$ is set for each trace. Before you select the measured parameter, first activate the trace.



4.7.3 Absolute Measurements

The absolute measurement is the measurement of absolute power of a signal at a receiver input. Unlike relative measurements of S-parameters, which represent a relation between the signals at inputs of two receivers, absolute measurements determine the signal power at input of one receiver. A 2-port Analyzer has four independent receivers: A, B, R1, R2 (See figure 4.11).

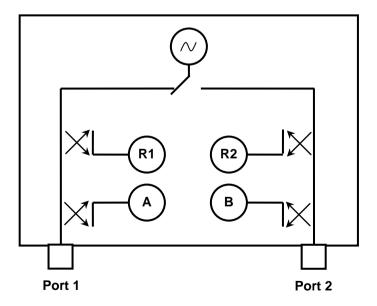


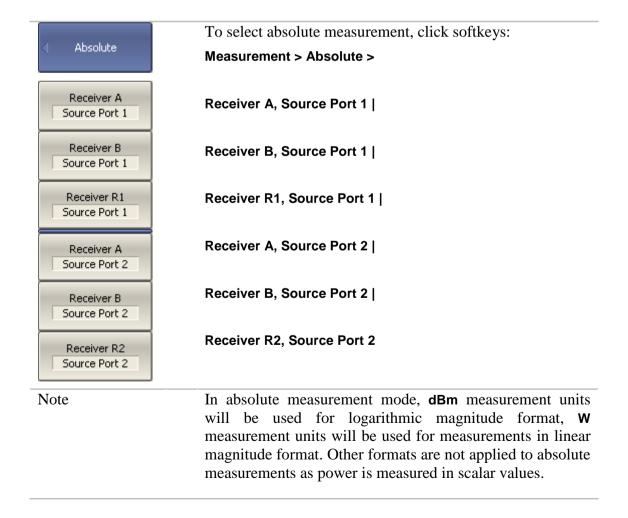
Figure 4.11 Analyzer block diagram

R1 and R2 are the receivers of a reference signal, A and B are the receivers of a test signal. A and R1 receivers are located in port 1, B and R2 receivers are located in port 2. There are six types of absolute measurements depending on the port number (See table 4.10):

Table 4.10 Absolute measurements

Symbols	Definition
A(1)	Test signal receiver A (Source Port 1)
A(2)	Test signal receiver A (Source Port 2)
B(1)	Test signal receiver B (Source Port 1)
B(2)	Test signal receiver B (Source Port 2)
R1(1)	Reference signal receiver R1 (Source Port 1)
R2(2)	Reference signal receiver R2 (Source Port 2)

4.7.4 Absolute Measurement Setting



4.8 Format Setting

The Analyzer offers the display of the measured S-parameters on the screen in three formats:

- rectangular format;
- polar format;
- Smith chart format.

4.8.1 Rectangular Formats

In this format, stimulus values are plotted along X-axis and the measured data are plotted along Y-axis (See figure 4.12).

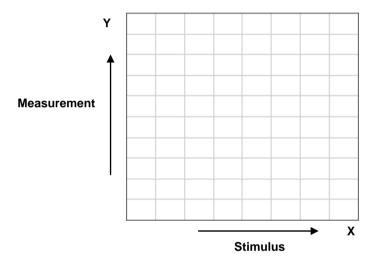


Figure 4.12 Rectangular format

To display S-parameter complex value along Y-axis, it should be transformed into a real number. Rectangular formats involve various types of transformation of an S-parameter $S = a + j \cdot b$, where:

- \blacksquare a real part of S-parameter complex value;
- b imaginary part of S-parameter complex value.

There are eight types of rectangular formats depending on the measured value plotted along Y-axis (See table 4.11).

Table 4.11 Rectangular formats

Table 4.11 Rectang	guiai ioiiliais		
Format Type Description	Label	Data Type (Y-axis)	Measurement Unit (Y-axis)
Logarithmic Magnitude	Log Mag	S-parameter logarithmic magnitude:	Decibel (dB)
		$20 \cdot \log S $,	
		$ S = \sqrt{a^2 + b^2}$	
Voltage Standing Wave Ratio	SWR	$\frac{1 + S }{1 - S }$	Abstract number
Phase	Phase	S-parameter phase from – 180° to +180°:	Degree (°)
		$\frac{180}{\pi} \cdot arctg \frac{a}{b}$	
Expanded Phase	Expand Phase	S-parameter phase, measurement range expanded to from below – 180° to over +180°	Degree (°)
Group Delay	Group Delay	Signal propagation delay within the DUT: $-\frac{d\varphi}{d\omega},$ $\varphi = arctg \frac{a}{b}, \omega = 2\pi \cdot f$	Second (sec.)
Linear Magnitude	Lin Mag	S-parameter linear magnitude: $\sqrt{a^2 + b^2}$	Abstract number
Real Part	Real	S-parameter real part: $a = re(S)$	Abstract number
Imaginary Part	Imag	S-parameter imaginary part: $b = im(S)$	Abstract number

4.8.2 Polar Format

Polar format represents the measurement results on the pie chart (See figure 4.13). The distance to a measured point from the graph center corresponds to the magnitude of its value. The counterclockwise angle from the positive horizontal axis corresponds to the phase of the measured value.

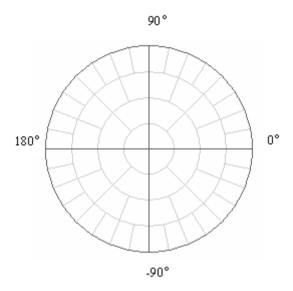


Figure 4.13 Polar format

The polar graph does not have a frequency axis, so frequency will be indicated by the markers. There are three types of polar formats depending on the data displayed by the marker. The traces will remain the same on all the graphs.

Table 4.12 Polar formats

Format Type Description	Label	Data Displayed by Marker	Measurement Unit (Y-axis)
Linear Magnitude and	Polar (Lin)	S-parameter linear magnitude	Abstract number
Phase		S-parameter phase	Degree (°)
Logarithmic Magnitude and	Polar (Log)	S-parameter logarithmic magnitude	Decibel (dB)
Phase		S-parameter phase	Degree (°)
Real and	Polar (Re/lm)	S-parameter real part	Abstract number
Imaginary Parts	(**************************************	S-parameter imaginary part	Abstract number

4.8.3 Smith Chart Format

Smith chart format is used for representation of impedance values for DUT reflection measurements. In this format, the trace has the same points as in polar format.

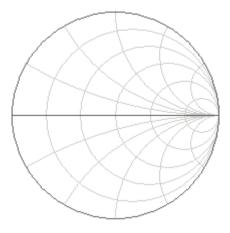


Figure 4.14 Smith chart format

The polar graph does not have a frequency axis, so frequency will be indicated by the markers. There are five types of Smith chart formats depending on the data displayed by the marker. The traces will remain the same on all the graphs.

Table 4.13 Smith chart formats

Format Type Description	Label	Data Displayed by Marker	Measurement Unit (Y-axis)
Linear Magnitude and	Smith (Lin)	S-parameter linear magnitude	Abstract number
Phase		S-parameter phase	Degree (°)
Logarithmic Magnitude and	Smith (Log)	S-parameter logarithmic magnitude	Decibel (dB)
Phase		S-parameter phase	Degree (°)
Real and Imaginary Parts	Smith (Re/Im)	S-parameter real part	Abstract number
inaginary runs		S-parameter imaginary part	Abstract number

Table 4.13 Smith chart formats (continued)

Complex Impedance (at Input)	dance $(R + jX)$		Ohm (Ω)
		Reactance at input: $X = im(Z_{inp})$	Ohm (Ω)
		Equivalent capacitance or inductance:	
		$C = -\frac{1}{\omega X}, X < 0$	Farad (F)
		$L = \frac{X}{\omega}, X > 0$	Henry (H)
Complex admittance (at Input)	Smith (G + jB)	Conductance at input: $G = re(Y_{inp}),$ $Y_{inp} = \frac{1}{Z_0} \cdot \frac{1 - S}{1 + S}$	Siemens (S)
		Susceptance at input: $B = im(Y_{inp})$	Siemens (S)
		Equivalent capacitance or inductance:	
		$C = \frac{B}{\omega}, B > 0$	Farad (F)
		$L = -\frac{1}{\omega B}, B < 0$	Henry (H)

 $Z_0-\mbox{test}$ port impedance. Z_0 setting is described in section 5.2.12.

4.8.4 Data Format Setting

You can select the format for each trace of the channel individually. Before you set the format, first activate the trace.



To set the rectangular format, use the following softkey:

Format

Then select the required format:

- Logarithmic magnitude
- SWR
- Phase
- Expanded phase
- Group delay
- Linear magnitude
- Real part
- Imaginary part



To set the Smith chart format, use the following softkeys:

Format > Smith

Then select the required format:

- Logarithmic magnitude and phase
- Linear magnitude and phase
- Real and imaginary parts
- Complex impedance (at input)
- Complex admittance (at input)



To set the Smith chart format, use the following softkeys:

Format > Polar

Then select the required format:

- Logarithmic magnitude and phase
- Linear magnitude and phase
- Real and imaginary parts

4.9 Scale Setting

4.9.1 Rectangular Scale

For rectangular format you can set the following parameters (See figure 4.15):

- Scale division:
- Reference level value;
- Reference level position;

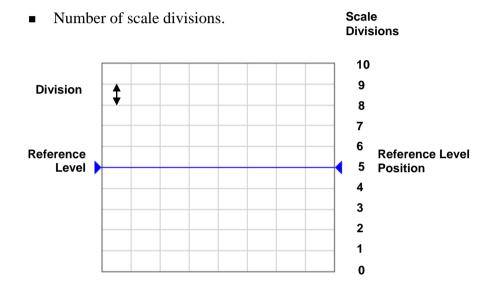
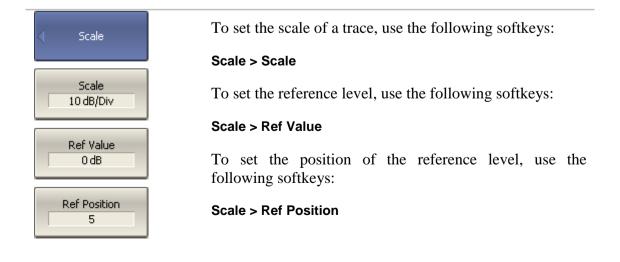


Figure 4.15 Rectangular scale

4.9.2 Rectangular Scale Setting

You can set the scale for each trace of a channel. Before you set the scale, first activate the trace.



Divisions 10	To set the number of trace scale divisions, use the following softkeys:
	Scale > Divisions ¹
Note	Quick trace scale setting by the mouse is described in section 4.3.

4.9.3 Circular Scale

For polar and Smith chart formats, you can set the outer circle value (See figure 4.16).

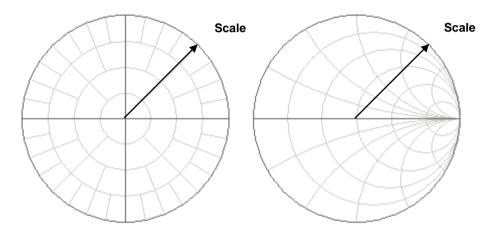
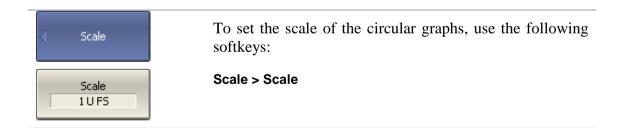


Figure 4.16 Circular scale

4.9.4 Circular Scale Setting

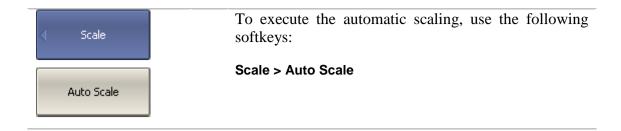


4.9.5 Automatic Scaling

The automatic scaling function automatically allows the user to define the trace scale so that the trace of the measured value could fit into the graph entirely.

In rectangular format, two parameters are adjustable: scale division and reference level position. In circular format, the outer circle value will be adjusted.

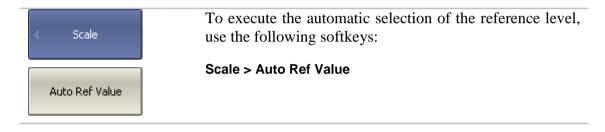
Number of the scale divisions affect all the graphs of the channel.



4.9.6 Reference Level Automatic Selection

This function executes automatic selection of the reference level in rectangular coordinates.

After the function has been executed, the trace of the measured value makes the vertical shift so that the reference level crosses the graph in the middle. The scale division will remain the same.



4.9.7 Electrical Delay Setting

The electrical delay function allows the user to define the compensation value for the electrical delay of a device. This value is used as compensation for the electrical delay during non-linear phase measurements. The electrical delay is set in seconds.

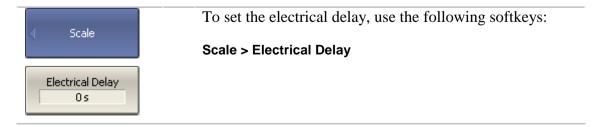
If the electrical delay setting is other than zero, S-parameter value will vary in accordance with the following formula:

$$S = S \cdot e^{j \cdot 2\pi \cdot f \cdot t}$$
, where

f – frequency, Hz,

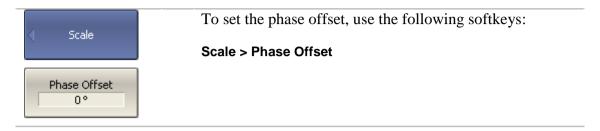
t – electrical delay, sec.

The electrical delay is set for each trace individually. Before you set the electrical delay, first activate the trace.



4.9.8 Phase Offset Setting

The phase offset function allows the user to define the constant phase offset of a trace. The value of the phase offset is set in degrees for each trace individually. Before you set the phase offset, first activate the trace.



4.10 Measurement Optimizing

You can set IF bandwidth, averaging and smoothing parameters in **Average** softkey submenu.

4.10.1 IF Bandwidth Setting

The IF bandwidth function allows the user to define the bandwidth of the test receiver. The IF bandwidth runs through the following sequence of numbers: 1, 1.5, 2, 3, 5, 7 within the range of 10 Hz to 30 kHz.

The IF bandwidth narrowing allows to reduce self-noise and widen the dynamic range of the Analyzer. Also the sweep time will increase. Narrowing of the IF bandwidth by 10 will reduce the receiver noise by 10 dB.

The IF bandwidth should be set for each channel individually. Before you set the IF bandwidth, first activate the channel.



To set the IF bandwidth, use the following softkeys:

Average > IF Bandwidth

4.10.2 Averaging Setting

The averaging is performed in a measurement point is made over several previous sweeps. The averaging function is similar to IF bandwidth narrowing. It allows you to reduce self-noise and widen the dynamic measurement range of the Analyzer.

The averaging in each measurement point is made over several sweeps in accordance with the following equation:

$$\begin{cases} M_i = S_i, & i = 0 \\ M_i = \left(1 - \frac{1}{n}\right) \cdot M_{i-1} + \frac{S_i}{n}, & i > 0, \quad n = \min(i+1, N) \end{cases}$$

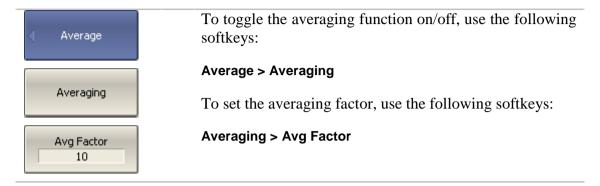
 M_i - i-sweep averaging result;

 S_i – i-sweep measurement parameter (S-parameter) value;

N – averaging factor is set by the user from 1 to 999; the higher the factor value the stronger the averaging effect.

When the averaging function is enabled, the current number of iterations and the averaging factor, e.g. «9/10», will appear in the channel status bar. The averaging process is considered stable when the both numbers have become equal.

The averaging should be set for each channel individually. Before you set the averaging, first activate the channel.

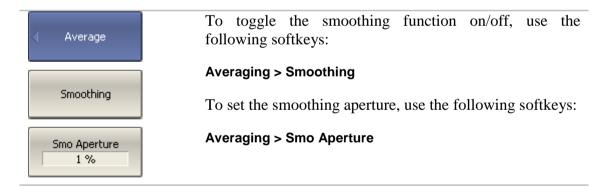


4.10.3 Smoothing Setting

The smoothing of the sweep results is made by averaging of adjacent points of the trace determined by the moving aperture. The aperture is set by the user in percent against the total number of the trace points.

The smoothing does not increase dynamic range of the Analyzer. It does not affect the average level of the trace, but it reduces the noise bursts.

The smoothing should be set for each trace individually. Before you set the smoothing, first activate the trace.



4.11 Mixer Measurements

4.11.1 Mixer Measurement Methods

The Analyzer allows you to perform measurements of mixers and other frequency translating devices using scalar and vector methods.

The **scalar method** allows measurement of scalar transmission S-parameters of the frequency translating devices. Phase and group delay measurements are not accessible in this mode. Simple measurement setup (without any additional equipment) is the advantage of this method (See figure 4.17).

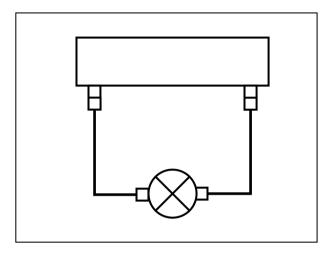


Figure 4.17 Scalar mixer measurement setup

The scalar measurement method is based on *frequency offset* mode. The frequency offset mode produces frequency offset between the Analyzer test ports and described in detail in section 4.11.2. The frequency offset mode can be combined with different calibration methods.

When measuring the mixers by scalar method the most accurate method of calibration is *scalar mixer calibration* (See section 5.6).

An easier but less accurate method is to use the absolute measurements in combination with receiver calibration and power calibration (See sections 4.7.3, 5.5 and section 5.4). This method often features ripple of transmission S-parameters of the mixer due to the mixer input and output mismatch. Partially this can be compensated by matching attenuators at input and output of the 3-10 dB mixer.

The **vector method** allows measurement of mixer transmission complex S-parameter including phase and group delay. The method requires additional equipment (See figure 4.18): an external mixer with filter, which is called *calibration mixer*, and a LO common for both the calibration mixer and the mixer under test.

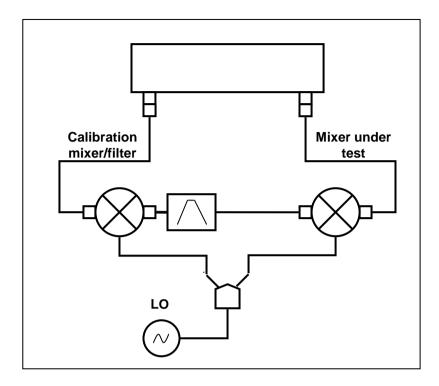


Figure 4.18 Vector mixer measurement setup

The vector mixer measurement method ensures same frequency at the both test ports of the Analyzer, in normal operation mode. In this case, the only applicable calibration method is *vector mixer calibration* (See section 5.7).

4.11.2 Frequency Offset Mode

The frequency offset mode enables you to measure transmission S-parameters of the frequency translating devices. In this section, we refer to the frequency translating devices such frequency shifting devices as mixers and converters, as well as devices dividing or multiplying frequency.

This measurement mode is based on frequency offset of receiver port frequency relative to source port frequency. The frequency offset is defined for each port using three coefficients: multiplier, divider, and offset. These coefficients allow for calculation of a port frequency relative to the *basic frequency range*.

$$F_{port} = \frac{M}{D} F_{base} + F_{ofs}$$

M – multiplier,

D – divider,

 F_{ofs} – offset,

 F_{base} – basic frequency.

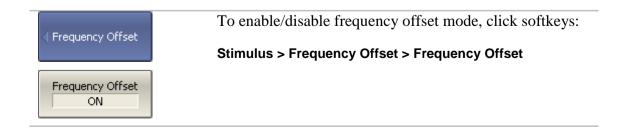
In majority of cases it is sufficient to apply offset to one of the ports, leaving the other one at the basic frequency (M=1, D=1, Fofs=0).

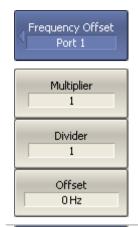
Below are some examples of offset coefficient calculation at different types of frequency conversion. Mixer input is connected to port 1, mixer output is connected to port 2. RF – output frequency, IF – intermediate frequency, LO – local oscillator frequency. Second port of the Analyzer is running in frequency offset mode:

In frequency offset mode, the bottom part of the channel window will indicate each port frequency span (See figure 4.19).



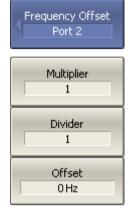
Figure 4.19 Channel window in frequency offset mode





To enter offset coefficients for port 1, click softkeys:

Stimulus > Frequency Offset > Port 1 > Multiplier | Divider | Offset



To enter offset coefficients for port 2, click softkeys:

Stimulus > Frequency Offset > Port 2 > Multiplier | Divider | Offset.

4.11.3 Automatic Adjustment of Offset Frequency

When you perform mixer measurements in frequency offset mode, you need to set the offset frequency equal to LO frequency. The accuracy of the offset frequency setting must be no less than IF filter bandwidth, otherwise, the receiver will not get the output signal from the mixer. In practice, there is always some LO frequency setting error (unknown to the user) when the tested mixer has an internal LO.

The Analyzer offers the automatic adjustment function of the offset frequency. This function enables you to accurately set the offset frequency equal to the frequency of the internal LO of the DUT.

Automatic adjustment function of the offset frequency can be activated only for one port. The value of the offset frequency automatic adjustment will be indicated in the line of the respective port in the channel window (See figure 4.20).

The automatic adjustment can be made within ± 500 kHz range from the offset frequency set by the user. The function can be enabled/disabled by the user. Adjustment can be performed upon key pressing, or continuously with the set time interval.



Figure 4.20 Channel window in frequency offset mode with enabled automatic adjustment function of the offset frequency

The typical error of automatic adjustment of the offset frequency depends on the current IF filter bandwidth (See table 4.14).

Table 4.14 Typical error of offset frequency automatic adjustment

IF Filter Bandwidth	Typical Error of Offset Frequency Automatic Adjustment
10 kHz	500 Hz
3 kHz	50 Hz
1 kHz	15 Hz
300 Hz	5 Hz
100 Hz	1.5 Hz

4.11.3.1 Setting of Offset Frequency Automatic Adjustment



To enable/disable automatic adjustment function of the offset frequency, click softkeys:

Stimulus > Frequency Offset > Offset Adjust > Offset Adjust

Select Port	Select port by softkeys:
2	Stimulus > Frequency Offset > Offset Adjust > Select Port
	Note: normally, it is the port with enabled frequency offset.
Adjust Value	Enter adjustment value by softkeys:
950 Hz	Stimulus > Frequency Offset > Offset Adjust > Adjust Value
	Note: or click Adjust Immediate , as described below.
Continuous Adjust	To enable/disable continuous adjustment, click softkeys:
OFF	Stimulus > Frequency Offset > Offset Adjust > Continuous Adjust
Adjust Period 10 sec	To enter the time interval for continuous adjustment, click softkeys:
	Stimulus > Frequency Offset > Offset Adjust > Adjust Period
Adjust Immediate	To initiate a single adjustment, click softkeys:
. Adjuse Influence	Stimulus > Frequency Offset > Offset Adjust > Adjust Immediate

5 CALIBRATION AND CALIBRATION KIT

5.1 General Information

5.1.1 Measurement Errors

S-parameter measurements are influenced by various measurement errors, which can be broken down into two categories:

- systematic errors, and
- random errors.

Random errors comprise such errors as noise fluctuations and thermal drift in electronic components, changes in the mechanical dimensions of cables and connectors subject to temperature drift, repeatability of connections and cable bends. Random errors are unpredictable and hence cannot be estimated and eliminated in calibration. Random errors can be reduced by correct setting of the source power, IF bandwidth narrowing, sweep averaging, maintaining constant environment temperature, observance of the Analyzer warm-up time, careful connector handling, and avoidance of cable bending after calibration.

Random errors and related methods of correction are not mentioned further in this section.

Systematic errors are the errors caused by imperfections in the components of the measurement system. Such errors occur repeatedly and their characteristics do not change with time. Systematic errors can be determined and then reduced by performing mathematical correction of the measurement results.

The process of measurement of precision devices with predefined parameters with the purpose of determination of measurement systematic errors is called **calibration**, and such precision devices are called **calibration standards**. The most commonly used calibration standards are SHORT, OPEN, and LOAD.

The process of mathematical compensation (numerical reduction) for measurement systematic errors is called an **error correction**.

5.1.2 Systematic Errors

The systematic measurement errors of vector network analyzers are subdivided into the following categories according to their source:

- Directivity;
- Source match:
- Load match;
- Isolation:
- Reflection/transmission tracking.

The measurement results before the procedure of error correction has been executed are called **uncorrected**.

The residual values of the measurement results after the procedure of error correction are called **effective**.

5.1.2.1 Directivity Error

A directivity error (**Ed**) is caused by incomplete separation of the incident signal from the reflected signal by the directional coupler in the source port. In this case part of the incident signal energy comes to the receiver of the reflected signal. Directivity errors do not depend on the characteristics of the DUT and usually have stronger effect in reflection measurements.

5.1.2.2 Source Match Error

A source match error (**Es**) is caused by the mismatch between the source port and the input of the DUT. In this case part of the signal reflected by the DUT reflects at the source port and again comes into the input of the DUT. The error occurs both in reflection measurement and in transmission measurement. Source match errors depend on the relation between input impedance of the DUT and test port impedance when switched as a signal source.

Source match errors have strong effect in measurements of a DUT with poor input matching.

5.1.2.3 Load Match Error

A load match error (EI) is caused by the mismatch between the receiver port and the output of the DUT. In this case part of the signal transmitted through the DUT reflects at the receiver port and comes to the output of the DUT. The error occurs in transmission measurements and in reflection measurements (for a 2-port DUT). Load match errors depend on the relation between output impedance of the DUT and test port impedance switched as a signal receiver.

In transmission measurements the load match error has considerable influence if the output of the DUT is poorly matched.

In reflection measurements the load match error has considerable influence in case of poor output match and low attenuation between the output and input of the DUT.

5.1.2.4 Isolation Error

An isolation error (**Ex**) is caused by a leakage of the signal from the source port to the receiver port escaping transmission through the DUT.

The Analyzer has typical isolation ratio of -140 dB, what allows to ignore this error for most of measurements. The isolation error measurement is a non-mandatory option in all types of calibration.

5.1.2.5 Reflection Tracking Error

A reflection tracking error (Er) is caused by the difference in frequency response between the test receiver and the reference receiver of the source port in reflection measurement.

5.1.2.6 Transmission Tracking Error

A transmission tracking error (Et) is caused by the difference in frequency response between the test receiver of the receiver port and the reference receiver of the source port in transmission measurement.

5.1.3 Error Modeling

Error modeling and method of signal flow graphs are applied to vector network analyzers for analysis of its systematic errors.

5.1.3.1 One-Port Error Model

In reflection measurement only one port of the Analyzer is used. The signal flow graph of errors for the port 1 is represented in figure 5.1. For port 2 the signal flow graph of the errors will be similar.

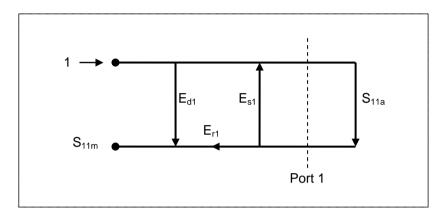


Figure 5.1 One-port error model

Where:

- S_{11a} reflection coefficient true value;
- S_{11m} reflection coefficient measured value.

The measurement result at port 1 is affected by the following three systematic error terms:

- \mathbf{E}_{d1} directivity;
- $\mathbf{E_{s1}}$ source match;
- $\mathbf{E_{r1}}$ reflection tracking.

For normalization the stimulus value is taken equal to 1. All the values used in the model are complex.

After determining all the three error terms E_{d1} , E_{s1} , E_{r1} for each measurement frequency by means of a **full 1-port calibration**, it is possible to calculate (mathematically subtract the errors from the measured value S_{11m}) the true value of the reflection coefficient S_{11a} .

There are simplified methods, which eliminate the effect of only one or two out of the three systematic errors.

5.1.3.2 Two-Port Error Model

For a two-port measurement, two signal flow graphs are considered. One of the graphs describes the case where port 1 is the stimulus source, the other graph describes the case where port 2 is the stimulus source.

The signal flow graphs of errors effect in a two-port system are represented in figure 5.2:

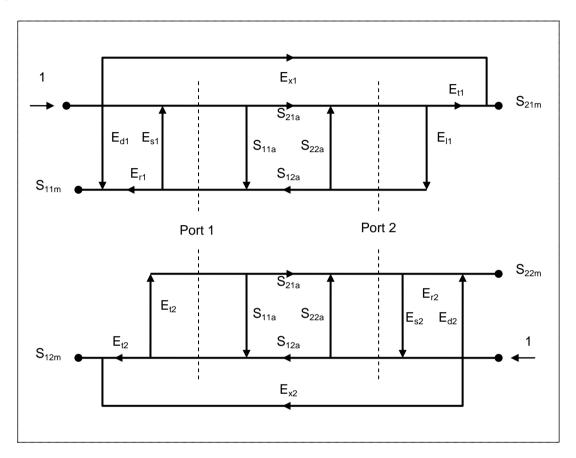


Figure 5.2 Two-port error model

Where:

- S_{11a} , S_{21a} , S_{12a} , S_{22a} true values of the DUT parameters;
- S_{11m} , S_{21m} , S_{12m} , S_{22m} measured values of the DUT parameters.

For normalization the stimulus value is taken equal to 1. All the values used in the model are complex.

The measurement result in a two-port system is affected by twelve systematic error terms.

Table 5.1 Systematic error terms

Description	Stimulus Source	
	Port 1	Port 2
Directivity	$\mathbf{E_{d1}}$	$\mathbf{E_{d2}}$
Source match	$\mathbf{E_{s1}}$	$\mathbf{E_{s2}},$
Reflection tracking	$\mathbf{E_{r1}}$	${ m E_{r2}}$
Transmission tracking	$\mathbf{E_{t1}}$	$\mathbf{E_{t2}}$
Load match	E _{l1}	\mathbf{E}_{12}
Isolation	$\mathbf{E_{x1}}$	$\mathbf{E_{x2}}$

After determination of all the twelve error terms for each measurement frequency by means of a **2-port calibration**, it is possible to calculate the true value of the S-parameters: S_{11a} , S_{21a} , S_{12a} , S_{22a} .

There are simplified methods, which eliminate the effect of only one or several out of the twelve systematic error terms.

Note	If you use a 2-port calibration, to determine any of S-parameters you need to know all the four measurements
	S_{11m} , S_{21m} , S_{12m} , S_{22m} . That is why to update one or all of the S-parameters, you need to perform two sweeps: with port 1 as a signal source, and with port 2 as a signal source.

5.1.4 Analyzer Test Ports Defining

The test ports of the Analyzer are defined by means of calibration. The test port is a connector accepting a calibration standard in the process of calibration.

A type-N 50 Ω connector on the front panel of the Analyzer will be the test port if the calibration standards are connected directly to it.

Sometimes it is necessary to connect coaxial cable and/or adapter to the connector on the front panel for connection of the DUT with a different connector type. In such cases connect calibration standards to the connector of the cable or adapter.

Figure 5.3 represents two cases of test port defining for 2-port measurement. The use of cables and/or adapters does not affect the measurement results if they were integrated into the process of calibration.

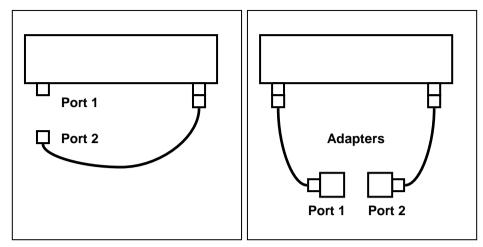


Figure 5.3 Test port defining

In some cases, the term of *calibration plane* is used. Calibration plane is an imaginary plane located at the ends of the connectors, which accept calibration standards during calibration.

5.1.5 Calibration Steps

The process of calibration comprises the following steps:

- Selection of the calibration kit matching the connector type of the test port. The calibration kit includes such standards as SHORT, OPEN, and LOAD with matched impedance. Magnitude and phase responses i.e. S-parameters of the standards are well known. The characteristics of the standards are represented in the form of an equivalent circuit model, as described below;
- Selection of a calibration method (see section 5.1.6) is based on the required accuracy of measurements. The calibration method determines what error terms of the model (or all of them) will be compensated;
- Measurement of the standards within a specified frequency range.
 The number of the measurements depends on the type of calibration:
- The Analyzer compares the measured parameters of the standards against their predefined values. The difference is used for calculation of the calibration coefficients (systematic errors);
- The table of calibration coefficients is saved into the memory of the Analyzer and used for error correction of the measured results of any DUT.

Calibration is always made for a specific channel, as it depends on the channel stimulus settings, particularly on the frequency span. This means that a table of calibration coefficients is being stored each for an individual channel.

5.1.6 Calibration Methods

The Analyzer supports several methods of one-port and two-port calibrations. The calibration methods vary by quantity and type of the standards being used, by type of error correction, and accuracy. The table below represents the overview of the calibration methods.

Table 5.2 Calibration methods

Calibration Method	Parameters	Standards	Errors	Accuracy
Reflection Normalization	S ₁₁ or S ₂₂	 SHORT or OPEN LOAD ¹ 	E_{r1}, E_{d1}^{-1} or E_{r2}, E_{d2}^{-1}	High
Transmission Normalization	S ₂₁ or S ₁₂	 THRU 2 LOADs² 	E_{t1}, E_{x1}^{2} or E_{t2}, E_{x2}^{2}	Low
Full One-Port Calibration	S ₁₁ or S ₂₂	SHORTOPENLOAD	E_{r1},E_{d1},E_{s1} or E_{r2},E_{d2},E_{s1}	High
One-Path Two- Port Calibration	S ₁₁ , S ₂₁ or S ₁₂ , S ₂₂	 SHORT OPEN LOAD THRU 2 LOADs² 	$\begin{aligned} &E_{rl}, E_{dl}, \ E_{sl}, \ E_{tl}, \\ &E_{xl}^{2} \end{aligned} or \\ &E_{rl}, E_{dl}, E_{sl}, E_{tl}, \\ &E_{xl}^{2} \end{aligned}$	Medium
Full Two-Port Calibration	S_{11}, S_{21} S_{12}, S_{22}	 SHORT OPEN LOAD THRU 2 LOADs² 	$\begin{split} E_{r1}, & E_{d1}, E_{s1}, E_{t1}, \\ E_{l1}, & E_{x1}^2 \end{split}$ $E_{r2}, & E_{d2}, E_{s2}, E_{t2}, \\ E_{l2}, & E_{x2}^2 \end{split}$	High
TRL Calibration	S_{11}, S_{21} S_{12}, S_{22}	THRU or LINEREFLECTLINE or 2 LOADs	$\begin{split} E_{r1}, E_{d1}, E_{s1}, E_{t1}, \\ E_{l1} \\ E_{r2}, E_{d2}, E_{s2}, E_{t2}, \\ E_{l2} \end{split}$	Very High

_

If optional directivity calibration is performed.

If optional isolation calibration is performed.

5.1.6.1 Normalization

Normalization is the simplest method of calibration as it involves measurement of only one calibration standard for each S-parameter.

- 1-port (reflection) S-parameters (S₁₁, S₂₂) are calibrated by means of a SHORT or an OPEN standard, estimating reflection tracking error term **Er**.
- 2-port (transmission) S-parameters (S₂₁, S₁₂) are calibrated by means of a THRU standard, estimating transmission tracking error term Et.

This method is called normalization because the measured S-parameter at each frequency point is divided (normalized) by the corresponding S-parameter of the calibration standard.

Normalization eliminates frequency-dependent attenuation and phase offset in the measurement circuit, but does not compensate for errors of directivity, mismatch or isolation. This constrains the accuracy of the method.

Note

Normalization can also be referred to as **response open**, **response short** or **response thru** calibration depending
on the standard being used: an OPEN, SHORT or THRU
respectively.

5.1.6.2 Directivity Calibration (Optional)

The Analyzer offers optional directivity (**Ed**) calibration feature, which can be used in combination with reflection normalization by means of additional measurement of a LOAD standard. Auxiliary directivity correction increases the accuracy of normalization.

5.1.6.3 Isolation Calibration (Optional)

The Analyzer offers optional isolation (Ex) calibration to be combined with the following three methods of calibration:

- transmission normalization,
- one-path two-port calibration,
- full two-port calibration.

This calibration is performed by isolation measurement using LOAD standards connected to the both test ports of the Analyzer. Isolation calibration can be omitted in most of tests as the signal leakage between the test ports of the Analyzer is negligible.

Note	For isolation calibration, it is recommended to set narrow
	IF bandwidth, attenuation, and firmly fix the cables.

5.1.6.4 Full One-Port Calibration

Full one-port calibration involves connection of the following three standards to one test port:

- SHORT,
- OPEN.
- LOAD.

Measurement of the three standards allows for acquisition of all the three error terms (**Ed, Es, and Er**) of a one-port model. Full 1-port calibration is a highly accurate method for 1-port reflection measurements.

5.1.6.5 One-Path Two-Port Calibration

A one-path two-port calibration combines full one-port calibration with transmission normalization. This method allows for a more accurate estimation of transmission tracking error (Et) than using transmission normalization.

One-path two-port calibration involves connection of the three standards to the source port of the Analyzer (as for one-port calibration) and a THRU standard connection between the calibrated source port and the other receiver port.

One-path two-port calibration allows for correction of **Ed**, **Es**, and **Er** error terms of the source port and a transmission tracking error term (**Et**). This method does not derive source match error term (**El**) of a 2-port error model.

One-path two-port calibration is used for measurements of the parameters of a DUT in one direction, e.g. S_{11} and S_{21} .

5.1.6.6 Full Two-Port Calibration

A full two-port calibration involves seven connections of the standards. This calibration combines two full 1-port calibrations for each port, and one THRU connection, which provides two transmission measurements for each test port being a source. If optional isolation calibration is required, connect LOAD standards to the both test ports of the Analyzer and perform two isolation measurements for each source port.

Full 2-port calibration allows for correction of all the twelve error terms of a 2-port error model: $\mathbf{E_{d1}}$, $\mathbf{E_{d2}}$, $\mathbf{E_{s1}}$, $\mathbf{E_{s2}}$, $\mathbf{E_{r1}}$, $\mathbf{E_{r2}}$, $\mathbf{E_{t1}}$, $\mathbf{E_{t2}}$, $\mathbf{E_{l1}}$, $\mathbf{E_{l2}}$, $\mathbf{E_{x1}}$, $\mathbf{E_{x2}}$ (correction of $\mathbf{E_{x1}}$, $\mathbf{E_{x2}}$ can be omitted).

Full 2-port calibration is a highly accurate method of calibration for 2-port DUT measurements.

5.1.6.7 Sliding Load Calibration

In full one-port and full two-port calibrations it is possible to employ a SLIDING LOAD calibration standard instead of a fixed one. The use of the SLIDING LOAD standard allows for significant increase in calibration accuracy at high frequencies compared to the FIXED LOAD standard.

The sliding load calibration involves a series of measurements in different positions of the sliding element to compensate for reflection from the dissipation component.

To activate the sliding load calibration algorithm, the selected calibration kit should contain the calibration standard of sliding load type, and it should be assigned "load" *class* of the corresponding port. Calibration standard editing and class assignment are further described in detail.

The sliding load calibration is not applied at lower frequencies. To eliminate this limitation, use a FIXED LOAD standard in the lower part of the frequency range. For combined calibration with SLIDING and FIXED LOADS, use the procedure of standard *subclasses* assigning. This procedure is described in detail below.

5.1.6.8 Unknown Thru Calibration

An UNKNOWN THRU calibration standard is used only in full two-port calibration, which is also known as SOLT (Short, Open, Load, Thru) calibration.

This calibration method involves connecting the test ports to each other, what is called THRU. If the connectors' gender or type prevent direct connection, a DEFINED THRU is used. But it is not always possible to know the exact parameters of the THRU, in this case UNKNOWN THRU calibration is used.

An arbitrary two-port device with unknown parameters can be used as an UNKNOWN THRU. An UNKNOWN THRU should satisfy only two requirements.

The first requirement applies to the transmission coefficient of the THRU. It should satisfy the reciprocity condition ($S_{21} = S_{12}$), which holds for almost any passive network. Besides, it is not recommended to use a THRU with the loss higher than 20 dB as it can reduce the calibration accuracy.

The second requirement is to know the approximate electrical length of the UNKNOWN THRU within the accuracy of 1/4 of the wavelength at the maximum calibration frequency. This requirement, however, can be omitted if the following frequency increment is selected:

$$\Delta F < \frac{1}{4 \cdot \tau_0}$$
 , where τ_0 – delay of a two-port device.

In this case the Analyzer program automatically determines the electrical length (delay) of the two-port device.

In other words, you can perform the calibration without setting the delay of the UNKNOWN THRU if the frequency increment is small enough. For example, for UNKNOWN THRU with $l_0 \approx 100mm$ and delay coefficient $1/\sqrt{\varepsilon} \approx 0.7$, the delay will be $\tau_0 \approx 477\,ps$. In this case the frequency increment for automatic defining of the UNKNOWN THRU delay should be set to $\Delta F < 524MHz$, or the number of points within the sweep span of 8 GHz should be no less than 16. To ensure reliable operation, set the frequency increment and the number of points with double margin at least.

To be able to use the unknown thru calibration algorithm in full two-port calibration, the calibration kit definition should include the UNKNOWN THRU standard, assigned to the THRU class for the two ports. The procedure of calibration standards editing and their assignment to classes is further described in detail.

An UNKNOWN THRU is defined automatically, if you set the delay to zero in the calibration kit editing menu. Otherwise the user-defined delay value will be used. This value should be set within the accuracy of 1/4 of the wavelength at the maximum calibration frequency.

5.1.6.9 TRL Calibration

TRL (Thru-Reflect-Line) calibration is the most accurate calibration method described herein, as it uses airlines as calibration standards. The TRL calibration requires the use of the following calibration standards:

- THRU or REFERENCE LINE,
- REFLECT (SHORT or OPEN),
- Second LINE or two MATCHes.

TRL is a general name for a calibration family, which comprises such calibrations as LRL, TRM, or LRM named depending on the calibration standards used.

If a zero-length THRU is used as the first standard, the method is called TRL calibration. If a non-zero length LINE is used as the first standard, the calibration method is called LRL (Line-Reflect-Line). To denote the first standard of the TRL and LRL calibration, assign *TRL-Thru* class, which includes THRU and LINEs. A LINE of *TRL-Thru* class is also called *Reference Line*.

An OPEN or SHORT is usually used as a second standard in TRL calibration. To denote the second standard of the TRL calibration, assign *TRL-Reflect* class.

A second LINE is used as the third standard in TRL calibration. At low frequencies, at which MATCHes work well, two MATCHes can be used, as they are an equivalent of a matched line of infinite length. In the latter case, the calibration method is called TRM (Thru-Reflect-Match) or LRM (Line-Reflect-Match) respectively. To denote the third standard of the TRL calibration, assign *TRL-line/match* class, which includes LINEs and MATCHes.

Frequency Range

TRL and LRL calibrations have a limited bandwidth with lower to upper frequency ratio up to 1:8. The band limits depend on the LINE length in TRL calibration or on the difference between the lengths of the two LINEs in LRL calibration.

In theory TRM and LRM calibrations do not have limitations by frequency, however their use at higher frequencies is limited by the quality of the MATCHes. It is recommended to use the TRM and LRM calibrations up to 1 GHz.

Impedance of LINEs and MATCHes

All the LINEs and MATCHes used for TRL calibration must have Z0 impedance values as precise as possible. TRL calibration transfers the impedance of standards into the calibrated system. Precise airlines with an accurate Z0 impedance of 50 Ω are used as LINEs in coaxial paths.

REFERENCE LINE

A zero-length THRU is used as the first standard in TRL calibration. In LRL calibration a LINE, which is called REFERENCE LINE, is used instead of a zero-length THRU. The shortest LINE is used as the REFERENCE LINE. Its length must to be known, so that the calibration plane positions could be calculated exactly. However, LRL calibration is also possible when the REFERENCE LINE length is not known. In this case, its length is assumed to be equal to zero, the calibration plane being in the middle of the LINE, and not at the ports' edges.

TRL LINE

TRL LINE is an airline used in TRL calibration, or the second longest LINE used in LRL calibration. The length of TRL LINE should be known just approximately. The LINE length is used to determine the calibration bandwidth. Let ΔL be the difference between the two LINEs in LRL calibration. In TRL calibration this difference will be equal to the LINE length, as a zero-length THRU is used as a REFERENCE LINE. Then the phase difference between the TRL LINE and REFERENCE LINE or THRU should be no less than 20° at the lower frequency and no more than 160° at the upper frequency of the calibration.

$$20 < \frac{360 \cdot f \cdot \Delta L}{v} < 160$$

$$\Delta L = L_1 - L_0$$
,

L₀ – REFERENCE LINE length,

 L_1 – TRL LINE length,

v – wave velocity in LINE (for airline it is c =2.9979·10⁸ M/c).

So, the useful frequency range for TRL/LRL calibration is 1:8. Besides, TRL/LRL calibration does not work at low frequencies, as it would require a very long LINE. Two

or more TRL LINEs are used to extend the calibration frequency. For example, in case of using two TRL LINEs the frequency range can be increased up to 1:64.

TRL MATCH

Unlike TRL/LRL calibration, TRM/LRM calibration uses MATCHes, which are the equivalent to the infinitely long LINE, instead of a TRL LINE. Theoretically TRM/LRM calibration has no frequency limitations. However, the use of TRM/LRM calibration at higher frequencies is limited by the quality of the MATCHes. As a rule, the TRM/LRM calibration is used at lower frequencies, as it is good starting from zero frequency.

TRL REFLECT

There are no strict requirements to the TRL REFLECT standard. You should know only approximate parameters of the TRL REFLECT standard. The REFLECT standard should have high reflection coefficient, close to 1. The phase of the standard must be known within ±90°. Normally, any OPEN or SHORT meets this requirement. The next requirement is that the reflection coefficient must be the same for all the ports. If one standard is used for all the ports by turns, then this requirement is automatically fulfilled. If the ports have different genderes or types of connectors, use special standards with the identical electrical specifications, which are available in pairs.

TRL Calibration Frequency Extension

To extend the frequency of TRL calibration a method of dividing into several non-overlapping bands is applied. For each frequency band a separate TRL LINE of different length is used. The phase difference between each TRL LINE and the REFERENCE LINE must be from 20° to 160°, as indicated above. A MATCH standard is used in the lowest frequency band.

The Analyzer software allows using up to 8 LINES for calibration frequency extension. To achieve this, there are two steps of handling the calibration kits:

- defining frequency limits to calibration standards (see section 5.3.2);
- assigning classes to calibration standards, where up to 8 calibration standards can be assigned to one class (see section 5.3.4).

Perform the above mentioned dividing of the calibration band into sub-bands and assign a separate TRL LINE to each of them in the calibration kit editing menu before calibration.

5.1.6.10 Multiline TRL Calibration

Regular TRL calibration, described in the previous section uses several LINEs of different lengths for frequency extension. It is provided by the method of dividing the frequency band into separate sub-bands.

Multiline TRL calibration also uses several LINEs. But it does not divide the frequency band into several sub-bands. Instead, all the LINEs are used simultaneously over the whole calibration bandwidth. The redundancy of the LINEs measurements allows for both extending the frequency range and increasing the calibration accuracy. The number

of LINEs should be no less than three. The more LINEs you use, the higher the accuracy you will achieve.

To employ multiple LINEs in the calibration procedure, use the same method of standards subclasses assignment as in the regular TRL calibration (see section 5.3.4). Defining frequency limits to calibration standards is not necessary for Multiline TRL calibration method.

The procedure of switching between the normal and Multiline TRL calibrations see in section 5.2.7.1.

The following table shows the differences between the regular and Multiline TRL calibrations when entering the data into the calibration standards editing menu.

Calibration Standard	Data in Calibration Kit Manager		
	TRL	Multiline TRL	
REFERENCE LINE or THRU	1. Type: THRU/LINE	1. Type: THRU/LINE	
or Tinco	2. Min and max frequency	2. Delay*	
	3. Delay*	3. Class: TRL LINE/MATCH	
	4. Class: TRL THRU	or TRL THRU	
LINE	Type: THRU/LINE Min and max frequency Type Language	The total number of LINEs is no less than 3.	
	3. Class: TRL LINE/MATCH		
MATCH (optional)	1. Type: MATCH	1. Type: MATCH	
	2. Min and max frequency	2. Class: TRL LINE/MATCH	
	3. Class: TRL LINE/MATCH		
REFLECT	1. Type: SHORT or OPEN		
	2. Min and max frequency		
	3. Model parameters, which allow calculating value of phase response within $\pm 90^{\circ}$.		
	4. Class: TRL REFLECT		

^{*} The delay for coaxial airlines is equal to $\frac{L}{v}$, where L is the length of the LINE, and v is the wave velocity in LINE equal to 2.9979·108 m/s.

5.1.7 Calibration Standards and Calibration Kits

Calibration standards are precision physical devices used for determination of errors in a measurement system.

A calibration kit is a set of calibration standards with a specific connector type and specific impedance.

The Analyzer provides definitions of calibration kits produced by different manufacturers. The user can add the definitions of own calibration kits or modify the predefined kits. Calibration kits editing procedure is described in the section 5.3.

To ensure the required calibration accuracy, select the calibration kit being used in the program menu. The procedure of calibration kit selection is described in section 5.2.1.

5.1.7.1 Definitions and Classes of Calibration Standards

Each calibration standard has a definition and belongs to one or several classes.

Calibration standard definition is a mathematical description of its parameters.

Calibration standard class is an application of the standard in a specific calibration method associated with a specific test port number. For example, "LOAD of port 1" in full two-port calibration.

5.1.7.2 Types of Calibration Standards

Calibration standard type is a category of physical devices used to define the parameters of the standard. The Analyzer supports the following types of the calibration standards:

- OPEN,
- SHORT,
- FIXED LOAD,
- SLIDING LOAD,
- THRU/LINE,
- UNKNOWN TRHU,
- standard defined by data (S-parameters).

Note

The type of a calibration standard should not be confused with its class. Calibration standard type is a part of the standard definition used for the calculation of its parameters.

5.1.7.3 Methods of Calibration Standard Defining

The Analyzer provides two methods of defining a calibration standard:

- calibration standard model (See section 5.1.7.4),
- table of S-parameters (See section 5.1.7.5).

The calibration standards defined by the table of S-parameters are called *Data-Based standards*.

Besides, each calibration standard is characterized by lower and upper values of the operating frequency. In the process of calibration, the measurements of the calibration standards outside the specified frequency range are not used.

5.1.7.4 Calibration Standard Model

A model of a calibration standard presented as an equivalent circuit is used for determining of S-parameters of the standard. The model is employed for standards of OPEN, SHORT, FIXED LOAD, THRU/LINE types.

One-port model is used for the standards OPEN, SHORT, and FIXED LOAD (See figure 5.4).

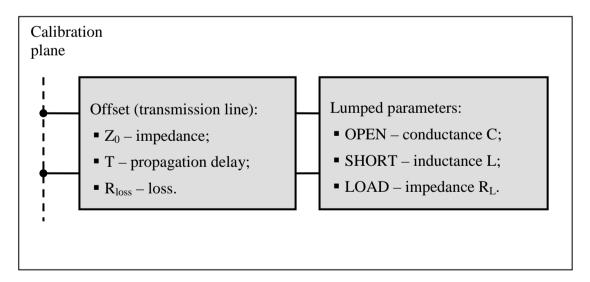


Figure 5.4 One-port standard model

Calibration plane

Offset (transmission line): Z_0 – impedance; R_{loss} – loss.

Two-port model is used for the standard THRU/LINE (See figure 5.5).

Figure 5.5 Two-port standard model

The description of the numeric parameters of an equivalent circuit model of a calibration standard is shown in table 5.3.

Table 5.3 Parameters of the calibration standard equivalent circuit model

Parameter (as in the program)	Parameter Definition
Z ₀ (Offset Z0)	For a one-port standard, it is the offset impedance (of a transmission line) between the calibration plane and the circuit with lumped parameters.
	For a two-port standard, it is the transmission line impedance between the two calibration planes.
T (Offset Delay)	The offset delay. It is defined as one-way propagation time (in seconds) from the calibration plane to the circuit with lumped parameters or to the other calibration plane. Each standard delay can be measured or mathematically determined by dividing the exact physical length by the propagation velocity.
R _{loss} (Offset Loss)	The offset loss in one-way propagation due to the skin effect. The loss is defined in Ω /sec at 1 GHz frequency. The loss in a transmission line is determined by measuring the delay T [sec] and loss L [dB] at 1 GHz frequency. The measured values are used in the following formula: $Rn[\Omega/s] = \frac{L[dB] \cdot Z_0[\Omega]}{4.3429[dB] \cdot T[s]}$

R _{load} (Load Impedance)	Load impedance in $[\Omega]$.
C (C0, C1, C2, C3)	The fringe capacitance of an OPEN standard, which causes a phase offset of the reflection coefficient at high frequencies. The fringe capacitance model is described as a function of frequency, which is a polynomial of the third degree:
	$C = C_0 + C_1 f + C_2 f^2 + C_3 f^3$, where
	f – frequency [Hz]
	C_0C_3 – polynomial coefficients
	Units: $C_0[F]$, $C_1[F/Hz]$, $C_2[F/Hz^2]$, $C_3[F/Hz^3]$
L (L0, L1, L2, L3)	The residual inductance of a SHORT standard, which causes a phase offset of the reflection coefficient at high frequencies. The residual inductance model is described as a function of frequency, which is a polynomial of the third degree:
	$L = L_0 + L_1 f + L_2 f^2 + L_3 f^3$, where
	f – frequency [Hz]
	L_0L_3 – polynomial coefficients
	Units: $L_0[H]$, $L_1[H/Hz]$, $L_2[H/Hz^2]$, $L_3[H/Hz^3]$

5.1.7.5 Data-Based Calibration Standards

The calibration standards defined by data are set using the table of S-parameters. Each line of the table contains frequency and S-parameters of the calibration standard. For one-port standards the table contains the value of only one parameter $-S_{11}$, and for two-port standards the table contains the values of all the four parameters $-S_{11}$, S_{21} , S_{12} , S_{22} .

The table of S-parameters can be filled in manually by the user or downloaded from a file of Touchstone format. Files with *.s1p extension are used for one-port standards, and files with *.s2p extension are used for two-port standards.

5.1.7.6 Scope of Calibration Standard Definition

Different methods of calibration apply either full or partial definitions of the calibration standard kits.

The full two-port calibration, full one-port calibration, one-path two-port calibration, and normalization use fully defined calibration standards, i.e. the standards with known S-parameters. The S-parameters of OPEN, SHORT, LOAD, and THRU/LINE must be defined by the model or by data.

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1 1	•	w

The UNKNOWN THRU and SLIDING LOAD standards are exceptional in the above calibrations. The Sparameters of these standards are defined in the process of calibration. UNKNOWN THRU is used only in full two-port calibration.

TRL calibration and its modifications (TRM, LRL, LRM) apply partial definition of the standards:

- TRL THRU standards must have the required value of Z0 $(S_{11}=S_{22}=0)$ and known length (delay),
- TRL LINE/MATCH standard must have the same value of Z0 as the first standard,
- TRL REFLECT standard must have the phase known as accurately as $\pm 90^{\circ}$.

5.1.7.7 Classes of Calibration Standards

Along with defining a calibration standard by a calibration model or data, the standard should also be assigned a specific class. One calibration standard may belong to several classes. The class assignment is performed for each particular calibration kit. The procedure of class assignment to the calibration standards is described in section 5.3.4.

Class assignment to a calibration standards is required for specifying such properties as the calibration method, the role of a standard in the calibration, and the number of the port(s). The Analyzer supports the following classes of the calibration standards (See table 5.4).

Table 5.4 Classes of the calibration standards

Calibration Methods	Class Label	Port
Full Two-Port	OPEN	1
Calibration		2
Full One-Port Calibration	SHORT	1
One-Path Two-Port		2
Calibration	LOAD	1
Transmission Normalization		2
Reflection Normalization	THRU	1-2
TRL Calibration	TRL THRU	1-2
LRL Calibration	TRL REFLECT	1
TRM Calibration		2
LRM Calibration	TRL LINE/MATCH	1-2

For example, if you assign the class "OPEN of port 1" to the OPEN -F- calibration standard, it will indicate that this standard is used for calibrating the first port using the following calibration methods: full two-port, full one-port, one-path two-port, and normalization.

Note	Class assignment changes the labels of the calibration
	standards on the calibration softkeys.

5.1.7.8 Subclasses of Calibration Standards

Subclasses are used for assignment of one class to several calibration standards. The procedure of subclass assignment is mainly employed for calibration within a wide frequency range by several calibration standards, each of which does not cover the full frequency range. Each class of standards can contain up to 8 subclasses.

For example, in your calibration kit the LOAD standard is defined as from 0 GHz to 2 GHz, and the LINE standard is defined as from 1.5 GHz to 12 GHz. To perform the TRM/TRL calibration within the full frequency range the LOAD should be assigned the subclass 1, and the LINE should assigned the subclass 2 of the "TRL line/match" class.

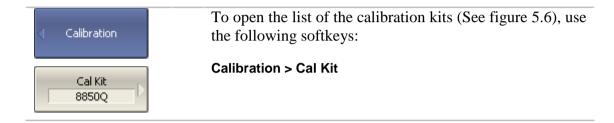
If the standards have an overlapping frequency range (as in the example above, from 1.5 GHz to 2 GHz), the last measured standard will be used.

Note Subclass assignment changes the labels of the	
	softkeys. The measurement softkey is replaced by the
	key, which opens the subclass menu containing the keys
	for measuring several calibration standards.

5.2 Calibration Procedures

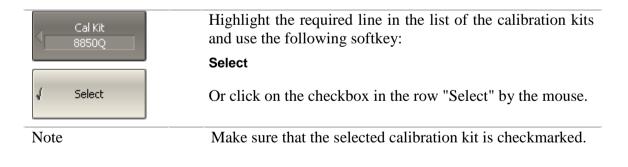
5.2.1 Calibration Kit Selection

The calibration kit employed during a calibration should be selected according to the following procedure. If it is not specified in the list of the predefined calibration kits, you should add it. The procedure of adding and editing of the calibration kits is described in the section 5.3.



	Label	Description	Select	Predefined	Modified	#STDs	
2	85032B/E	Type-N 50Ω 6GHz Cal Kit (Agilent)		Yes	No	6	
3	85032F	Type-N 50Ω 9GHz Cal Kit (Agilent)		Yes	No	8	
4	85054B	Type-N 50Ω 18GHz Cal Kit with Sliding Load(Agilent)		Yes	No	8	
5	85054D	Type-N 50Ω 18GHz Cal Kit (Agilent)		Yes	No	6	
6	05CK10A-150	Type-N 50Ω 18GHz Cal Kit (Rosenberger)		Yes	No	6	
7	8850Q	Type-N 50Ω 18GHz Cal Kit (Maury Microwave)	✓	Yes	No	6	
8	8850C	Type-N 50Ω 18GHz Cal Kit with Sliding Load(Maury Mici		Yes	No	8	
9	85033D/E	3.5 mm 6GHz/9GHz Cal Kit (Agilent)		Yes	No	6	
10	85052B	3.5 mm 26.5GHz Cal Kit with Sliding Load (Agilent)		Yes	No	10	▼

Figure 5.6 The list of calibration kits



5.2.2 Reflection Normalization

Reflection normalization is the simplest calibration method used for reflection coefficient measurements (S_{11} or S_{22}). Only one standard (SHORT or OPEN) is measured (See figure 5.7) in the process of this calibration. You can also perform directivity calibration by measuring a LOAD standard.

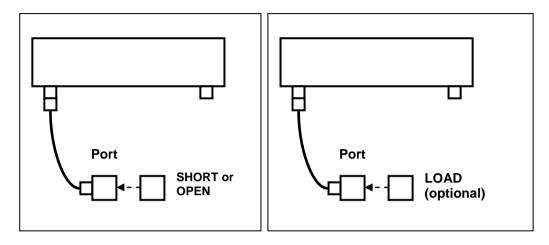
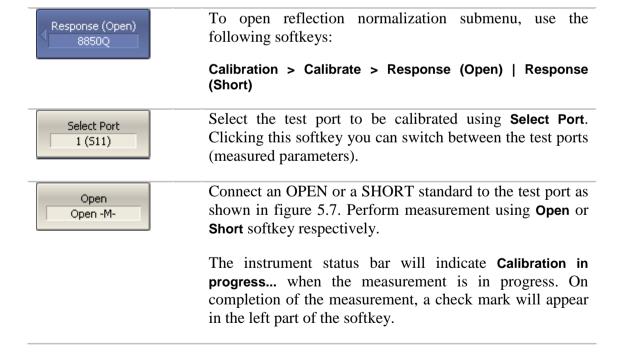


Figure 5.7 Reflection normalization



Γ	Load (Optional) Broadband	

To perform the optional directivity calibration, connect a LOAD standard to the test port as shown in figure 5.7 and perform measurement using **Load (Optional)** softkey.

The instrument status bar will indicate **Calibration in progress...** when the measurement is in progress. On completion of the measurement a check mark will appear in the left part of the softkey.

Apply

To complete the calibration procedure, click **Apply**.

This will activate the process of calibration coefficient table calculation and saving it into the memory. The error correction function will also be automatically enabled.



To clear the measurement results of the standards, click **Cancel**.

This softkey does not cancel the current calibration. To disable the current calibration turn off the error correction function (See section 5.2.10).

Note

You can check the calibration status in channel status bar (See table 5.5) or in trace status field (See table 5.6).

5.2.3 Transmission Normalization

Transmission normalization is the simplest calibration method used for transmission coefficient measurements (S_{21} or S_{12}). One THRU standard is measured (See figure 5.8) in the process of this calibration. You can also perform isolation calibration by measuring two LOAD standards.

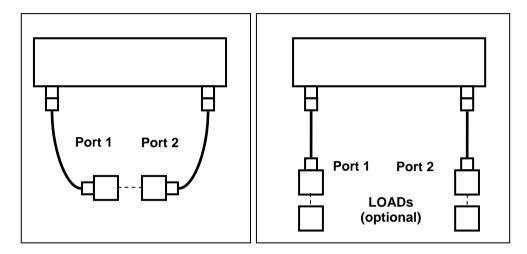
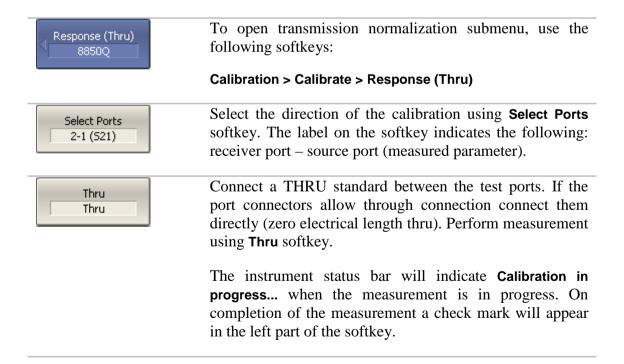


Figure 5.8 Transmission normalization



To perform the optional isolation calibration, connect two Isolation LOAD standards to the test ports as shown in figure 5.8 (Optional) and enable measurement using Isolation (Optional) softkey. The instrument status bar will indicate Calibration in progress... when the measurement is in progress. On completion of the measurement a check mark will appear in the left part of the softkey. To complete the calibration procedure, click **Apply**. Apply This will activate the process of calibration coefficient table calculation and saving it into the memory. The error correction function will also be automatically enabled. To clear the measurement results of the standard, click Cancel Cancel. This softkey does not cancel the current calibration. To disable the current calibration, turn off the error correction function (See section 5.2.10). Note You can check the calibration status in channel status bar (See table 5.5) or in trace status field (See table 5.6).

5.2.4 Full One-Port Calibration

Full one-port calibration is used for reflection coefficient measurements (S_{11} or S_{22}). The three calibration standards (SHORT, OPEN, LOAD) are measured (See figure 5.9) in the process of this calibration.

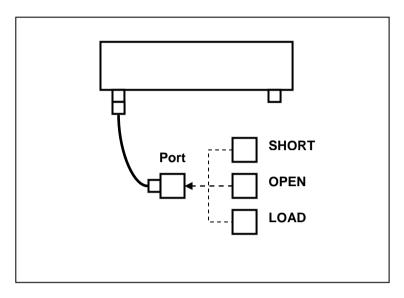
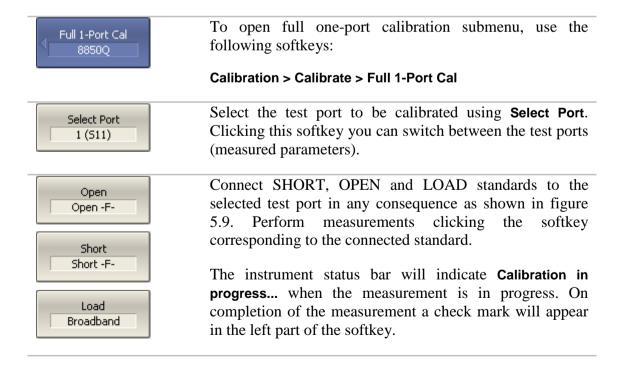


Figure 5.9 Full one-port calibration



Apply	To complete the calibration procedure, click Apply . This will activate the process of calibration coefficient table calculation and saving it into the memory. The error correction function will also be automatically enabled.
Cancel >	To clear the measurement results of the standards, click Cancel .
	This softkey does not cancel the current calibration. To disable the current calibration, turn off the error correction function (See section 5.2.10).
Note	You can check the calibration status in channel status bar (See table 5.5) or in trace status field (See table 5.6).

5.2.5 One-Path Two-Port Calibration

One-path two-port calibration is used for measurements of the DUT parameters in one direction, e.g. S_{11} and S_{21} . This method involves connection of the three calibration standards to the source port, and connection of a THRU standard between the calibrated source port and the other receiver port (See figure 5.10). You can also perform isolation calibration by measuring two LOAD standards.

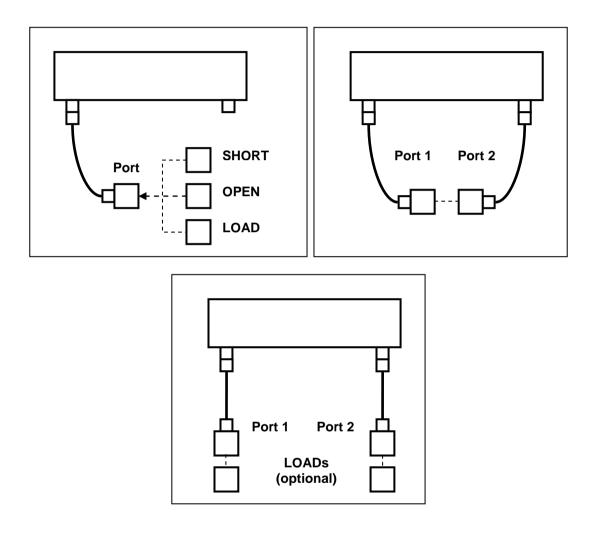
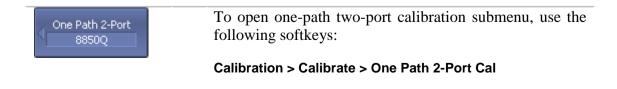


Figure 5.10 One-path two-port calibration



Select Ports 2-1 (521 511)	Select the direction of the calibration using Select Ports softkey. The label on the softkey indicates the following: receiver port – source port (measured parameters).
Open Open -F- Short Short -F-	Connect SHORT, OPEN and LOAD standards to the source port in any consequence, as shown in figure 5.10. Perform measurements clicking the softkey corresponding to the connected standard.
Load Broadband	Connect a THRU standard between the test ports. If the port connectors allow through connection connect them directly (zero electrical length thru). Perform measurement using Thru softkey.
Thru Thru	The instrument status bar will indicate Calibration in progress when the measurement is in progress. On completion of the measurement a check mark will appear in the left part of the softkey.
Isolation (Optional)	To perform the optional isolation calibration, connect two LOAD standards to the test ports as shown in figure 5.10 and enable measurement using Isolation (Optional) softkey.
	The instrument status bar will indicate Calibration in progress when the measurement is in progress. On completion of the measurement a check mark will appear in the left part of the softkey.
Apply	To complete the calibration procedure, click Apply .
	This will activate the process of calibration coefficient table calculation and saving it into the memory. The error correction function will also be automatically enabled.
Cancel	To clear the measurement results of the standards, click Cancel .
	This softkey does not cancel the current calibration. To disable the current calibration, turn off the error correction function (See section 5.2.10).
Note	You can check the calibration status in channel status bar (See table 5.5) or in trace status field (See table 5.6).

5.2.6 Full Two-Port Calibration

Full two-port calibration combines two one-port calibrations for each test port with measurement of transmission and reflection of a THRU standard in both directions (See figure 5.11). You can also perform isolation calibration by measuring two LOAD standards.

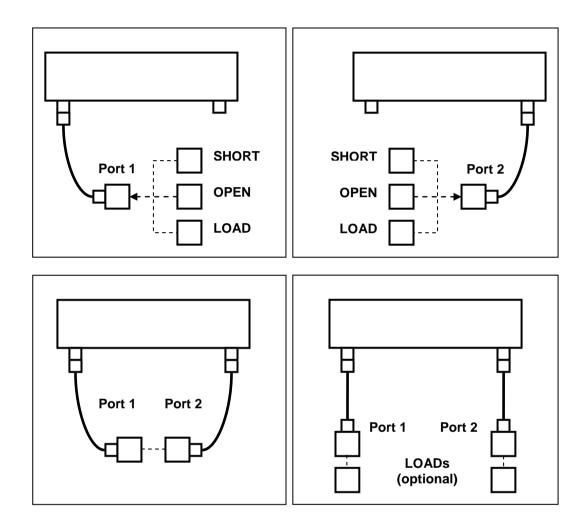
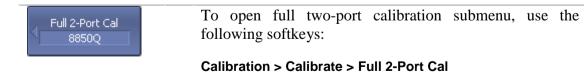


Figure 5.11 Full two-port calibration



Connect SHORT, OPEN and LOAD standards to the 1 Port1 Open and 2 ports in any consequence, as shown in figure 5.11. Open -F-Perform measurements clicking the softkey corresponding to the connected standard. Port1 Short Short -F-Connect a THRU standard between the test ports. If the port connectors allow through connection connect them Port1 Load directly (zero electrical length thru). Perform measurement Broadband using Port 1-2 Thru softkey. The instrument status bar will indicate Calibration in Port2 Open Open -Mprogress... when the measurement is in progress. On completion of the measurement a check mark will appear in the left part of the softkey. Port2 Short Short -M-Port2 Load Broadband Port1-2 Thru Thru To perform the optional isolation calibration, connect two Port1-2 Isol LOAD standards to the test ports as shown in figure 5.11 (Optional) and enable measurement using Port 1-2 Isol (Optional) softkey. The instrument status bar will indicate Calibration in progress... when the measurement is in progress. On completion of the measurement a check mark will appear in the left part of the softkey. To complete the calibration procedure, click **Apply**. Apply This will activate the process of calibration coefficient table calculation and saving it into the memory. The error correction function will also be automatically enabled. To clear the measurement results of the standards, click Cancel Cancel. This softkey does not cancel the current calibration. To disable the current calibration, turn off the error correction function (See section 5.2.10). Note You can check the calibration status in channel status bar (See table 5.5) or in trace status field (See table 5.6).

5.2.6.1 Unknown Thru Calibration

The unknown thru calibration procedure is same as the one for a full two-port calibration described in the previous section.

To start unknown thru calibration, first add UNKNOWN THRU standard to the description of the calibration kit and assign the class to it. After that, the unknown thru measurement softkey will become available in the two-port calibration menu.

See section 5.3.2 for a calibration standard definition in a calibration kit. When adding the unknown thru standard to a kit you should specify just two parameters: UNKNOWN THRU type of the standard and approximate delay of propagation in one direction. You can enter zero value for delay for it to be automatically determined during calibration (See section 5.1.6.8).

See section 5.3.4 for the calibration standard class assignment. A newly added UNKNOWN THRU standard is to be assigned to "Thru, Port 1-2" class.

5.2.7 TRL Calibration

TRL calibration is the most accurate calibration method for two-port measurements (See figure 5.12):

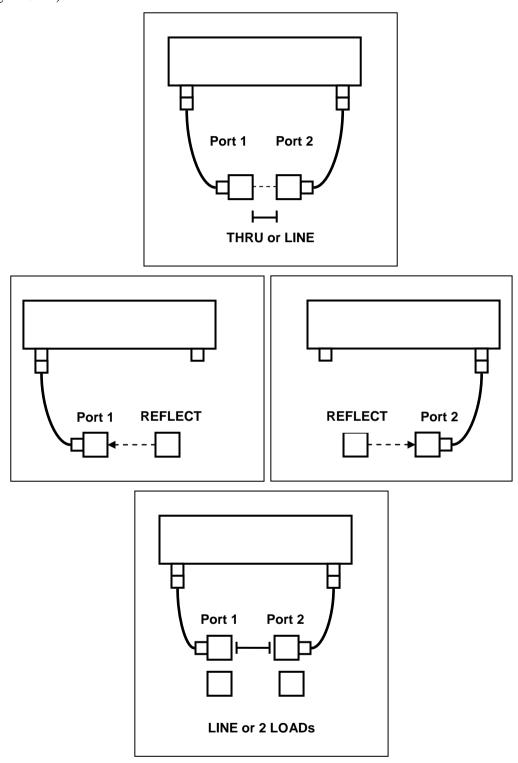


Figure 5.12 TRL calibration

2-Port TRL Cal 8860A	To open TRL calibration submenu, use the following softkeys:
	Calibration > Calibrate > 2-Port TRL Cal
1-2 Thru/Line	Connect a TRL THRU (THRU or LINE) standard between the test ports. Perform measurement using 1–2 Thru/Line softkey.
Port1 Reflect Short	Connect a TRL REFLECT standard to the test ports in any order. Perform measurement using Port 1 Reflect and Port 2 Reflect softkey.
Port2 Reflect Short	·
57.67	Connect a TRL LINE/MATCH (LINE between the test ports and 2 LOADs to each port). Perform measurement
1-2 Line/Match	using Port 1-2 Line/Match softkey.
	The instrument status bar will indicate Calibration in progress when the measurement is in progress. On completion of the measurement a check mark will appear in the left part of the softkey.
Apply	To complete the calibration procedure, click Apply .
Арріу	This will activate the process of calibration coefficient table calculation and saving it into the memory. The error correction function will also be automatically enabled.
Note	System correction will turn automatically off when you press Apply softkey to perform TRL calibration (See section 8.4).
Cancel >	To clear the measurement results of the standards, click Cancel .
	This softkey does not cancel the current calibration. To disable the current calibration, turn off the error correction function (See section 5.2.10).
Note	You can check the calibration status in channel status bar (See table 5.5) or in trace status field (See table 5.6).

5.2.7.1 Multiline Option of TRL Calibration

The procedure of Mulitline TRL calibration is the same as the procedure of TRL calibration described above. The number of the LINEs of various lengths should be no less than three.

First of all create and edit the calibration kit for the Multiline TRL calibration. For details on the data to be entered for the normal and Multiline TRL calibrations see section 5.1.6.10.

Switching between the normal and Multiline TRL calibrations is performed by a specific button in TRL calibration menu.



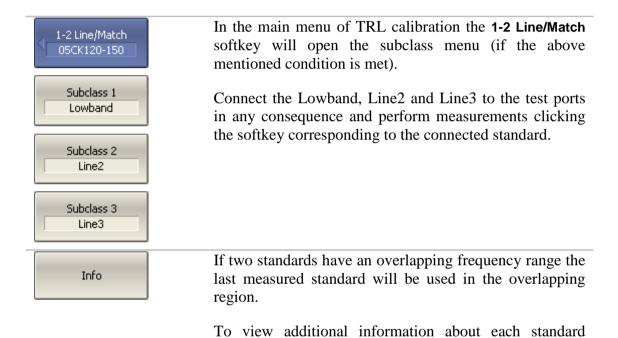
To toggle between normal and Multiline TRL calibrations, use **Multiline** softkey.

5.2.8 Calibration Using Subclasses

When several calibration standards of one class are used for calibration, you should assign subclasses to these standards using the calibration kit editing function. The procedure of subclass assignment is described in section 5.3.4.

When assigning two or more subclasses to one class of calibration standards, the standard measurement softkey is replaced by the softkey, which opens the subclass menu containing the list of all the standards of this class.

Further this section describes an example of calibration using the calibration kit for TRL calibration, in which the "TRL LINE/MATCH" class contains 3 subclasses: load (Lowband), line 2 (TRL Line2), and line 3 (TRL Line3).



1 01:/84-6-6	Used in	STD Label	Applied to Range		
1-2 Line/Match	Calculations		Fmin	Fmax	
Subclass 1	•	Lowband	300 kHz	680.2745 MHz	
Subclass 2	•	Line2	3.600165 GHz	8 GHz	
Subclass 3	•	Line3	720.273 MHz	3.5601665 GHz	
Subclass 4					
Subclass 5					
Subclass 6					
Subclass 7					

(See figure 5.13), press **Info** softkey.

frequency range, in which its measurements are applied

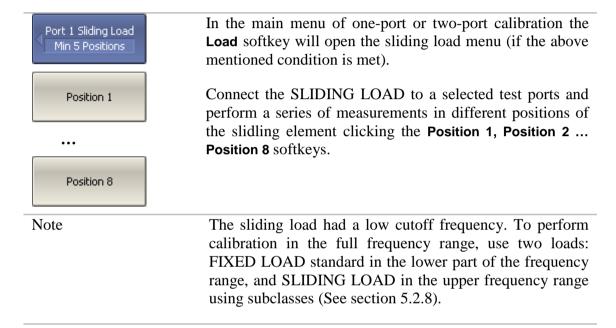
Figure 5.13 Information on calibration standard measurements.

5.2.9 Calibration Using Sliding Load

The SLIDING LOAD can be used instead of a FIXED LOAD in full one-port and two-port calibrations.

If a calibration kit contains a SLIDING LOAD, the standard measurement softkey is replaced by the softkey, which opens the submenu containing the SLIDING LOAD calibration logic.

The sliding load calibration involves a series of measurements in different positions of the sliding element. The minimum number of measurements is 5, the maximum number of measurements is 8.



5.2.10 Error Correction Disabling

This feature allows the user to disable the error correction function, which automatically becomes enabled after completion of calibration by any method.



To disable and enable again the error correction function, use the following softkeys:

Calibration > Correction

5.2.11 Error Correction Status

The error correction status is indicated for each trace individually. Also there is a general status of error correction for all the traces of a channel.

The general error correction status for all the S-parameter traces of a channel is indicted in the specific field on a channel status bar (See table 5.5). For channel status bar description, see section 4.2.6.

Table 5.5 General error correction status

Symbol	Definition	Note
Cor	Error correction is enabled. The stimulus settings are the same for the measurement and the calibration.	for all the traces – black characters on gray
C?	Error correction is enabled. The stimulus settings are not the same for the measurement and the calibration. Interpolation is applied.	background. If the function is active only for some of the traces (other traces are
C!	Error correction is enabled. The stimulus settings are not the same for the measurement and the calibration. Extrapolation is applied.	not calibrated) – white characters on red background.
Off	Error correction is turned off.	For all the traces. White
	No calibration data. No calibration was performed.	characters on red background.

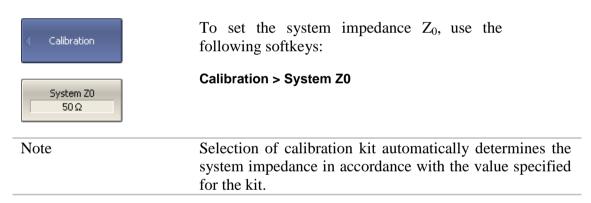
The error correction status for each individual trace is indicated in the trace status field (See table 5.6). For trace status field description, see section 4.2.2.

Table 5.6 Trace error correction status

Symbols	Definition		
RO	OPEN response calibration		
RS	SHORT response calibration		
RT	THRU response calibration		
ОР	One-path 2-port calibration		
F1	Full 1-port calibration		
F2	Full 2-port or TRL calibration		

5.2.12 System Impedance Z₀

 Z_0 is the system impedance of a measurement path. Normally it is equal to the impedance of the calibration standards, which are used for calibration. The Z_0 value should be specified before calibration, as it is used for calibration coefficient calculations.



5.2.13 Port Extension

The port extension function enables you to eliminate the fixture (with or without losses) effects on the measurement results. The function virtually extends the test ports moving the calibration plane to the terminals of the DUT (by the length of the fixture). The fixture parameters are defined by the user for each port individually (See figure 5.14).

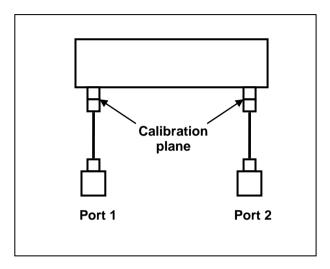


Figure 5.14 Port extension

The phase incursion caused by electrical delay is compensated for, when a lossless fixture needs to be removed:

$$e^{j\cdot 2\pi\cdot f\cdot t}$$
 , where

f – frequency, Hz,

t – electrical delay, sec.

The feature of removing a lossless fixture is similar to the feature of electrical delay setting for a trace (See section 4.9.7), but unlike the latter it applies to all the traces of the channel. It compensates for a fixture length in transmission measurements and for a double fixture length in reflection measurements.

To remove a fixture with losses, the following methods of loss defining (in one, two or three frequency points) are applied:

1. Frequency-independent loss at DC - L_0

$$L(f) = L_0$$

2. Frequency-dependent loss determined by the losses in two frequency points: L_0 at DC, and L_1 at frequency F_1

$$L(f) = L_0 + (L_1 - L_0) \sqrt{\frac{f}{F_1}}$$

3. Frequency-dependent loss determined by the losses in three frequency points: L_0 at DC, L_1 at frequency F_1 , and L_2 at frequency F_2

$$L(f) = L_0 + (L_1 - L_0) \left(\frac{f}{F_1}\right)^n$$

$$n = \frac{\log \left| \frac{L_1}{L_2} \right|}{\log \frac{F_1}{F_2}}$$

5.3 Calibration Kit Management

This section describes how to edit the calibration kit description, add and delete a calibration kit.

The Analyzer provides a table for 50 calibration kits. The first part of the table contains the predefined kits. The second part of the table is for calibration kit added by the user.

A calibration kit redefining can be required for the following purposes:

- To change the port assignment of a standard to ensure connector type (male, female) matching;
- To add a user-defined standard into the kit, e.g. a non zero-length thru;
- To precise the standard parameters to improve the calibration accuracy.

A new user-defined calibration kit adding can be added when a required kit is not included in the list of the predefined kits.

Deleting function is available for user-defined calibration kits only.

Any changes made to the calibration kits are automatically saved into the nonvolatile memory of the Analyzer. For the saving no clicking on a "Save" button is required.

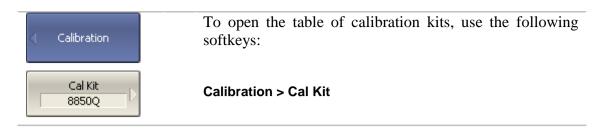
Note Changes to a predefined calibration kit can be cancelled any time and the initial state will be restored.

5.3.1 Table of Calibration Kits

The table of calibration kits (See figure 5.15) allows selecting and editing of the calibration kits.

	Label	Description	Select	Predefined	Modified	#STDs	
2	85032B/E	Type-N 50Ω 6GHz Cal Kit (Agilent)		Yes	No	6	
3	85032F	Type-N 50Ω 9GHz Cal Kit (Agilent)		Yes	No	8	
4	85054B	Type-N 50Ω 18GHz Cal Kit with Sliding Load(Agilent)		Yes	No	8	
5	85054D	Type-N 50Ω 18GHz Cal Kit (Agilent)		Yes	No	6	
6	05CK10A-150	Type-N 50Ω 18GHz Cal Kit (Rosenberger)		Yes	No	6	
7	8850Q	Type-N 50Ω 18GHz Cal Kit (Maury Microwave)	✓	Yes	No	6	
8	8850C	Type-N 50Ω 18GHz Cal Kit with Sliding Load (Maury Mici		Yes	No	8	
9	85033D/E	3.5 mm 6GHz/9GHz Cal Kit (Agilent)		Yes	No	6	
10	85052B	3.5 mm 26.5GHz Cal Kit with Sliding Load (Agilent)		Yes	No	10	ϗ

Figure 5.15 Table of calibration kits



To edit a calibration kit, highlight its line in the table.

The calibration kit editing is comprised of two main procedures: defining of calibration standard (sections 5.3.2 and 5.3.3) and assignment of classes to calibration standards (section 5.3.4). First you need to perform defining of the calibration standards, and then the assignment of classes to them. Defining of calibration standards and assignment of classes to them is performed in different tables.

The label of a calibration kit and its description can be edited in the table of the calibration kits (figure 5.15). The label appears on the calibration menu softkeys. The description is just for information of the user.

The table also contains display-only fields: flags of predefined and modified calibration kits and the counter of the calibration standards in a kit.

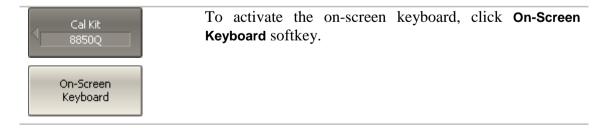
5.3.1.1 Calibration Kit Selection for Editing

Move the highlighting to the required line in the calibration kit (See figure 5.15) table using "↑" and "↓" arrows.

Note	The checkmark in the "Select" field does not matter for
	the kit selection for editing, it selects the calibration kit for calibration.

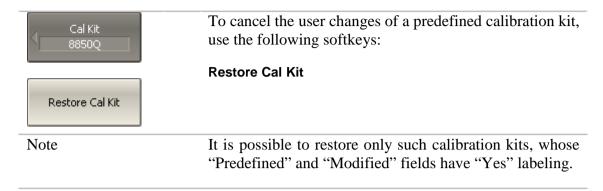
5.3.1.2 Calibration Kit Label and Description Editing

Move the highlighting to the required line in the calibration kit (See figure 5.15) table using " \uparrow " and " \downarrow " arrows and click on the **«Enter»** softkey. Then enter the new text in the table.



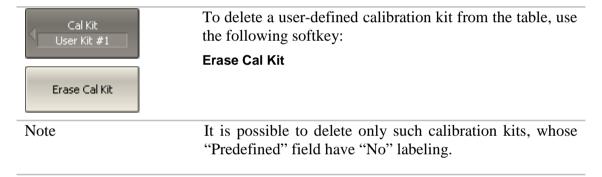
5.3.1.3 Predefined Calibration Kit Restoration

Move the highlighting to the required line in the calibration kit (See figure 5.15).



5.3.1.4 User-Defined Calibration Kit Deleting

Move the highlighting to the required line in the calibration kit (See figure 5.15).

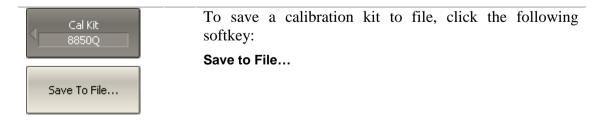


5.3.1.5 Calibration Kit Saving to File

Saving of a calibration kit to file is necessary for copying it to a different line of the table or to a different Analyzer.

This command is not necessary for saving of changes made by the user to the definitions of the kit as these changes are saved automatically.

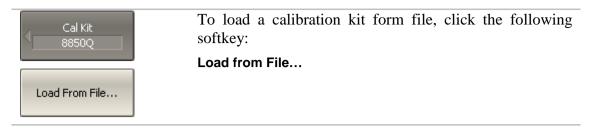
Move the highlighting to the required line in the calibration kit (See figure 5.15).



5.3.1.6 Calibration Kit Loading from File

You can load the calibration kit files created by the previous command.

Move the highlighting to the required line in the calibration kit (See figure 5.15).



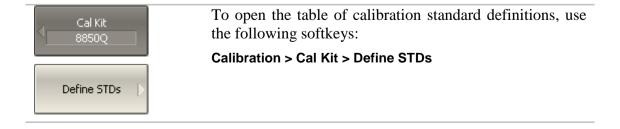
5.3.2 Calibration Standard Definition

The table of the calibration standards (See figure 5.16) includes the full list of the standards in one calibration kit. For the standards defined by the model, the table contains the model parameters. For the data-based standards, the parameters of the model remain blank; S-parameters of such standards are represented in a different table (See section 5.3.3).

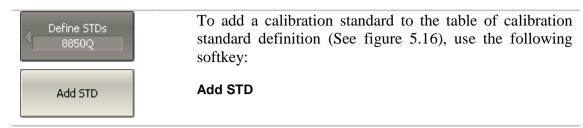
	Standard			Frequency		Offset			
	No	Туре	Label	Min	Max	Delay	Z0	Loss	
\triangleright	1	Open	Open -M-	0 Hz	999 GHz	37.026 ps	50Ω	700 MΩ/s	
	2	Open	Open -F-	0 Hz	999 GHz	19.42 ps	50 Ω	700 MΩ/s	
	3	Short	Short -M-	0 Hz	999 GHz	42.063 ps	50 Ω	700 MΩ/s	
	4	Short	Short -F-	0 Hz	999 GHz	24.512 ps	50 Ω	700 MΩ/s	
	5	Load	Broadband	0 Hz	999 GHz	0s	50 Ω	0Ω/s	
	6	Thru/Delay	Thru	0 Hz	999 GHz	0 s	50 Ω	700 MΩ/s	
1	▼								

Terminal	C0·10 ⁻¹⁵ F	C1 · 10 ⁻²⁷ F/Hz	C2-10 ⁻³⁶ F/Hz ²	C3·10 ⁻⁴⁵ F/Hz ³ L3·10 ⁻⁴² H/Hz ³	
Impedance	L0-10 ⁻¹² H	L1 ·10 ⁻²⁴ H/Hz	L2-10 ⁻³³ H/Hz ²		
	99.14	353.6	62,23	0	
	103	0	110	10.2	
	0	0	0	0	
	0	0	0	0	
50 Ω					
				P	

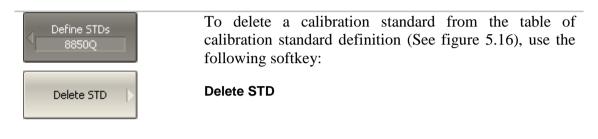
Figure 5.16 Calibration standard definition table



5.3.2.1 Standard Adding to Calibration Kit



5.3.2.2 Standard Deleting from Calibration Kit



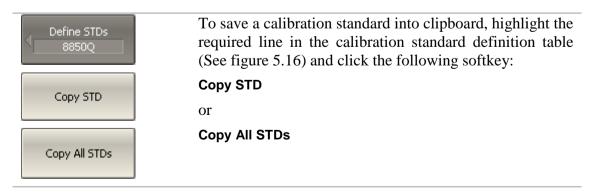
5.3.2.3 Calibration Standard Editing

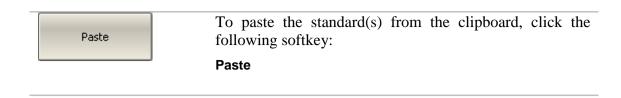
Moving in the table of calibration standard definitions (See figure 5.16) using navigation keys, enter the parameter values for a calibration kit:

Standard No.	The calibration standard number is specified in the calibration kit data sheet (just for information).	
Standard Type	Select the standard type:	
	■ Open,	
	■ Short,	
	■ Load,	
	 Thru/Line, 	
	 Unknown Thru, 	
	 Sliding Load, 	
	 Data-Based 	
Standard Label	Standard labels specified on the calibration menu softkeys.	
Freq. Min.	Lower cutoff frequency of the standard.	
Freq. Max.	Upper cutoff frequency of the standard.	
Offset Delay	Offset delay value in one direction (s).	

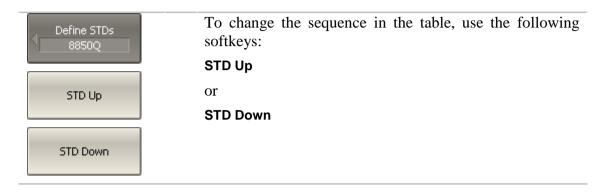
Offset Z0	Offset wave impedance value (Ω).
Offset Loss	Offset loss value (Ω /s).
Load Impedance	Lumped load impedance value (Ω).
C0 10 ⁻¹⁵ F	For an OPEN standard, C_0 coefficient in the polynomial formula of the fringe capacitance:
	$C = C_0 + C_1 f + C_2 f^2 + C_3 f^3$
C1 10 ⁻²⁷ F/Hz	For an OPEN standard, C_1 coefficient in the polynomial formula of the fringe capacitance.
C2 10 ⁻³⁶ F/Hz ²	For an OPEN standard, C_2 coefficient in the polynomial formula of the fringe capacitance.
C2 10 ⁻⁴⁵ F/Hz ³	For an OPEN standard, C ₃ coefficient in the polynomial formula of the fringe capacitance.
L0 10 ⁻¹² H	For a SHORT standard, L_0 coefficient in the polynomial formula of the residual inductance:
	$L = L_0 + L_1 f + L_2 f^2 + L_3 f^3$
L1 10 ⁻²⁴ H/Hz	For a SHORT standard, L_1 coefficient in the polynomial formula of the residual inductance.
L2 10 ⁻³³ H/Hz ²	For a SHORT standard, L_2 coefficient in the polynomial formula of the residual inductance.
L2 10 ⁻⁴² H/Hz ³	For a SHORT standard, L_3 coefficient in the polynomial formula of the residual inductance.

5.3.2.4 Calibration Standard Copy/Paste Function





5.3.2.5 Management of Sequence in Standard Table

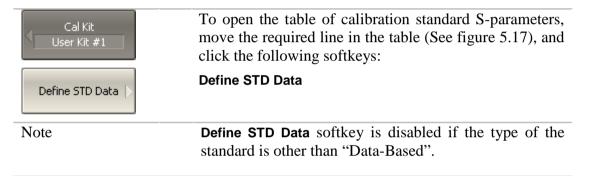


5.3.3 Table of Calibration Standard S-Parameters

The table of calibration standard S-parameters (See figure 5.17) allows viewing and editing of S-parameters of the calibration standards of the "Data-Based" type.

	Frequency	MLog(S11)	Arg(S11)	MLog(S21)	Arg(S21)	
1	300 kHz	-67.5270094 dB	53.4023888°	0.00394846762 dB	0.291495528°	
2	8.2997 MHz	-81.9584188 dB	-119.014476°	0.00351271886 dB	0.322307311°	
3	16.2994 MHz	-78.8287269 dB	-128.601485°	0.00322754052 dB	0.320729452°	
4	24.2991 MHz	-76.6945937 dB	-126.226624°	0.00335760667 dB	0.321443452°	
5	32.2988 MHz	-75.3564463 dB	-123.320088°	0.00336896915 dB	0.322652352°	
6	40.2985 MHz	-73.9037876 dB	-118.924822°	0.00352190889 dB	0.325734959°	
7	48.2982 MHz	-72.3276906 dB	-114.247608°	0.00416283402 dB	0.327349639°	
8	56.2979 MHz	-70.8755884 dB	-109.418739°	0.00457673931 dB	0.322968328°	
9	64.2976 MHz	-69.1166427 dB	-105.957991°	0.00452183965 dB	0.316878686°	-
1						•

Figure 5.17 Table of calibration standard S-parameters



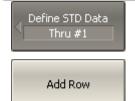
There are two different tables for one-port standards and for two-port standards. The table contains one parameter (S_{11}) for one-port standards, and four parameters (S_{11} , S_{21} , S_{12} , S_{22}) for two-port standards. Before the user fills in the table, its type will be defined: by the Touchstone format (s1p or s2p) if the data is downloaded from a file, or the user will be requested to specify the type if the data is entered by the user.

The data in the table can be represented in three formats according to the user settings:

- Real part and Imaginary part,
- Linear magnitude and Phase (°),
- Logarithmic magnitude (dB) and Phase (°).

The following rule is applied for the calibration of a two-port standard: the standard is considered connected by port 1 (S_{11}) to the port with smallest number, and by port 2 (S_{22}) to the port with the biggest number. If you need to "reverse" a two-port standard, use the "Port Reverse" function (section 5.3.3.5).

5.3.3.1 Line Adding to Table



To add a line to the table of the calibration standard S-parameters (See figure 5.17), use the following softkeys:

Add Row

5.3.3.2 Line Deleting from Table



To delete a line from the table of the calibration standard S-parameters (See figure 5.17), use the following softkey:

Delete Line

5.3.3.3 Table Clearing



To clear the entire table of the calibration standard S-parameters (See figure 5.17), use the following softkey:

Clear Data

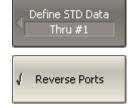
5.3.3.4 Table Format Selecting



To select the format of the table of the calibration standard S-parameters (See figure 5.17), use the following softkey:

Format > Real/Imag | Magn/Angle | MLog/Angle

5.3.3.5 Port Reversing



To enable/disable reversing of the ports of a two-port standard, use the following softkey:

Reverse Ports

5.3.3.6 Data Opening from File



To open the data from Touchstone file, use the following softkey:

Load Data from Touchstone file...

In the pop-up dialog select the file type (s1p or s2p) and specify the file name.

5.3.4 Calibration Standard Class Assignment

The assignment of classes to the standards of the selected calibration kit is made in the table of standard classes (See figure 5.18).

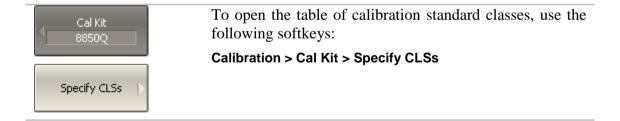
Standard labels filled in the table cells by selecting them from the list of calibration kit standards.

Each row of the table corresponds to the standard class specified in the two left columns of the table.

If a single standard is assigned to the class then it filled into the "Subclass 1" column. If several standards are assigned to the class, as described in section 5.2.8, then "Subclass 2", "Subclass 3", etc columns are filled in.

Class	Port	Subclass 1	Subclass 2	Subclass 3	S
^	1	4. Open -M-			
Open	2	4. Open -M-			
Short	1	5. Short -M-			
SHORE	2	5. Short -M-			
Load	1	1. Lowdband	2. Sliding Load	3. Broadband	
Loau	2	1. Lowdband	2. Sliding Load	3. Broadband	
Thru	1-2	11. Thru			
TRL Thru	1-2				
TRL Reflect	1				
TRE Reflect	2				
TRL Line/Match	1-2				
1					•

Figure 5.18 Table of calibration standard classes



5.3.4.1 Standard Class Table Editing

Moving in the table of calibration standard classes (See figure 5.18) using navigation keys, click **«Enter»** in the required cell for the pop-up menu. Select the standard label in the pop-up menu to assign it the class and port number specified in the left part of the table.

5.3.4.2 Standard Deleting from Standard Class Table

Moving in the table of calibration standard classes (See figure 5.18) using navigation keys, click **«Enter»** in the required cell for the pop-up menu. Select the line **None** in the pop-up menu to delete the standard contained in the cell.



To delete all the standards in the table of calibration standard classes, use the following softkey:

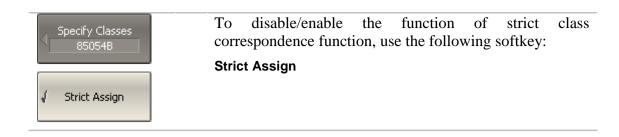
Clear All CLSs

5.3.4.3 Strict Class Assignment Function

This function allows for limitation of the one standard type(s) available in each class by the feature of strict correspondence (See table 5.7). If this function is disabled, any class can be assigned to the standard.

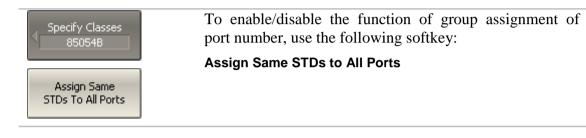
Table 5.7 Standard class and standard type correspondence

N	Standard Class	Standard Type
1	OPEN	Open,Data-Based (One Port)
2	SHORT	Short,Data-Based (One Port)
3	LOAD	Load,Sliding Load,Data-Based (One Port)
4	THRU	Thru/Line,Data-Based (Two Port)
5	TRL THRU	Thru/Line,Data-Based (Two Port)
6	TRL REFLECT	Open,Short,Data-Based (One Port)
7	TRL LINE/MATCH	Load,Thru/Line



5.3.4.4 Function of Group Assignment of Port Number

This function allows for automatic assignment of one standard to all the ports of a specific class when assigned to at least one port.



5.4 Power Calibration

The Analyzer ensures steady power level at the test port inputs with the specified accuracy. The power level is defined by the user from -50 dBm to +5 dBm.

A DUT is connected to the Analyzer by cables, which have some losses. The power calibration allows the user to maintain a more accurate power level at a DUT input, adjusted to the use of the cables.

The power calibration is performed by an external power meter connected to the cables' ends, which will be later connected to the DUT.

After the power calibration is complete, power correction automatically turns on. Later the user can disable or enable again the power correction function.

The power calibration is performed for each port and each channel individually.

Note	The power correction status is indicated in the trace status field (See section 4.2.2) and in the channel status bar (See section 4.2.6).

5.4.1 Loss Compensation Table

The loss compensation function allows the user to apply compensation for unwanted losses produced between the power meter and the calibrated port in the process of power calibration. Define the losses, which you need to compensate in the table (See figure 5.19) specifying frequency and losses.

	Frequency	Loss
1	300 kHz	0.1 dB
2	1 GHz	0.2 dB
3	2 GHz	0.4 dB
4	3 GHz	0.5 dB
5		

Figure 5.19 Loss compensation table

Linear interpolation will be applied to the losses in the intermediary frequency points.

The loss compensation table is defined for each port individually.

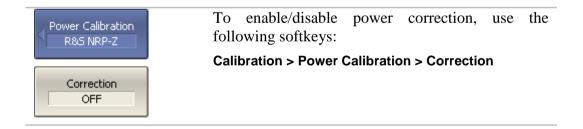
Note	To have the losses compensated for, you need to enable this function and fill out the table before you start the
	power calibration procedure.

5.4.2 Power Calibration Procedure

Perform connection and setting of an external power meter as described in section 8.10. Connect the sensor to one of the test ports of the Analyzer and perform calibration as described below. Then repeat the calibration for the other test port.

Power Calibration R&S NRP-Z Select Port 1	To select the calibrated port number, use the following softkeys: Calibration > Power Calibration > Select Port
Power Sensor Zero Correction	To zero power meter, use the following softkeys: Calibration > Power Calibration > Power Sensor Zero Correction
Note	Power meter sensor can be connected to the port, as during zero setting the output signal of the port is turned off.
Take Cal Sweep	To execute power calibration, use the following softkeys: Calibration > Power Calibration > Take Cal Sweep
Note	After the power calibration is complete, power correction automatically turns on.

5.4.3 Power Correction Setting



5.4.4 Loss Compensation Table Editing

If you need to apply the loss compensation, enable this function and fill out the table before you start the power calibration procedure. Fill out the table for each port individually.

Loss Compen Port 1	To add a new row to the loss compensation table, use the following softkeys:
	Calibration > Power Calibration > Loss Compen > Add
Add	A new row will appear under the highlighted one.
	To delete a highlighted row, use the following softkeys:
Delete	Calibration > Power Calibration > Loss Compen > Delete
51-1-1-1-N	To clear all the table, use the following softkeys:
Clear Loss Table	Calibration > Power Calibration > Loss Compen > Clear Loss Table
	To save the table into a *.lct file on the hard, use the
Export Loss Table	following softkeys:
	Calibration > Power Calibration > Loss Compen > Export Loss Table
Import Loss Table	To open the table from a *.lct file from the hard, use the following softkeys:
	Calibration > Power Calibration > Loss Compen > Import Loss Table
	Enter frequency and loss values into the table, scrolling by navigation keys.
Compensation	To enable the loss compensation function, use the following softkeys:
	Calibration > Power Calibration > Loss Compen > Compensation

5.5 Receiver Calibration

When you perform absolute power measurements (See section 4.7.3), the gain of some receivers are factory calibrated to test port inputs.

In practice, the power is measured at test port inputs made by the fixture producing losses. The receiver calibration enables the user to measure the power at port inputs with higher accuracy.

The receiver calibration is performed by sending the calibration signal from the source port to the calibrated port input. The receiver calibration requires the connection between the both test ports using THRU line.

To make the receiver calibration most accurate, first perform power calibration on the source port. If the source power calibration was not performed, to get good results you need to connect the calibrated port to the source port on the front panel.

After the receiver calibration is complete, receiver correction automatically turns on. Later the user can disable or enable again the receiver correction function.

The receiver calibration can be performed only for the test signal receivers (A and B) of each port (See figure 4.11).

The power calibration is performed for each port and each channel individually.

Note	The power correction status is indicated in the trace status field (See section 4.2.2) and in the channel status bar (See section 4.2.6).

5.5.1 Receiver Calibration Procedure

Connect a THRU line between the receiver port and the source port.

Receiver Calibration	To select the calibrated port number, use the following softkeys:	
Select Port	Calibration > Receiver Calibration > Select Port	
Source Port	To select the source port number, use the following softkeys:	
	Calibration > Receiver Calibration > Source Port	
Take Cal Sweep	To execute receiver calibration, use the following softkeys:	
	Calibration > Receiver Calibration > Take Cal Sweep	

After the receiver calibration is complete, receiver correction automatically turns on.

5.5.2 Receiver Correction Setting



To enable/disable receiver correction, use the following softkeys:

Calibration > Receiver Calibration > Correction

5.6 Scalar Mixer Calibration

Scalar mixer calibration is the most accurate method of calibration applied to measurements of mixers in frequency offset mode.

The scalar mixer calibration requires OPEN, SHORT, and LOAD standards as well as external power meter (See figure 5.20). The power meter connection and setup is described in section 8.8.

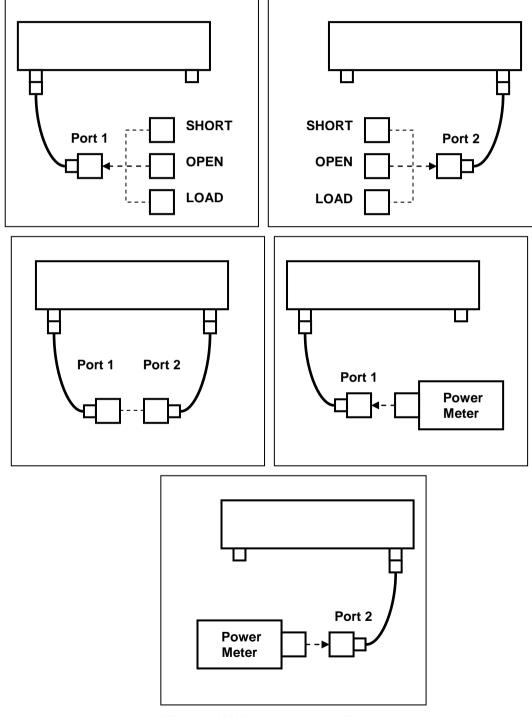


Figure 5.20 Scalar mixer calibration setup

The scalar mixer calibration allows the following measurements:

- reflection S_{11} and S_{22} parameters in vector form;
- transmission S_{21} and S_{12} parameters in scalar form.

Before you start the calibration, perform the following settings: select active channel and set its parameters (frequency span, IF bandwidth, etc), and define the calibration kit. Then enable the frequency offset mode and perform the port settings.

Note

The scalar mixer calibration can be performed without frequency offset. You can enable the frequency offset mode later, during mixer measurements. In this case the basic frequency range should cover the frequency spans of the ports in offset mode. This procedure is convenient but less accurate as involves interpolation.



To access the scalar mixer calibration menu, use the following softkeys:

Calibration > Mixer/Converter Calibration > Scalar Mixer Calibration



Click Reflection Port 1 softkey.

Port 1 @Freq 1 Open Open -M- Connect SHORT, OPEN and LOAD standards to port 1 as shown in figure 5.20. Perform two measurements over two frequency ranges (**Freq 1** and **Freq 2**) for each standard using the respective standard softkeys.

Port 1 @Freq 2 Open Open -M-

If the frequency offset is disabled, after measurement over one frequency range the result will be automatically saved for the both frequency ranges.

Port 1 @Freq 1 Short Short -M-

The instrument status bar will indicate **Calibration in progress...** when the measurement is in progress. On completion of the measurement, a check mark will appear in the left part of the softkey.

Port 1 @Freq 2 Short Short -M-

Port 1 @Freq 1 Load Broadband

Port 1 @Freq 2 Load Broadband



Port 2 @Freq 1 Open Open -M-

Port 2 @Freq 2 Open Open -M-

Port 2 @Freq 1 Short Short -M-

Port 2 @Freq 2 Short Short -M-

Port 2 @Freq 1 Load Broadband

Port 2 @Freq 2 Load Broadband

Click Reflection Port 2 softkey.

Connect SHORT, OPEN and LOAD standards to port 2 as shown in figure 5.20. Perform two measurements over two frequency ranges (**Freq 1** and **Freq 2**) for each standard using the respective standard softkeys.

If the frequency offset is disabled, after measurement over one frequency range the result will be automatically saved for the both frequency ranges.

The instrument status bar will indicate **Calibration in progress...** when the measurement is in progress. On completion of the measurement, a check mark will appear in the left part of the softkey.



Port 1-2 @Freq 1 Thru Thru

Port 1-2 @Freq 2 Thru Thru

Click **Transmission** softkey.

Connect a THRU standards between the test ports. If the port connectors allow, connect the ports directly together (through line with zero electrical length). Perform two measurements over two frequency ranges (Freq 1 and Freq 2).

If the frequency offset is disabled, after measurement over one frequency range the result will be automatically saved for the both frequency ranges.

The instrument status bar will indicate **Calibration in progress...** when the measurement is in progress. On completion of the measurement, a check mark will appear in the left part of the softkey.



T.

Power Sensor Zero Correction

Click Power softkey.

To zero power meter, click **Power Sensor Zero Correction** softkey.

Note

Power meter sensor can be connected to the port, as during zero setting the output signal of the port is turned off.

Port 1 @Freq 1	Connect the power meter to port 1. Perform two measurements over two frequency ranges (Freq 1 and Freq 2).
Port 1 @Freq 2	If the frequency offset is disabled, after measurement over one frequency range the result will be automatically saved for the both frequency ranges.
Port 2 @Freq 1	Connect the power meter to port 2. Perform two measurements over two frequency ranges (Freq 1 and Freq 2).
Port 2 @Freq 2	The instrument status bar will indicate Calibration in progress when the measurement is in progress. On completion of the measurement, a check mark will appear in the left part of the softkey.
0h-	To complete the calibration procedure, click Apply .
Apply	To complete the calibration procedure, click Apply . This will activate the process of calibration coefficient table calculation and saving it into the memory. The error correction function will also be automatically enabled.
Apply Cancel	This will activate the process of calibration coefficient table calculation and saving it into the memory. The error
	This will activate the process of calibration coefficient table calculation and saving it into the memory. The error correction function will also be automatically enabled. To clear the measurement results of the standards, click

5.7 Vector Mixer Calibration

Vector scalar calibration is a calibration method applied for mixer measurements. This method allows measurement of both reflection and transmission S-parameters in vector form, including phase and group delay of transmission coefficient.

The vector mixer measurements require an additional mixer with filter, which is called calibration mixer.

The filter separates the IF, which is the input frequency for the mixer under test:

- RF + LO
- RF LO
- LO RF

Both calibration mixer and mixer under test are powered from one LO.

The vector mixer measurement is a combination of a 2-port calibration and a deembedding function (See figure 5.21).

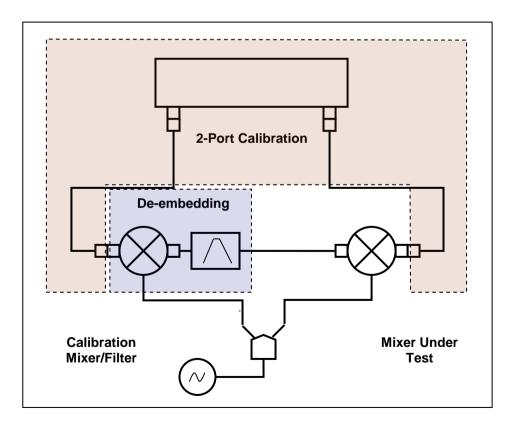


Figure 5.21 Vector mixer measurements

The de-embedding function requires an S-parameter file of the circuit. Acquisition of such a file for the calibration mixer/filter pair is called vector mixer calibration.

To obtain an S-parameter file of the calibration mixer/filter, you need to use SHORT, OPEN, and LOAD calibration standards (See figure 5.22).

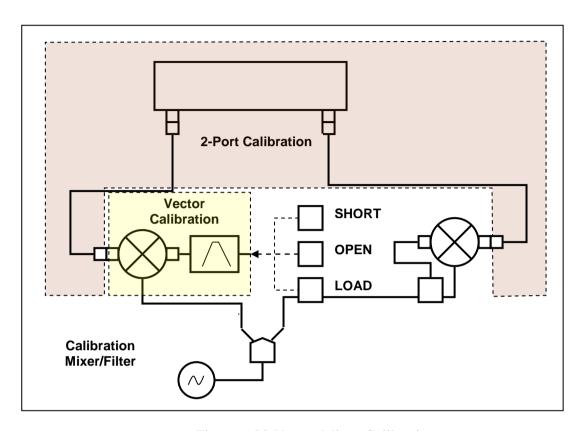
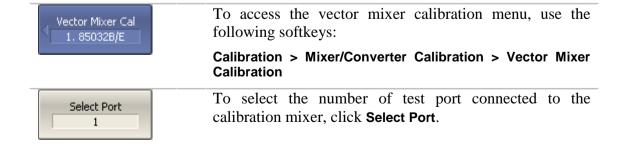


Figure 5.22 Vector Mixer Calibration

5.7.1 Vector Mixer Calibration Procedure

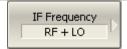
Before you start the calibration, perform the following settings: activate a channel and set its parameters (frequency span, IF bandwidth, etc), and define the calibration kit.

- Perform 2-port calibration.
- Assemble vector calibration setup.
- Set frequency and power of the external LO.



LO Frequency	
0 Hz	

Enter the LO frequency, using **LO Frequency** softkey.



Select the frequency to be separated by the filter, using **IF Frequency** softkey:

- RF + LO
- RF-LO
- LO RF



Connect SHORT, OPEN and LOAD standards to IF filter output as shown in figure 5.22. Perform the measurement using the respective standard softkey.



The instrument status bar will indicate **Calibration in progress...** when the measurement is in progress. On completion of the measurement, a check mark will appear in the left part of the softkey.



Setup Option

To complete the calibration procedure, click **Save To Touchstone File**.



This will activate calculation of the calibration mixer/filter pair S-parameters, and saving those into a Touchstone file. Enter the file name in the pop-up dialog.

If **Setup Option** feature is enabled, S-parameter file will be passed to the de-embedding function and this function will be activated.

Note

You can check the calibration status in channel status bar (See table 5.5) – **F2** μ **Dmb** labels (2-port calibration and de-embedding function).

5.8 Automatic Calibration Module

Automatic calibration module (ACM) is a special device, which allows for automating of the process of calibration. ACM is shown in figure 5.23.



Figure 5.23 Automatic Calibration Module

ACM offers the following advantages over the traditional SOLT calibration, which uses a mechanical calibration kit:

- Reduces the number of connections of standards. Instead of connecting seven standards, it requires connecting only two ACM connectors;
- Reduces the calibration time;
- Reduces human error probability;
- Provides higher accuracy potentially.

ACM has two RF connectors for connection to the Analyzer test ports and a USB connector for control. ACM contains electronic switches, which switch between different reflection and transmission impedance states, as well as memory, which stores precise S-parameters of these impedance states.

After you connect the ACM to the Analyzer, the Analyzer software performs the calibration procedure automatically, i.e. switches between different ACM states, measures them, and computes calibration coefficients using the data stored in the ACM memory.

5.8.1 Automatic Calibration Module Features

Calibration Types:

ACM allows the Analyzer software to perform full two-port or full one-port calibrations with the click of a button. We recommend that you terminate the unusable ACM port with a load while performing one-port calibration.

Characterization:

Characterization is a table of S-parameters of all the states of the ACM switches, stored in the ACM memory. There are two types of characterization: user characterization and factory characterization. ACM has two memory sections. The first one is write-protected and contains factory characterization. The second memory section allows you to store up to three user characterizations. Before calibration you can select the factory characterization or any of the user characterizations stored in the ACM memory. The user characterization option is provided for saving new S-parameters of the ACM after connecting adapters to the ACM ports.

The software enables you to perform a user characterization and save the data to ACM with the click of a button. To be able to do this, you should first calibrate the Analyzer test ports in configuration compatible with the ACM ports.

Automatic Orientation:

Orientation means relating the ACM ports to the test ports of the Analyzer. While the Analyzer test ports are indicated by numbers, the ACM ports are indicated by letters A and B.

Orientation is defined either manually by the user, or automatically. The user is to select the manual or automatic orientation method. In case of automatic orientation, the Analyzer software determines the ACM orientation each time prior to its calibration or characterization.

Unknown Thru:

The Thru implemented by the electronic switches inside the ACM introduces losses. That is why you should know the exact parameters of the Thru or use an Unknown Thru algorithm to achieve the specified calibration accuracy.

The software allows using the both options. ACM memory stores S-parameters of the Thru, which are used to compute calibration coefficients. In case if an Unknown Thru algorithm is applied, such parameters are disregarded.

Thermal Compensation:

The most accurate calibration can be achieved if the ACM temperature is equal to the temperature, at which it was characterized. When this temperature changes, certain ACM state parameters may deviate from the parameters stored in the memory. This results in reduction of the ACM calibration accuracy.

To compensate for the thermal error, the ACM features thermal compensation function. Thermal compensation is a software function of the ACM S-parameter correction based on its temperature dependence and the data from the temperature sensor inside the ACM. The temperature dependence of each ACM is determined at the factory and saved into its memory.

The function of thermal compensation can be enabled or disabled by the user.

Confidence Check:

ACM also implements an additional state – an attenuator, which is not used in calibration. The attenuator is used to check the current calibration performed by ACM or any other method. Such test is called a confidence check.

The confidence check consists in simultaneous display of the measured and stored in memory S-parameters of the attenuator. The measured parameters are shown as the data trace and the parameters saved in the ACM memory are shown as the memory trace. You can compare the two traces, evaluate their differences and determine the accuracy of the calibration performed.

For a detailed comparison you can use the math (division) function for data and memory.

5.8.2 Automatic Calibration Procedure

Before calibrating the Analyzer with ACM, perform some settings, i.e. activate a channel and set channel parameters (frequency range, IF bandwidth, etc).

Connect the ACM to the Analyzer test ports, and connect the USB port of the ACM to the USB port of the computer.

AutoCal Module SC6000	To start automatic calibration, use the following softkeys: Calibration > AutoCal
Characterization Factory	Select characterization using Characterization softkey.
Orientation AUTO	Select manual or automatic orientation of the ACM using Orientation softkey. It is recommended to select AUTO orientation.
Unkn Thru OFF	Enable or disable Unknown Thru algorithm using Unkn. Thru softkey.
Thermo compensation ON	Enable or disable the thermal compensation using Thermal Compensation softkey.

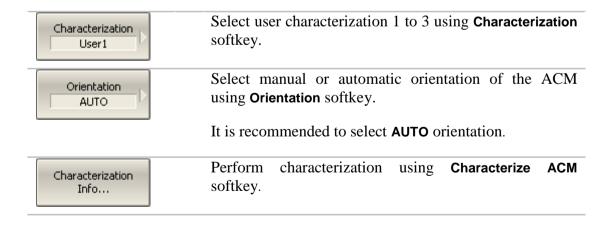
Characterization Info	To display detailed information on characterization, use Characterization Info softkey.
2-Port AutoCal	To perform full two-port calibration, use 2-Port AutoCal softkey.
1-Port AutoCal	To perform full one-port calibration, use 1-Port AutoCal softkey.
Port 1	Then select the port number.
Port 2	

5.8.3 User Characterization Procedure

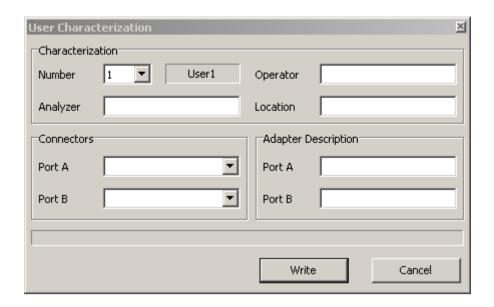
User characterization of ACM is required in case of ACM connectors modification by the use of adapters. The characterization is performed for the new ACM configuration, which includes adapters. To ensure calibration accuracy it is not recommended to disconnect and reconnect the adapters back.

Before you perform the user characterization of the ACM, perform full two-port calibration of the Analyzer in configuration of the test ports compatible with the configuration of ACM ports.

Connect the ACM to the Analyzer test ports, and connect the USB port of the ACM to the USB port of the computer.



After the ACM measurement is completed, the following dialog box will appear:



Fill in the following fields:

- User name;
- Analyzer name;
- Characterization location;
- Connectors (types of adapter connectors);
- Adapter description (description of adapters).

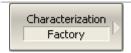
Use **Save** softkey to complete the user characterization of the ACM.

5.8.4 Confidence Check Procedure

In case you need to verify the reliability of the current calibration, perform the confidence check. This function can be used to check the accuracy of either calibration performed with an ACM or with a mechanical calibration kit.

Connect the ACM to the Analyzer test ports, and connect the USB port of the ACM to the USB port of the computer.

Enable the display of the data trace for the needed parameter, for example S21. It is possible to enable several data traces simultaneously, for example, S11, S22, S21, S12.



Select characterization using **Characterization** softkey.

Orientation AUTO	Select manual or automatic orientation of the ACM using Orientation softkey.
	It is recommended to select AUTO orientation.
Confidence Check	Perform confidence check using Confidence Check softkey.

After the measurement is completed, two traces for each S-parameter will be displayed. The measured parameters will be shown as the data trace, and the ACM parameters will be shown as the memory trace.

Compare the data trace and the memory trace of the same parameter, for example S21. To perform more accurate comparison, enable the function of math operations between data and memory traces. In the logarithmic magnitude or phase format use the Data / Memory operation. In the linear magnitude format use the Data – Memory operation.

The conclusion on whether the current calibration provides sufficient accuracy or not is made by the user.

6 MEASUREMENT DATA ANALYSIS

6.1 Markers

A marker is a tool for numerical readout of a stimulus value and value of the measured parameter in a specific point on the trace. You can activate up to 16 markers on each trace. See a trace with two markers in figure 6.1.

The markers allow the user to perform the following tasks:

- Reading absolute values of a stimulus and a measured parameter in selected points on the trace;
- Reading relative values of a stimulus and a measured parameter related to the reference point;
- Search for specific points on the trace (minimum, maximum, target level, etc);
- Determining trace parameters (statistics, bandwidth, etc);
- Editing stimulus parameters using markers.

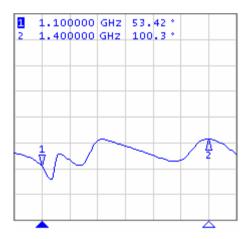


Figure 6.1

Markers can have the following indicators:

1 ∇	symbol and number of the active marker on a trace,
Δ 2	symbol and number of the inactive marker on a trace,
	symbol of the active marker on a stimulus axis,
Δ	symbol of the inactive marker on a stimulus axis.

The marker data field contains the marker number, stimulus value, and the measured parameter value. The number of the active marker is highlighted in inverse color.

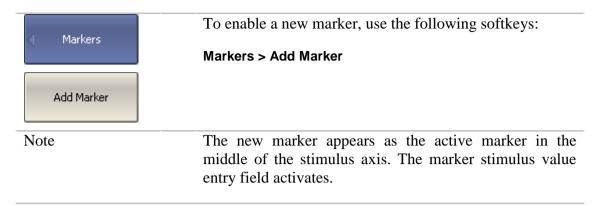
The marker data field contents vary depending on the display format (rectangular or circular).

- In rectangular format, the marker shows the measurement parameter value plotted along Y-axis in the active format (See table 4.8).
- In circular format, the marker shows two or three values listed in table
 6.1

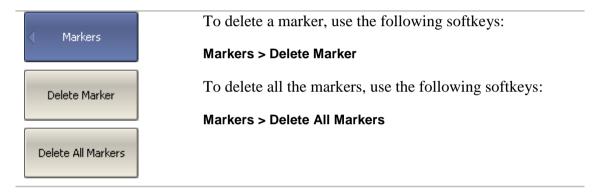
Table 6.1 Marker readings in circular formats

Label	Marker Readings (Measurement Unit)		
	Reading 1	Reading 2	Reading 3
Smith (Lin)	Linear magnitude	Phase (°)	-
Smith (Log)	Logarithmic magnitude (dB)	Phase (°)	-
Smith (Re/lm)	Real part	Imaginary part	-
Smith (R + jX)	Resistance (Ω)	Reactance (Ω)	Equivalent capacitance or inductance (F/H)
Smith (G + jB)	Conductance (S)	Susceptance (S)	Equivalent capacitance or inductance (F/H)
Polar (Lin)	Linear magnitude	Phase (°)	_
Polar (Log)	Logarithmic magnitude (dB)	Phase (°)	_
Polar (Re/lm)	Real part	Imaginary part	_

6.1.1 Marker Adding

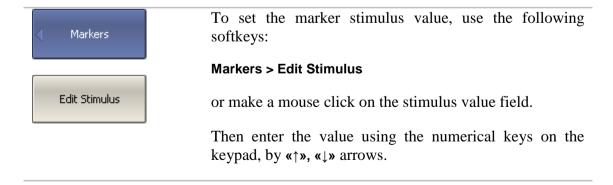


6.1.2 Marker Deleting

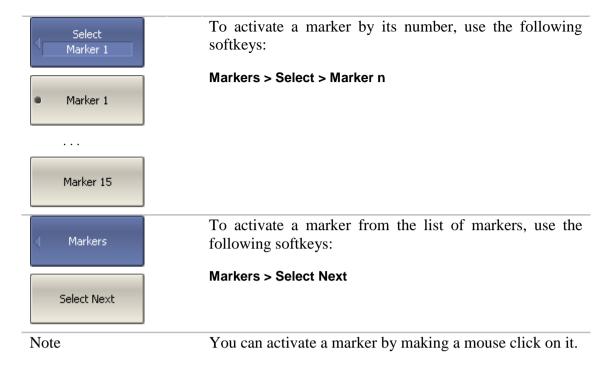


6.1.3 Marker Stimulus Value Setting

Before you set the marker stimulus value, you need to select the active marker. You can set the stimulus value by entering the numerical value from the keyboard, by arrows, or by dragging the marker using the mouse, or enabling the search function. Drag-and-drop operation is described in section 4.3.12. Marker search function is described in section 6.1.7.



6.1.4 Marker Activating



6.1.5 Reference Marker Feature

Reference marker feature allows the user to view the data relative to the reference marker. Other marker readings are represented as delta relative to the reference marker. The reference marker shows the absolute data. The reference marker is indicated with Δ symbol instead of a number (See figure 6.2). Enabling of a reference marker turns all the other markers to relative display mode.

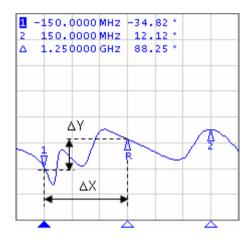


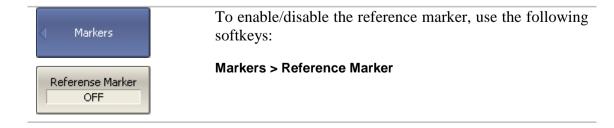
Figure 6.2

Reference marker can be indicated on the trace as follows:

R V	symbol of the active reference marker on a trace;
Δ R	symbol of the inactive reference marker on a trace.

The reference marker displays the stimulus and measurement absolute values. All the rest of the markers display the relative values:

- stimulus value difference between the absolute stimulus values of this marker and the reference marker;
- measured value difference between the absolute measurement values of this marker and the reference marker.



6.1.6 Marker Properties

6.1.6.1 Marker Coupling Feature

The marker coupling feature enables/disables dependence of the markers of the same numbers on different traces. If the feature is turned on, the coupled markers (markers with same numbers) will move along X-axis synchronously on all the traces. If the coupling feature is off, the position of the markers with same numbers along X-axis will be independent (See figure 6.3).

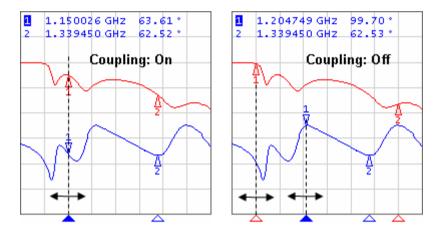
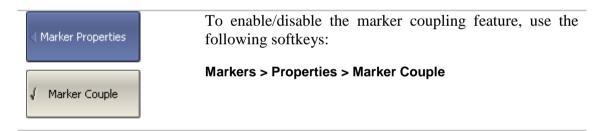


Figure 6.3 Marker coupling feature



6.1.6.2 Marker Table

The marker table enables you to view the values of the markers of all the traces and all the channels (See figure 6.4).

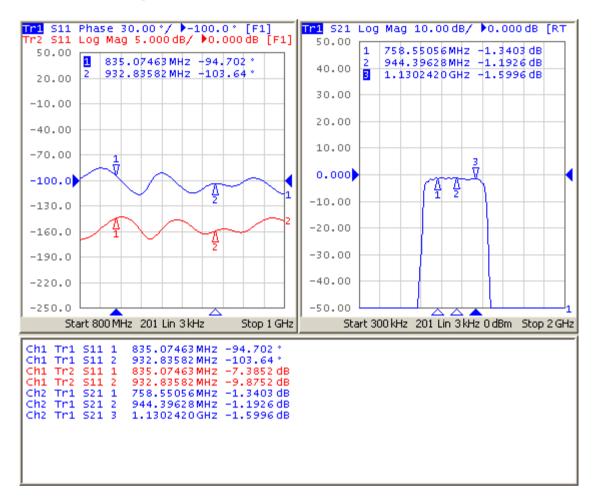
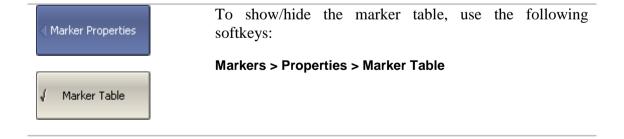
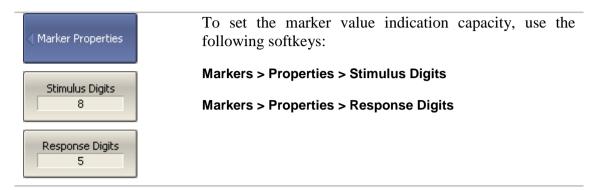


Figure 6.4 Marker table



6.1.6.3 Marker Value Indication Capacity

By default, the marker stimulus values are displayed with 8 decimal digits and marker response values are displayed with 5 decimal digits. The user can change these settings.



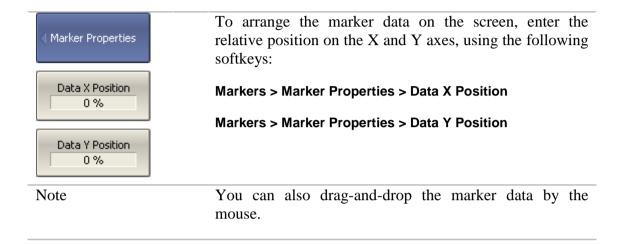
6.1.6.4 Multi Marker Data Display

If several overlapping traces are displayed in one graph, by default only active marker data are displayed on the screen. The user can enable display of the marker data of all the traces simultaneously. The markers of different traces will be distinguished by the color. Each marker will have same color with its trace.

< Marker Properties	To enable/disable the multi marker data display, toggle the softkey:
√ Active Only	Markers > Marker Properties > Active Only
Note	When multi marker data display is enabled, to avoid data overlapping on the screen, arrange the marker data on the screen (See section 6.1.6.5).

6.1.6.5 Marker Data Arranging

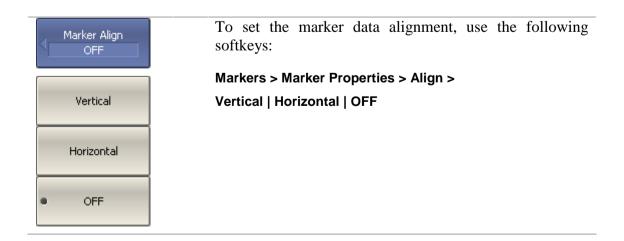
By default, the marker data are displayed in the upper left corner of the screen. The user can rearrange the marker data display on the screen. The marker data position on the screen is described by two parameters: relative position on the X and Y axes, in percent. Zero percent is upper left corner, 100% is lower right corner. Marker data position for each trace is set separately. This allows the user to avoid data overlapping on the screen.



6.1.6.6 Marker Data Alignment

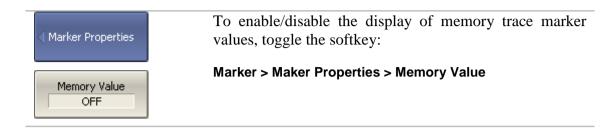
By default, the marker data are displayed independently for each trace. The user can align the marker data display on the screen. The alignment deactivates the independent marker data layout. In this case, the relative position on the X and Y axes is valid only for the first trace. The marker data of the other traces become aligned relatively to the first trace. Two types of alignment are available:

- Vertical marker data of different traces are displayed one under another;
- Horizontal marker data of different traces are displayed in line.



6.1.6.7 Memory Trace Value Display

By default, the marker values of the data traces (not memory traces) are displayed on the screen. The user can enable the display of memory trace maker values, if a memory trace is available.



6.1.7 Marker Position Search Functions

Marker position search function enables you to find on a trace the following values:

- maximum value;
- minimum value;
- peak value;
- target level.

6.1.7.1 Search for Maximum and Minimum

Maximum and minimum search functions enable you to determine the maximum and minimum values of the measured parameter and move the marker to these positions on the trace (See figure 6.5).

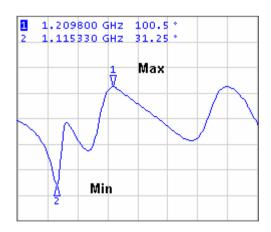
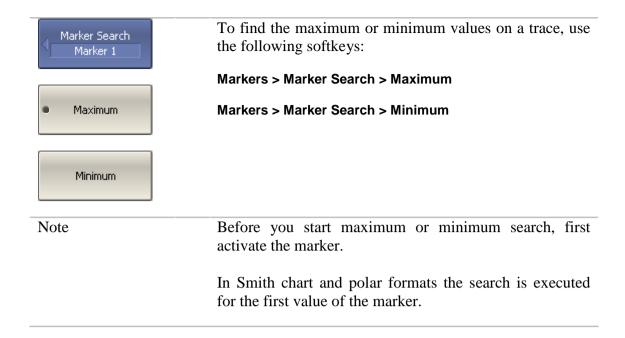


Figure 6.5 Maximum and minimum search



6.1.7.2 Search for Peak

Peak search function enables you to determine the peak value of the measured parameter and move the marker to this position on the trace (See figure 6.6).

Peak is a local extremum of the trace.

Peak is called **positive** if the value in the peak is greater than the values of the adjacent points.

Peak is called **negative** if the value in the peak is smaller than the values of the adjacent points.

Peak excursion is the smallest of the absolute differences between the response values in the peak point and the two adjoining peaks of the opposite polarity.

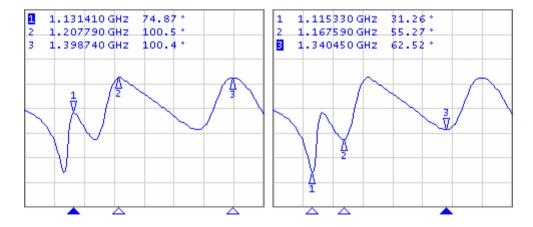


Figure 6.6 Positive and negative peaks

The peak search is executed only for the peaks meeting the following conditions:

- The peaks must have the polarity (positive, negative, or both) specified by the user;
- The peaks must have the peak deviation not less than the value assigned by the user.

The following options of the peak search are available:

- Search for nearest peak;
- Search for greatest peak;
- Search for left peak;
- Search for right peak.

The nearest peak is a peak, which is located most near to the current position of the marker along the stimulus axis.

The greatest peak is a peak with maximum or minimum value, depending on the current polarity settings of the peak.

Note	The search for the greatest peak is deferent from the search for maximum or minimum as the peak cannot be located in the limiting points of the trace even if these points have maximum or minimum values.
Peak Polarity	To set the polarity of the peak, use the following softkeys:
Positive	Markers > Marker Search > Peak > Peak Polarity > Positive Negative Both
Positive	
Negative	
Both	
Search Peak Marker 1	To enter the peak excursion value, use the following softkeys:
Peak Excursion	Markers > Marker Search > Peak > Peak Excursion
1 dB	Then enter the value using numerical keypad, or $\langle \rangle$, $\langle \rangle$ arrows.
Search Peak	To activate the nearest peak search, use the following softkeys:
	Markers > Marker Search > Peak > Search Peak

Search Max Peak	To activate the greatest peak search, use the following softkeys: Markers > Marker Search > Peak > Search Max Peak	
Search Peak Left	To activate the left peak search, use the following softkeys:	
	Markers > Marker Search > Peak > Search Peak Left	
Search Peak Right	To activate the left peak search, use the following softkeys:	
	Markers > Marker Search > Peak > Search Peak Right	
Note	Before you start maximum or minimum search, first activate the marker.	
	In Smith chart and polar formats the search is executed for the first value of the marker.	

6.1.7.3 Search for Target Level

Target level search function enables you to locate the marker with the given level of the measured parameter (See figure 6.7).

The trace can have two types of transition in the points where the target level crosses the trace:

- transition type is positive if the function derivative (trace slope) is positive at the intersection point with the target level;
- transition type is negative if the function derivative (trace slope) is negative at the intersection point with the target level.

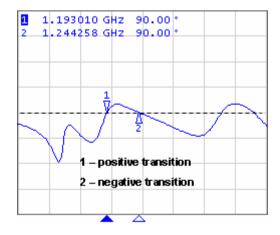


Figure 6.7 Target level search

The target level search is executed only for the intersection points, which have the specific transition polarity selected by the user (positive, negative, or both).

The following options of the target level search are available:

- Search for nearest target;
- Search for left target;
- Search for right target.

Target Transition	To set the transition polarity, use the following softkeys:
Both	Markers > Marker Search > Target > Target Transition > Positive Negative Both
Positive	
Negative	
Both	
Search Target	To enter the target level value, use the following softkeys:
Marker 1	Markers > Marker Search > Target > Target Value
Target Value 0 dB	Then enter the value using numerical keypad, or $\^*$, $\^*$ arrows.
 Search Target 	To activate the nearest target search, use the following softkeys:
	Markers > Marker Search > Target > Search Target
Search Target Left	To activate the left target search, use the following softkeys:
	Markers > Marker Search > Target > Search Target Left
Search Target Right	To activate the right target search, use the following softkeys:
	Markers > Marker Search > Target > Search Target Right
Target Line OFF	To enable/disable target level indication on the screen, use the following softkeys:
	Markers > Marker Search > Target > Target Line
Clear All Target	Clear All Target Lines softkey disables indication of target

Note

Before you start maximum or minimum search, first activate the marker.

In Smith chart and polar formats the search is executed for the first value of the marker.

6.1.7.4 Search Tracking

The marker position search function by default can be initiated by any search key pressing. Search tracking mode allows you to perform continuous marker position search, until this mode is disabled.



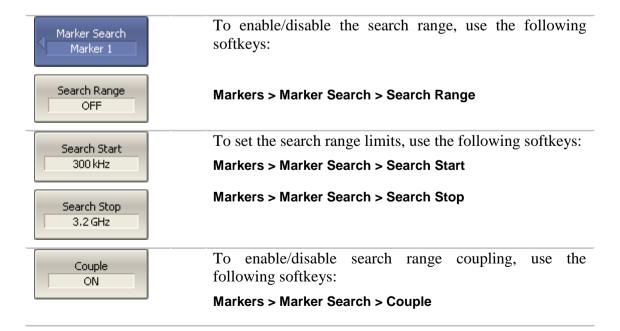
To enable/disable search tracking mode, use the following softkeys:

Markers > Marker Search > Tracking

6.1.7.5 Search Range

The user can set the search range for the marker position search by setting the stimulus limits. This function involves the following additional features:

- search range coupling, which allows the user to define the same search range for all the traces of a channel;
- vertical line indication of the search range limits.



Search Range Lines To enable/disable search range limits indication, use the following softkeys:

Markers > Marker Search > Search Range Lines

6.1.8 Marker Math Functions

Marker math functions are the functions, which use markers for calculating of various trace characteristics. Four marker math functions are available:

- Statistics:
- Bandwidth Search;
- Flatness:
- RF Filter.

6.1.8.1 Trace Statistics

The *trace statistics* feature allows the user to determine and view such trace parameters as mean, standard deviation, and peak-to-peak. The trace statistics range can be defined by two markers (See figure 6.8).

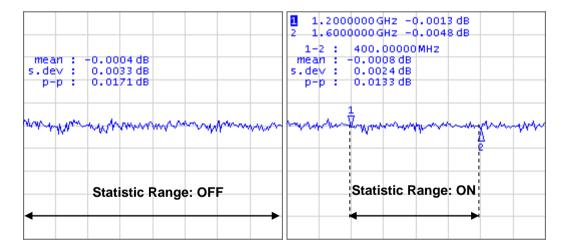


Figure 6.8 Trace statistics

Table 6.2 Statistics parameters

Symbol	Definition	Formula
mean	Arithmetic mean	$M = \frac{1}{N} \cdot \sum_{i=1}^{N} x_i$
s.dev	Standard deviation	$\sqrt{\frac{1}{N-1} \cdot \sum_{i=1}^{N} (x_i - M)^2}$
р-р	Peak-to-Peak: difference between the maximum and minimum values	Max – Min

(Statistics	To enable/disable trace statistics function, use the following softkeys: Markers > Marker Math > Statistics > Statistics	
Statistics OFF	Markers > Marker Matri > Statistics > Statistics	
Statistic Range OFF	To enable/disable trace statistics range, use the following softkeys: Markers > Marker Math > Statistics > Statistic Range	
Statistic Start Marker 1	To set the start/stop markers of the statistics range, use the following softkeys:	
	Markers > Marker Math > Statistics > Statistic Start	
Statistic Stop Marker 2	Markers > Marker Math > Statistics > Startistic Stop	

6.1.8.2 Bandwidth Search

The *bandwidth search* function allows the user to determine and view the following parameters of a passband or a stopband: bandwidth, center frequency, lower frequency, higher frequency, Q value, and insertion loss (See figure 6.9). In the figure, F1 and F2 are the lower and higher cutoff frequencies of the band respectively.

The bandwidth search is executed from the reference point. The user can select as reference point the active marker or the maximum of the trace. The bandwidth search function determines the lower and higher cutoff frequencies, which are apart from the reference point response by *bandwidth value* defined by the user (usually -3 dB).

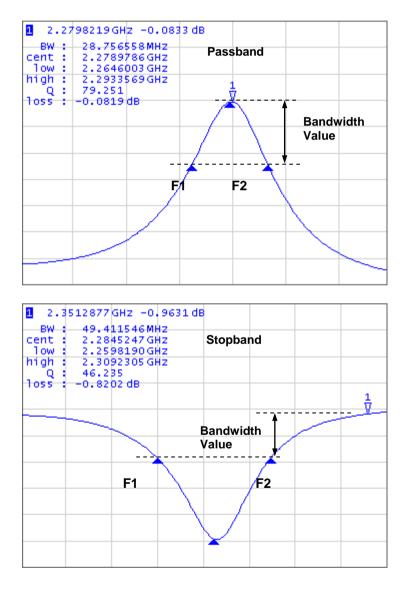


Figure 6.9 Bandwidth search

Table 6.3 Bandwidth parameters

Parameter Description	Symbol	Definition	Formula
Bandwidth	BW	The difference between the higher and lower cutoff frequencies	F2 – F1
Center Frequency	cent	The midpoint between the higher and lower cutoff frequencies	(F1+F2)/2
Lower Cutoff Frequency	low	The lower frequency point of the intersection of the bandwidth cutoff level and the trace	F1
Higher Cutoff Frequency	high	The higher frequency point of the intersection of the bandwidth cutoff level and the trace	F2
Quality Factor	Q	The ratio of the center frequency to the bandwidth	Cent/BW
Loss	loss	The trace measured value in the reference point of the bandwidth search	-

∃ Bandwidth Search ■	To enable/disable bandwidth search function, use the following softkeys:
Bandwidth Search OFF	Markers > Marker Math > Bandwidth Search > Bandwidth Search
Туре	Set the bandwidth search type by softkeys:
Bandpass	Markers > Marker Math > Bandwidth Search > Type
	The type and the softkey label toggle between Bandpass and Notch settings.
Search Ref To Marker	To set the search reference point, use the following softkeys:
	Markers > Marker Math > Bandwidth Search > Search Ref To
	The type and the softkey label toggle between Max and
	Marker settings.
Bandwidth Value	To enter the bandwidth value, use the following softkeys:
-3 dB	Markers > Marker Math > Bandwidth Search > Bandwidth Value

6.1.8.3 Flatness

The *flatness search* function allows the user to determine and view the following trace parameters: gain, slope, and flatness. The user sets two markers to specify the flatness search range (See figure 6.10).

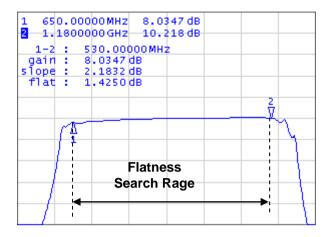


Figure 6.10 Flatness search

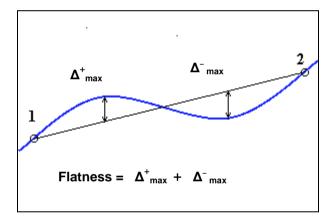
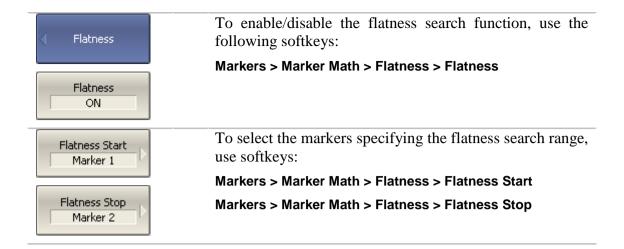


Figure 6.11 Calculation of flatness

Table 6.4 Flatness parameters

Parameter Description	Symbol	Definition
Gain	gain	Marker 1 value
Slope	slope	Difference between marker 2 and marker 1 values.
Flatness	flatness	Sum of "positive" and "negative" peaks of the trace, which are measured from the line connecting marker 1 and marker 2 (See figure 6.11).



6.1.8.4 RF Filter Statistics

The *RF filter statistics* function allows the user to determine and view the following filter parameters: loss, peak-to-peak in a passband, and rejection in a stopband. The passband is specified by the first pair of markers, the stopband is specified by the second pair of markers (See figure 6.12).

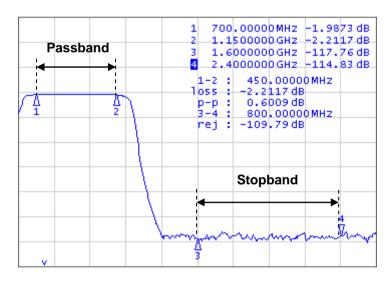
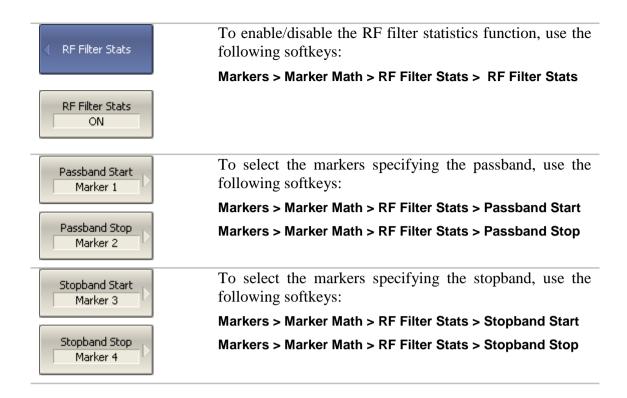


Figure 6.12 RF filter statistics

Table 6.5 RF filter statistics parameters

Parameter Description	Symbol	Definition
Loss in passband	loss	Minimum value in the passband
Peak-to-peak in passband	р-р	Difference between maximum and minimum in the passband
Reject	rej	Difference between maximum in stopband and minimum in passband



6.1.9 Marker Functions

Using the current position of a marker you can perform settings of the following parameters:

- Stimulus start;
- Stimulus stop;
- Stimulus center;
- Reference level;
- Electrical delay.

Before performing the settings, first activate the marker.

Marker Function Marker 1	To set the stimulus start, use the following softkeys: Markers > Marker Functions > Marker->Start
Marker -> Start	
Madan S Char	To set the stimulus stop, use the following softkeys:
Marker -> Stop	Markers > Marker Functions > Marker->Stop
Madan S Cartan	To set the stimulus center, use the following softkeys:
Marker -> Center	Markers > Marker Functions > Marker->Center

Marker ->	To set the reference level, use the following softkeys:
Refernse Value	Markers > Marker Functions > Marker->Ref Value
Marker -> Delay	To set the electrical delay, use the following softkeys:
Marker 12 Delay	Markers > Marker Functions > Marker->Delay
Marker -> Ref Marker	To set reference marker to the active marker point, use the following softkeys:
	Markeya - Markey Cunetions - Markey - Def Markey

Markers > Marker Functions > Marker->Ref Marker

6.2 Memory Trace Function

For each data trace displayed on the screen a so-called memory trace can be created. The memory trace is displayed in the same color as the main data trace, but its brightness is twice lower¹.

The data trace shows the currently measured data and is continuously being updated as the measurement goes on.

The memory trace is a data trace saved into the memory. It is created from the current measurement when the user is clicking the corresponding softkey. After that, the two traces become displayed on the screen – the data trace and the memory trace. The user can customize the trace indication. The trace status field will indicate the following:

- **D&M** data trace and memory trace are displayed;
- M only memory trace is displayed;
- **OFF** both traces are not displayed
- *Empty field* only data trace is displayed.

The memory trace bears the following features of the data trace (which if changed, will **clear** the memory):

- frequency range,
- number of points,
- sweep type.

The memory trace has the following settings common with the data trace (which if changed, modifies the both traces):

- format.
- scale,
- smoothing,
- electrical delay.

The following data trace settings (if changed after the memory trace creation) do not influence the memory trace:

- power in frequency sweep mode,
- frequency in power sweep mode,
- measured parameter (S-parameter),
- IF bandwidth,
- averaging,
- calibration.

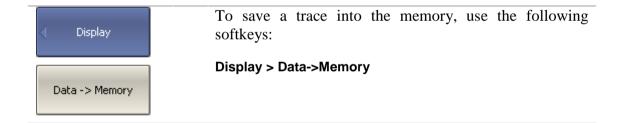
The color and brightness of the data and memory traces can be customized by the user (See section 8.6).

The memory trace can be used for math operations with the data trace. The resulting trace of such an operation will replace the data trace. The math operations with memory and data traces are performed in complex values. The following four math operations are available:

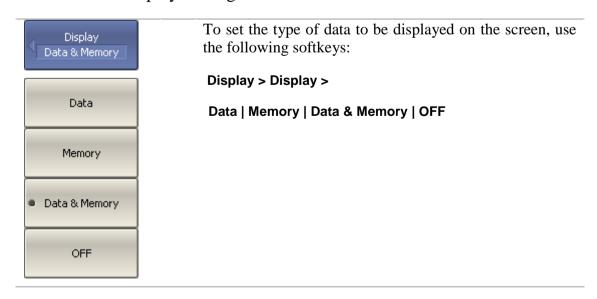
Data / Memory	Divides the measured data by the data in the memory trace.
	The trace status field indicates: D/M .
Data * Memory	Multiplies the measured data by the memory trace.
	The trace status field indicates: D*M .
Data – Memory	Subtracts a memory trace from the measured data.
	The trace status field indicates: D-M .
Data + Memory	Adds the measured data to the data in the memory trace.
	The trace status field indicates: D+M .

6.2.1 Saving Trace into Memory

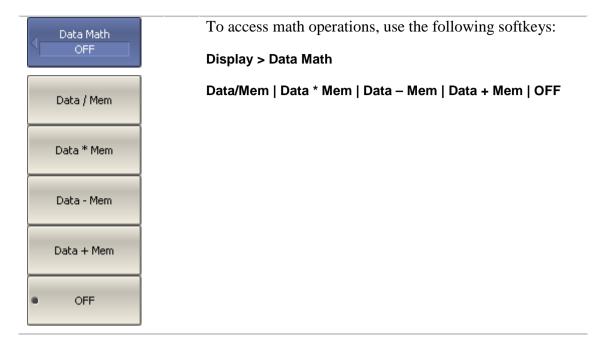
The memory trace function can be applied to the individual traces of the channel. Before you enable this function, first activate the trace.



6.2.2 Trace Display Setting



6.2.3 Mathematical Operations

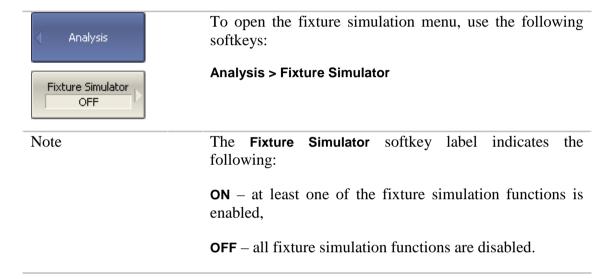


6.3 Fixture Simulation

The fixture simulation function enables you to emulate the measurement conditions other than those of the real setup. The following conditions can be simulated:

- Port Z conversion;
- De-embedding;
- Embedding.

Before starting the fixture simulation, first activate the channel. The simulation function will affect all the traces of the channel.



6.3.1 Port Z Conversion

Port Z conversion is a function of transformation of the S-parameters measured during port wave impedance change simulation (See figure 6.13).

Note	The value of the test port impedance is defined in the
	process of calibration. It is determined by the
	characteristic impedance of the calibration kit and the
	value is entered by the user as described in section 5.2.12.

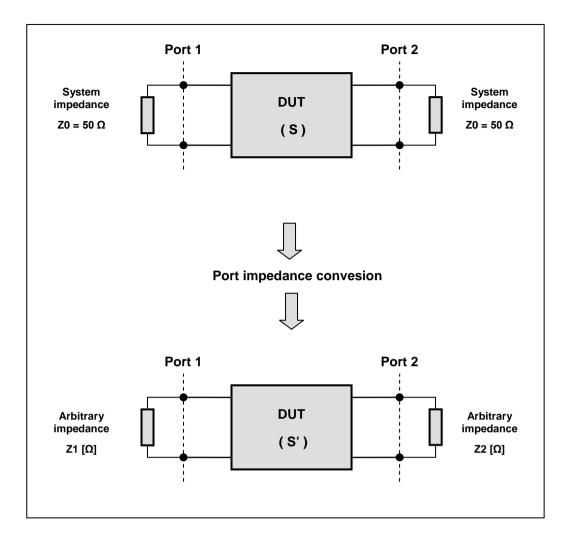
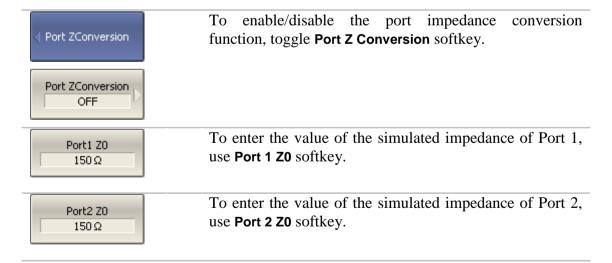


Figure 6.13 Port Z conversion



6.3.2 De-embedding

De-embedding is a function of the S-parameter transformation by removing of some circuit effect from the measurement results.

The circuit being removed should be defined in the data file containing S-parameters of this circuit. The circuit should be described as a 2-port in Touchstone file (extension .s2p), which contains the S-parameter table: S_{11} , S_{21} , S_{12} , S_{22} for a number of frequencies.

The de-embedding function allows to mathematically exclude from the measurement results the effect of the fixture circuit existing between the calibration plane and the DUT in the real network. The fixture is used for the DUTs, which cannot be directly connected to the test ports.

The de-embedding function shifts the calibration plane closer to the DUT, so as if the calibration has been executed of the network with this circuit removed (See figure 6.14).

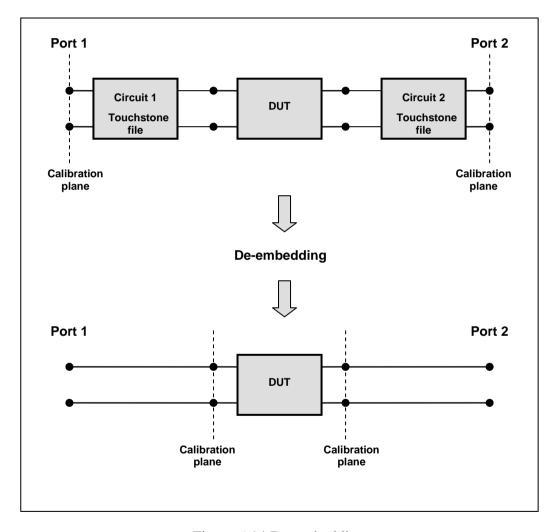
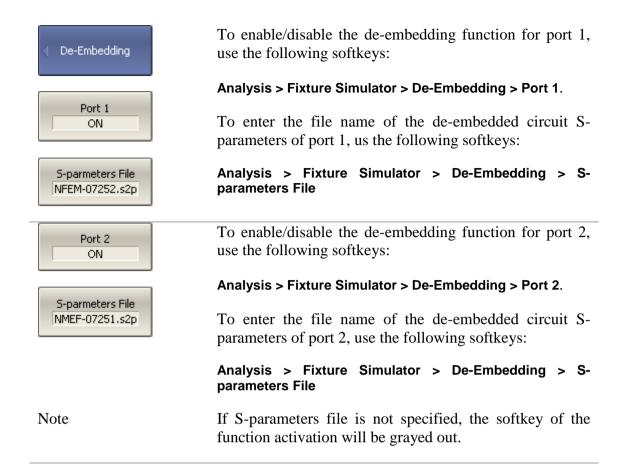


Figure 6.14 De-embedding

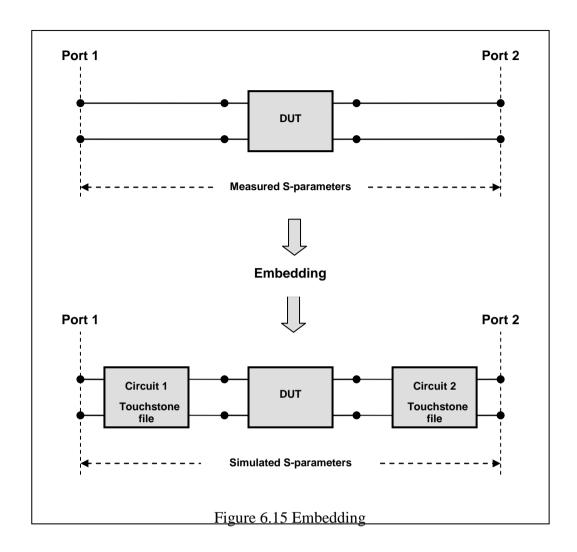


6.3.3 Embedding

Embedding is a function of the S-parameter transformation by integration of some virtual circuit into the real network (See figure 6.15). The embedding function is an inverted de-embedding function.

The circuit being integrated should be defined in the data file containing S-parameters of this circuit. The circuit should be described as a 2-port in Touchstone file (extension .s2p), which contains the S-parameter table: S_{11} , S_{21} , S_{12} , S_{22} for a number of frequencies.

The embedding function allows to mathematically simulate the DUT parameters after adding of the fixture circuits.





To enable/disable the embedding function for port 1, use the following softkeys:

Analysis > Fixture Simulator > Embedding > Port 1.

To enter the file name of the embedded circuit S-parameters of port 1, use the following softkeys:

S-parmeters File NFEM-07252.s2p Analysis > Fixture Simulator > Embedding > S-parameters File

	Port 2	
Г	ON	

To enable/disable the embedding function for port 2, use the following softkeys:

S-parmeters File NMEF-07251.s2p

Analysis > Fixture Simulator > Embedding > Port 2.

To enter the file name of the embedded circuit S-parameters of port 2, use the following softkeys:

Analysis > Fixture Simulator > Embedding > S-parameters File

Note

If S-parameters file is not specified, the softkey of the function activation will be grayed out.

6.4 Time Domain Transformation

The Analyzer measures and displays parameters of the DUT in frequency domain. Time domain transformation is a function of mathematical modification of the measured parameters in order to obtain the time domain representation.

For time domain transformation Z-transformation and frequency domain window function are applied.

The time domain transformation can be activated for separate traces of a channel. The current frequency parameters $(S_{11}, S_{21}, S_{12}, S_{22})$ of the trace will be transformed into the time domain.

Note Traces in frequency and time domains can simultaneously belong to one channel. The stimulus axis label will be displayed for the active trace, in frequency or time units.

The transformation function allows for setting of the measurement range in time domain within Z-transformation ambiguity range. The ambiguity range is determined by the measurement step in the frequency domain:

$$\Delta T = \frac{1}{\Delta F}; \quad \Delta F = \frac{F \max - F \min}{N - 1}$$

The time domain function allows to select the following transformation types:

- Bandpass mode simulates the impulse bandpass response. It allows the user to obtain the response for circuits incapable of direct current passing. The frequency range is arbitrary in this mode. The time domain resolution in this mode is twice lower than it is in the lowpass mode;
- Lowpass mode simulates lowpass impulse and lowpass step responses. It is applied to the circuits passing direct current, and the direct component (in point F=0 Hz) is interpolated from the start frequency (Fmin) of the range. In this mode the frequency range represents a harmonic grid where the frequency value at each frequency point is an integer multiple of the start frequency of the range Fmin. The time domain resolution is twice higher than it is in the bandpass mode.

The time domain transformation function applies Kaiser window for initial data processing in frequency domain. The window function allows to reduce the ringing (side lobes) in the time domain. The ringing is caused by the abrupt change of the data at the limits of the frequency domain. But while side lobes are reduced, the main pulse or front edge of the lowpass step becomes wider.

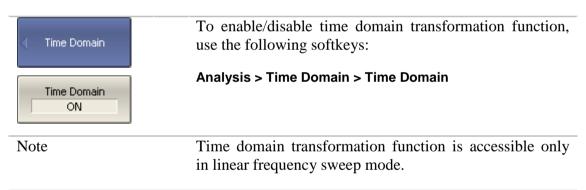
The Kaiser window is described by β parameter, which smoothly fine-tune the window shape from minimum (rectangular) to maximum. The user can fine-tune the window shape or select one of the three preprogrammed windows:

- Minimum (rectangular);
- Normal:
- Maximum.

Table 6.6 Preprogrammed window types

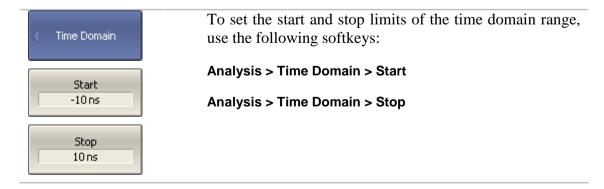
	Lowpass Impulse		Lowpass Step	
Window	Side Lobes Level	Pulse Width	Side Lobes Level	Edge Width
Minimum	– 13 dB	$\frac{0.6}{F \text{max} - F \text{min}}$	– 21 dB	$\frac{0.45}{F\text{max} - F\text{min}}$
Normal	– 44 dB	$\frac{0.98}{F \max - F \min}$	– 60 dB	$\frac{0.99}{F \text{max} - F \text{min}}$
Maximum	– 75 dB	$\frac{1.39}{F \max - F \min}$	– 70 dB	$\frac{1.48}{F \text{max} - F \text{min}}$

6.4.1 Time Domain Transformation Activating



6.4.2 Time Domain Transformation Span

To define the span of time domain representation, you can set its start and stop, or center and span values.





To set the center and span of the time domain, use the following softkeys:

Analysis > Time Domain > Center

Analysis > Time Domain > Span

6.4.3 Time Domain Transformation Type



To set the time domain transformation type, use the following softkeys:

Analysis > Time Domain > Type >

Bandpass | Lowpass Impulse | Lowpass Step

6.4.4 Time Domain Transformation Window Shape Setting



To set the window shape, use the following softkeys:

Analysis > Time Domain > Window >

Minimum | Normal | Maximum



To set the window shape for the specific impulse width or front edge width, use the following softkeys:

Analysis > Time Domain > Window > Impulse Width

The setting values are limited by the specified frequency range. The bottom limit corresponds to the value implemented in the minimum (rectangular) window. The top limit corresponds to the value implemented in the maximum window.

Kiser Beta 6	To set the window shape for the specific β -parameter of the Kaiser-Bessel filter, use the following softkeys:	
	Analysis > Time Domain > Window > Kaiser Beta	
The available β values are from 0 to 13. 0 corresponds to normal window, 6 corresponds to normal window.		
Note	The impulse width and β of the Kaiser-Bessel filter are the dependent parameters. When you set one of the parameters the other one will be adjusted automatically.	

6.4.5 Frequency Harmonic Grid Setting

If lowpass impulse or lowpass step transformation is enabled, the frequency range will be represented as a harmonic grid. The frequency values in measurement points are integer multiples of the start frequency Fmin. The Analyzer is capable of creating a harmonic grid for the current frequency range automatically.

√ Time Domain	To create a harmonic grid for the current frequency range, use the following softkeys: Analysis > Time Domain > Set Frequency Low Pass	
Set Frequency Low Pass		
Note	The frequency range will be transformed as follows:	
	Fmax > N x 0.3 MHz	Fmax < N x 0.3 MHz
	Fmin = Fmax / N	Fmin = 0.3 MHz , Fmax = $N \times 0.3 \text{ MHz}$

6.5 Time Domain Gating

Time domain gating is a function, which mathematically removes the unwanted responses in time domain. The function performs time domain transformation and applies reverse transformation back to frequency domain to the user-defined span in time domain. The function allows the user to remove spurious effects of the fixture devices from the frequency response, if the useful signal and spurious signal are separable in time domain.

Note

Use *time domain* function for viewing the layout of useful and spurious responses. Then enable *time domain gating* and set the gate span to remove as much of spurious response as possible. After that disable the time domain function and view the response without spurious effects in frequency domain.

The function involves two types of time domain gating:

- bandpass removes the response outside the gate span,
- *notch* removes the response inside the gate span.

The rectangular window shape in frequency domain leads to spurious sidelobes due to sharp signal changes at the limits of the window. The following gate shapes are offered to reduce the sidelobes:

- *maximum*;
- wide:
- normal;
- minimum.

The minimum window has the shape close to rectangular. The maximum window has more smoothed shape. From minimum to maximum window shape, the sidelobe level increases and the gate resolution reduces. The choice of the window shape is always a trade-off between the gate resolution and the level of spurious sidelobes. The parameters of different window shapes are represented in table 6.7.

Table 6.7 Time domain gating window shapes

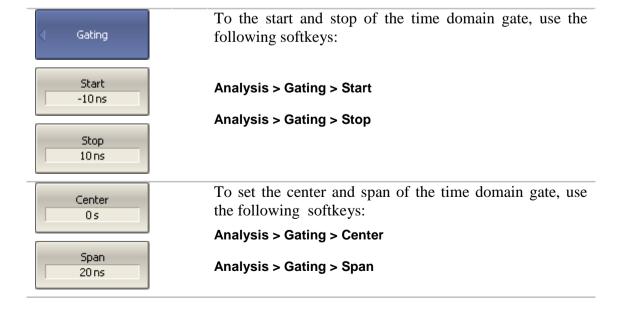
Window Shape	Bandpass Sidelobe Level	Gate Resolution (Minimum Gate Span)
Minimum	– 48 dB	$\frac{2.8}{F \max - F \min}$
Normal	- 68 dB	$\frac{5.6}{F \max - F \min}$
Wide	– 57 dB	$\frac{8.8}{F \text{max} - F \text{min}}$
Maximum	– 70 dB	$\frac{25.4}{F\text{max} - F\text{min}}$

6.5.1 Time Domain Gate Activating

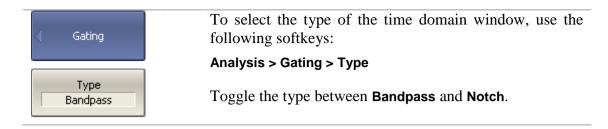
√ Gating	To enable/disable the time domain gating function: toggle the following softkey:
	Analysis > Gating > Gating
Gating OFF	
Note	Time domain gating function is accessible only in linear frequency sweep mode.

6.5.2 Time Domain Gate Span

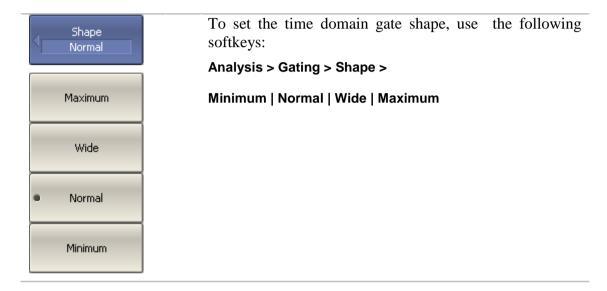
To define the span of time domain gate, you can set its start and stop, or center and span values.



6.5.3 Time Domain Gate Type



6.5.4 Time Domain Gate Shape Setting



6.6 S-Parameter Conversion

S-parameter conversion function allows conversion of the measurement results (S_{ab}) to the following parameters:

• Equivalent impedance (Zr) and equivalent admittance (Yr) in reflection measurement:

$$Z_r = Z_{0a} \cdot \frac{1 + S_{ab}}{1 - S_{ab}}$$
$$Y_r = \frac{1}{Z}$$

• Equivalent impedance (Zt) and equivalent admittance (Yr) in transmission measurement:

$$Z_{t} = \frac{2 \cdot \sqrt{Z_{0a} \cdot Z_{0b}}}{S_{ab}} - (Z_{0a} + Z_{0b})$$
$$Y_{t} = \frac{1}{Z_{t}}$$

■ Inverse S-parameter:

$$\left(\begin{array}{c} \frac{1}{S_{ab}} \end{array}\right)$$

• Equivalent impedance (Ztsh) and equivalent admittance (Ytsh) in transmission shunt measurements:

$$Z_{tsh} = rac{1}{Y_{tsh}}$$
 $Y_{sht} = rac{2 \cdot \sqrt{Y_{0a} \cdot Y_{0b}}}{Y_{ab}} - (Y_{0a} + Y_{0b})$ $Y_{0a} = rac{1}{Z_{0a}}, \qquad Y_{0b} = rac{1}{Z_{0b}}$

• S-parameter complex conjugate.

Where:

 Z_{0a} – characteristic impedance of Port a,

Z_{0b} – characteristic impedance of Port b,

 Z_{ab} – measured S-parameter (a and b are the port numbers).

S-parameter conversion function can be applied to an individual trace of a channel. Before enabling the function, first activate the trace.

< Conversion	To enable/disable the conversion, use the following softkeys:
Conversion OFF	Analysis > Conversion > Conversion
Function Z: Reflection	To select the conversion type, use the following softkeys: Analysis > Conversion > Function >
Z: Reflection	Zr: Reflection Zt: Transmission
Z: Transmission	Yr: Reflection
Y: Reflection	Yt: Transmission 1/S: Inverse
Y: Transmission	Ztsh: Trans-Shunt
1/5: Inverse	Ytsh: Trans-Shunt Conjugation
Z: Trans-Shunt	
Y: Trans-Shunt	
Conjugation	
Note	All conversion types are indicated in the trace status field, if enabled.

6.7 Limit Test

The limit test is a function of automatic pass/fail judgment for the trace of the measurement result. The judgment is based on the comparison of the trace to the limit line set by the user.

The limit line can consist of one or several segments (See figure 6.16). Each segment checks the measurement value for failing whether upper or lower limit. The limit line segment is defined by specifying the coordinates of the beginning (X_0, Y_0) and the end (X_1, Y_1) of the segment, and type of the limit. The MAX or MIN limit types check if the trace falls outside of the upper or lower limit respectively.

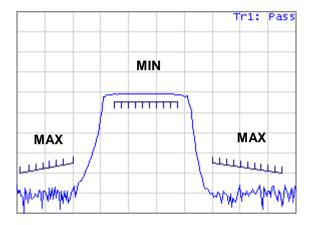


Figure 6.16 Limit line

The limit line is set by the user in the limit table. Each row in the table describes one segment of the line. Limit table editing is described below. The table can be saved into a *.lim file.

The display of the limit lines on the screen can be turned on/off independently of the status of the limit test function.

The result of the limit test is indicated in the upper right corner of the graph. If the measurement result passed the limit test, you will see the trace number and the result: **Tr1: Pass**.

If the measurement result failed, the result will be indicated in the following ways (See figure 6.17):

- Tr1: Fail will be displayed in upper right corner of the graph;
- Fail sign will be displayed in red in the center of the window;
- The points of the trace, which failed the test will be highlighted in red;
- You will hear a beep.

Fail sign and the beep can be disabled by the user. For beep deactivation see section 8.5.

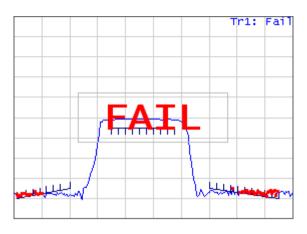
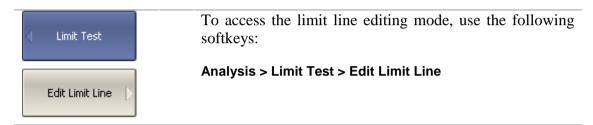


Figure 6.17 Test fail indication

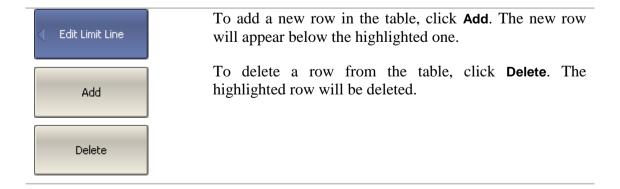
6.7.1 Limit Line Editing



In the editing mode the limit table will appear in the lower part of the screen (See figure 6.18). The limit table will be hidden when you quit the submenu.

	Туре	Begin Stimulus	End Stimulus	Begin Response	End Response
1	MAX	10 MHz	400 MHz	-100 dB	-90 dB
2	MIN	700MHz	1.2 GHz	-6 dB	-6 dB
3	MAX	1.4GHz	2 GHz	-90 dB	-100 dB
4					
,					

Figure 6.18 Limit line table

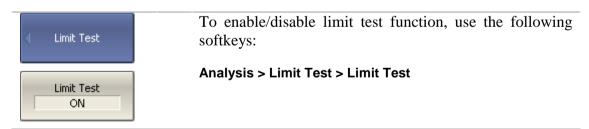


Clear Limit Table	To clear the entire table, use Clear Limit Table softkey.
Save Limit Table	To save the table into *.lim file, use Save Limit Table softkey.
Restore Limit Table	To open the table from a *.lim file, use Restore Limit Table softkey.

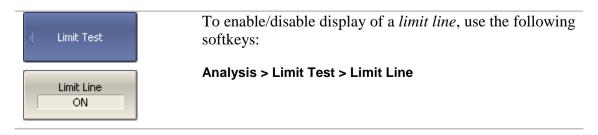
Navigating in the table to enter the values of the following parameters of a limit test segment:

Туре	Select the segment type among the following: • MAX – upper limit	
	■ MIN – lower limit	
	■ OFF — segment not used for the limit test	
Begin Stimulus	Stimulus value in the beginning point of the segment.	
End Stimulus	Stimulus value in the ending point of the segment.	
Begin Response	Response value in the beginning point of the segment.	
End Response	Response value in the ending point of the segment.	

6.7.2 Limit Test Enabling/Disabling



6.7.3 Limit Test Display Management

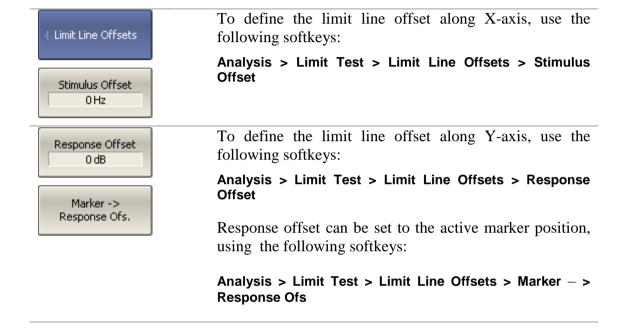




To enable/disable display of Fail sign in the center of the graph, use Fail Sign softkey.

6.7.4 Limit Line Offset

Limit line offset function allows the user to shift the segments of the limit line by the specified value along X and Y axes simultaneously.



6.8 Ripple Limit Test

Ripple limit test is an automatic pass/fail check of the measured trace data. The trace is checked against the maximum ripple value (*ripple limit*) defined by the user. The ripple value is the difference between the maximum and minimum response of the trace in the trace frequency band.

The ripple limit can include one or more segments (See figure 6.19). Each segment provides the ripple limit for the specific frequency band. A segment is set by the frequency band and the ripple limit value.

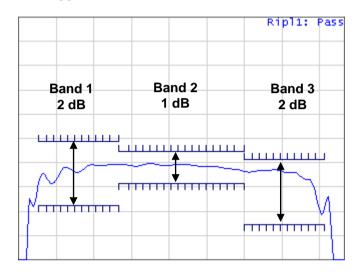


Figure 6.19 Ripple limits

The ripple limit settings are performed in the ripple limit table. Each row of the table describes the frequency band the ripple limit value. The ripple limit table editing is described below. The table can be saved into a *.lim file.

The display of the limit lines on the screen can be turned on/off by the user.

The result of the ripple limit test is indicated in the upper right corner of the graph. If the measurement result passed the limit test, you will see the trace number and the result: **Ripl1: Pass**.

If the measurement result failed, the result will be indicated in the following ways (See figure 6.20):

- **Ripl1: Fail** will be displayed in upper right corner of the graph;
- Fail sign will be displayed in red in the center of the window;
- You will hear a beep.

Fail sign and the beep can be disabled by the user. For beep deactivation see section 8.5.



Figure 6.20 Test fail indication

The display of the ripple value can be enabled/disabled by the user in the ripple limit test status line in the upper right corner of the graph (See figure 6.21). The ripple value is displayed for the band selected by the user. The ripple value can be represented as an *absolute* value or as a *margin* to the limit.

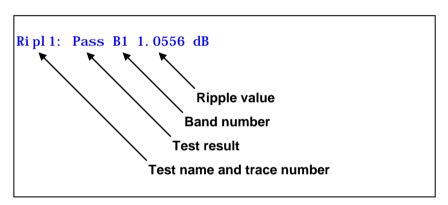
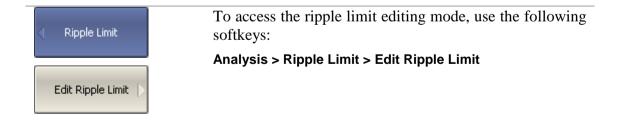


Figure 6.21 Ripple limit test status line

6.8.1 Ripple Limit Editing



In the editing mode the limit table will appear in the lower part of the screen (See figure 6.22). The limit table will be hidden when you quit the submenu.

	Туре	Begin Stimulus	End Stimulus	Ripple Limit
1	ON	640MHz	800MHz	4 dB
2	ON	800MHz	1.05 GHz	2 dB
3	ON	1.05 GHz	1.21GHz	3 dB
4				

Figure 6.22 Ripple limit table

< Edit Ripple Limit	To add a new row in the table, click Add . The new row will appear below the highlighted one.
Add	To delete a row from the table, click Delete . The highlighted row will be deleted.
Delete	
Clear Ripple Limit Table	To clear the entire table, use Clear Ripple Limit Table softkey.
Save Ripple Limit Table	To save the table into *.rlm file, use Save Ripple Limit Table softkey.
Restore Ripple Limit Table	To open the table from a *.rlm file, use Recall Ripple Limit Table softkey.

Navigating in the table to enter the values of the following parameters of a ripple limit test segment:

Select the segment type among the following: ON – band used for the ripple limit test	
 ON – band used for the ripple limit test OFF — band not used for the limit test 	
- Of the bank not used for the firmt test	
Stimulus value in the beginning point of the segment.	
Stimulus value in the ending point of the segment.	
Ripple limit value.	

6.8.2 Ripple Limit Enabling/Disabling



To enable/disable ripple limit test function, use the following softkeys:

Analysis > Ripple Limit > Ripple Test

6.8.3 Ripple Limit Test Display Management

Ripple Limit	To enable/disable display of the <i>ripple limit line</i> , use the following softkeys:
Ripple Limit ON	Analysis > Ripple Limit > Ripple Limit
Fail Sign	To enable/disable display of the Fail sign in the center of the graph, use the following softkeys:
	Analysis > Ripple Limit > Fail Sign.
Ripple Value OFF	To enable/disable display of the ripple value, use the following softkeys:
	Analysis > Ripple Limit > Ripple Value >
• OFF	OFF Absolute Margin
Absolute	
Margin	
Ripple Value Band	To enter the number of the band, whose ripple value should be displayed, use the following softkeys:
	Analysis > Ripple Limit > Ripple Value Band

7 ANALYZER DATA OUTPUT

7.1 Analyzer State

The Analyzer state, calibration and measured data can be saved on the hard disk to an Analyzer state file and later uploaded back into the Analyzer program. The following four types of saving are available:

State	The Analyzer settings.	
State & Cal	The Analyzer settings and the table of calibration coefficients.	
State & Trace	The Analyzer settings and data traces ¹ .	
All	The Analyzer settings, table of calibration coefficients, and data traces ¹ .	

The Analyzer settings that become saved into the Analyzer state file are the parameters, which can be set in the following submenus of the softkey menu:

- All the parameters in **Stimulus** submenu;
- All the parameters in **Measurement** submenu;
- All the parameters in **Format** submenu;
- All the parameters in **Scale** submenu;
- All the parameters in Average submenu;
- All the parameters in Display submenu except for Properties;
- All the parameters of Markers submenu;
- All the parameters of Analysis submenu;
- Ref Source and System Correction parameters in System submenu.

To save and recall a state file, you can use ten softkeys labeled **State01**, ... **State10**. Each of the softkeys correspond to a *.sta file having the same name.

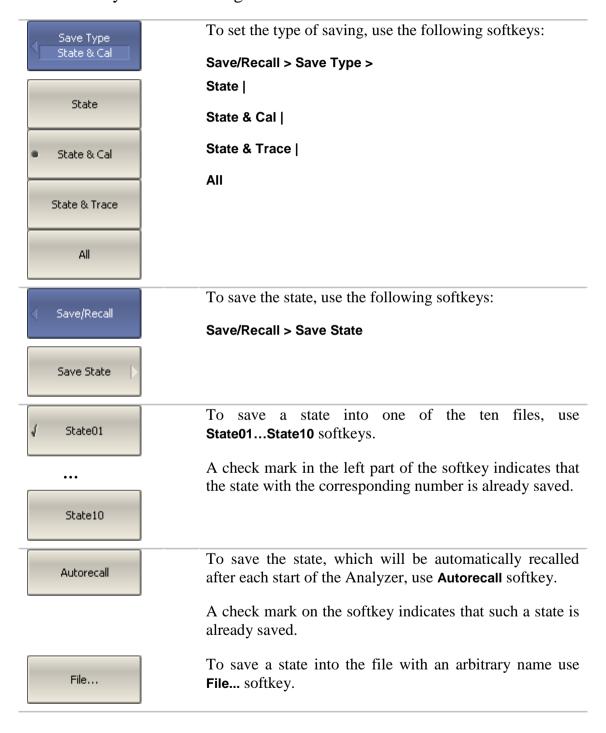
To have the Analyzer state automatically recalled after each start of the instrument use *Autorecall.sta* file. Use **Autorecall** softkey to save the corresponding file and thus enable this function.

When recalling the state with saved data traces, the trigger mode will be automatically set to «Hold», so that the recalled traces are not erased by the currently measured data.

To disable the automatic recall of the Analyzer state, delete the *Autorecall.sta* file using the specific softkey.

You can save and recall the files with arbitrary names. For this purpose use **File...** softkey, which will open the **Save as** dialog box.

7.1.1 Analyzer State Saving



7.1.2 Analyzer State Recalling

< Save/Recall	To recall the state from a file of Analyzer state, use the following softkeys:
Recall State	Save/Recall > Recall State
State01	Click the required softkey of the available State01State10.
	If the state with some number was not saved the corresponding softkey will be grayed out.
State10	
Autorecall	You can select the state automatic recall file by clicking Autorecall softkey.
File	To recall a state from the file with an arbitrary name, use File softkey.

7.2 Channel State

A channel state can be saved into the Analyzer memory. The channel state saving procedure is similar to saving of the Analyzer state saving, and the same saving types (described in section 7.1) are applied to the channel state saving.

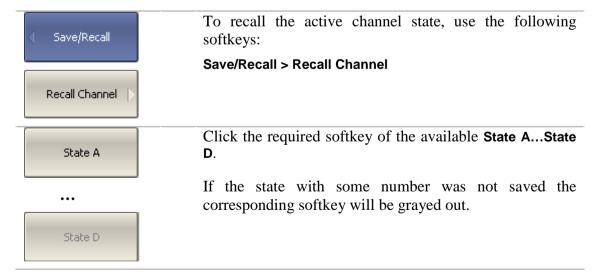
Unlike the Analyzer state, the channel state is saved into the Analyzer inner volatile memory (not to the hard disk) and is cleared when the power to the Analyzer is turned off. For channel state storage, there are four memory registers A, B, C, D.

The channel state saving allows the user to easily copy the settings of one channel to another one.

7.2.1 Channel State Saving

Save/Recall	To save the active channel state, use the following softkeys: Save/Recall > Save Channel
√ State A	To save a state into one of the four memory registers, use State AState D softkeys.
State D	A check mark in the left part of the softkey indicates that the state with the corresponding number is already saved.

7.2.2 Channel State Recalling



7.3 Trace Data CSV File

The Analyzer allows the use to save an individual trace data as a CSV file (comma separated values). The *.CSV file contains digital data separated by commas. The active trace stimulus and response values in current format are saved to *.CSV file.

Only one (active) trace data are saved to the file.

The trace data are saved to *.CSV in the following format:

I MITTE Dat	:a1, D	ata2
	•	ata2

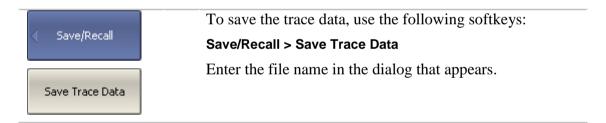
F[n] – frequency at measurement point n;

Data1 – trace response in rectangular format, real part in Smith chart and polar format;

Data2 – zero in rectangular format, imaginary part in Smith chart and polar format.

7.3.1 CSV File Saving/Recalling

To save the trace data, first activate the trace.



7.4 Trace Data Touchstone File

The Analyzer allows the user to save S-parameters to a Touchstone file. The Touchstone file contains the frequency values and S-parameters. The files of this format are typical for most of circuit simulator programs.

The *.s2p files are used for saving all the four S-parameters of a 2-port device.

The *.s1p files are used for saving S_{11} and S_{22} parameters of a 1-port device.

Only one (active) trace data are saved to the file.

Note	If a channel does not have all the S-parameter traces, only available S-parameter responses will be represented. For example, if one S_{11} trace is enabled, S_{21} response will be represented, and S_{12} and S_{22} will not be represented. The missing S-parameters are displayed as zeroes in the file.
	If full 2-port calibration is active, all the four S-parameters in a channel are measured, independently of the number of the traces.

The Touchstone file saving function is applied to individual channels. To use this function, first activate the channel.

The Touchstone file contains comments, header, and trace data lines. Comments start from «!» symbol. Header starts from «#» symbol.

The *.s1p Touchstone file for 1-port measurements:

```
! Comments

# Hz S FMT R Z0

F[0] {S<sub>11</sub>}' {S<sub>11</sub>}"

F[1] {S<sub>11</sub>}' {S<sub>11</sub>}"

. . . .

F[N] {S<sub>11</sub>}' {S<sub>11</sub>}"
```

The *.s2p Touchstone file for 2-port measurements:

```
! Comments
# Hz S FMT R ZO
           {S_{11}}'
                       {S_{11}}"
                                    {S_{21}}'
F[0]
                                                 {S_{21}}"
                                                              {S_{12}}'
                                                                          {S_{12}}"
                                                                                       {S_{22}}'
                                                                                                    {S_{22}}"
                       {S_{11}}"
F[1]
          {S_{11}}'
                                    {S_{21}}'
                                                 {S_{21}}"
                                                              {S_{12}}'
                                                                          {S_{12}}"
                                                                                       {S_{22}}'
                                                                                                    {S_{22}}"
          {S_{11}}'
                       {S_{11}}"
                                                 \{S_{21}\}"
                                                                          {S_{12}}"
F[N]
                                    {S_{21}}'
                                                              {S_{12}}'
                                                                                       \{S_{22}\}'
                                                                                                    \{S_{22}\}"
```

Hz – frequency measurement units (kHz, MHz, GHz)

FMT – data format:

- **RI** real and imaginary parts,
- MA linear magnitude and phase in degrees,
- **DB** logarithmic magnitude in dB and phase in degrees.

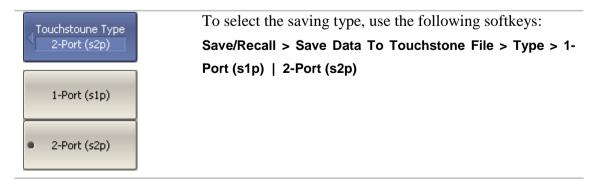
Z0 – reference impedance value

F[n] – frequency at measurement point n

{...}' - {real part (RI) | linear magnitude (MA) | logarithmic magnitude (DB)}

{...}" – {imaginary part (RI) | phase in degrees (MA) | phase in degrees (DB)}

7.4.1 Touchstone File Saving/Recalling





For 1-port saving type select the port number using the following softkeys:

Save/Recall > Save Data To Touchstone File > Select Port (s1p).



To select the data format, use the following softkeys:

Real-Imaginary

Save/Recall > Save Data To Touchstone File > Format > RI | MA | DB

Magnitude-Angle

dB-Angle



To save file to the hard disk, use the following softkeys:

Save/Recall > Save Data To Touchstone File > Save File...

Save File...

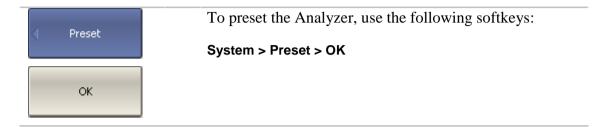
Enter the file name in the dialog that appears.

8 SYSTEM SETTINGS

8.1 Analyzer Presetting

Analyzer presetting feature allows the user to restore the default settings of the Analyzer.

The default settings of your Analyzer are specified in Appendix 1.



8.2 Graph Printing

This section describes the print/save procedures for the graph data.

The print function is provided with the preview feature, which allows the user to view the image to be printed on the screen, and/or save it to a file.

You can print out the graphs using three different applications:

- MS Word;
- Image Viewer for Windows;
- Print Wizard of the Analyzer.

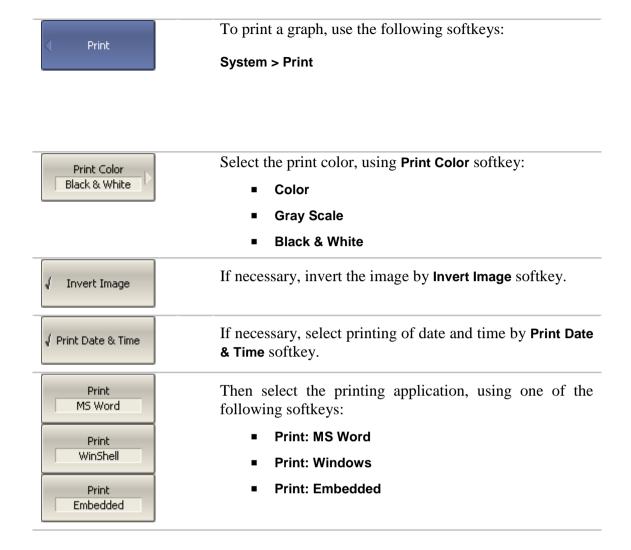
Note	MS Word application must be installed in Windows system.
Note	The Print Wizard requires at least one printer to be installed in Windows.

You can select the print color before the image is transferred to the printing application:

- Color (no changes);
- Gray Scale;
- Black & White.

You can invert the image before it is transferred to the printing application.

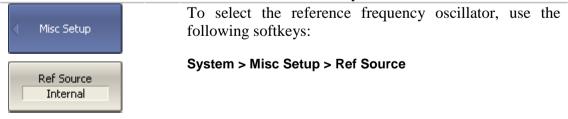
You can add current date and time before the image is transferred to the printing application.



8.3 Reference Frequency Oscillator Selection

The Analyzer can operate either with internal or with external reference frequency (10 MHz) oscillator. Initially the Analyzer is set to operation with the internal source of the reference frequency.

You can switch between these two modes in the softkey menu.



8.4 System Correction Setting

The Analyzer is supplied from the manufacturer calibrated with the calibration coefficients stored in its non-volatile memory. The factory calibration is used by default for initial correction of the measured S-parameters. Such calibration is referred to as system calibration, and the error correction is referred to as system correction.

The system correction ensures initial values of the measured S-parameters before the Analyzer is calibrated by the user. The system calibration is performed at the plane of the port physical connectors and leaves out of account the cables and other fixture used to connect the DUT. The measurement accuracy of the Analyzer without its calibration with the user setup is not rated.

Normally, the disabling of the system correction **is not required** for a calibration and further measurements.

The system correction can be disabled only in case the user provided a proper calibration for the Analyzer. The measurement accuracy is determined by user calibration and does not depend on the system correction status. The only rule that should be observes is to disable/enable the system correction before the user calibration, so that the calibration and further measurement could be performed under the same conditions.

If the system correction is disabled by the user, this is indicated in the instrument status bar.

Note	TRL calibration is not compatible with system correction. The system correction will be automatically turned off when TRL calibration is performed.



To disable/enable the system correction, use the following softkeys:

System > Misc Setup > System Correction

8.5 Beeper Setting

The Analyzer features two settings of the beeper, which can be toggled on/off independently from each other:

- *operation complete beeper* informs the user about normal completion of standard measurements during calibration;
- warning beeper informs the user about an error or a fail limit test result.



To toggle the beeper, use the following softkeys:

System > Misc Setup > Beeper > Beep Complete

System > Misc Setup > Beeper > Beep Warning

To test the beeper, use the following softkeys:

System > Misc Setup > Beeper > Test Beep Complete

System > Misc Setup > Beeper > Test Beep Warning

8.6 User Interface Setting

The Analyzer enables you to make the following user interface settings:

- Toggle between full screen and window display
- Set color of:
 - Data traces
 - Memory traces
 - Background and grid of graph
 - Background and font of menu bar
- Style and width of:
 - Data traces
 - Memory traces
 - Graph grid
- Font size of:
 - Softkeys
 - Channel window
 - Channel status bar
 - Instrument status bar
- Invert color of graph area
- Hide/show menu bar
- Hide/show stimulus graticule (X axis)
- Set response graticule mode (Y axis)
 - off
 - on for active trace
 - on for all traces

Note

The user interface settings are automatically saved and will restore when you next time turn the Analyzer on. No particular saving procedure is required. There is a button for restoration of the default factory settings for the user interface.



To toggle between full screen and window display, use the following softkeys:

Display > Properties > Full Screen

To change the color of the active data trace, use the following softkeys:

Display > Properties > Color > Data Trace

Then select the rate (from 0 to 255) of color components.

The changes made to the color of the active data traces will affect all the traces with the same number in other channels.

To change the color of the active memory trace, use the following softkeys:

Display > Properties > Color > Memory Trace

Then select the rate (from 0 to 255) of color components.

The changes made to the color of the active memory traces will affect all the traces with the same number in other channels.



Color

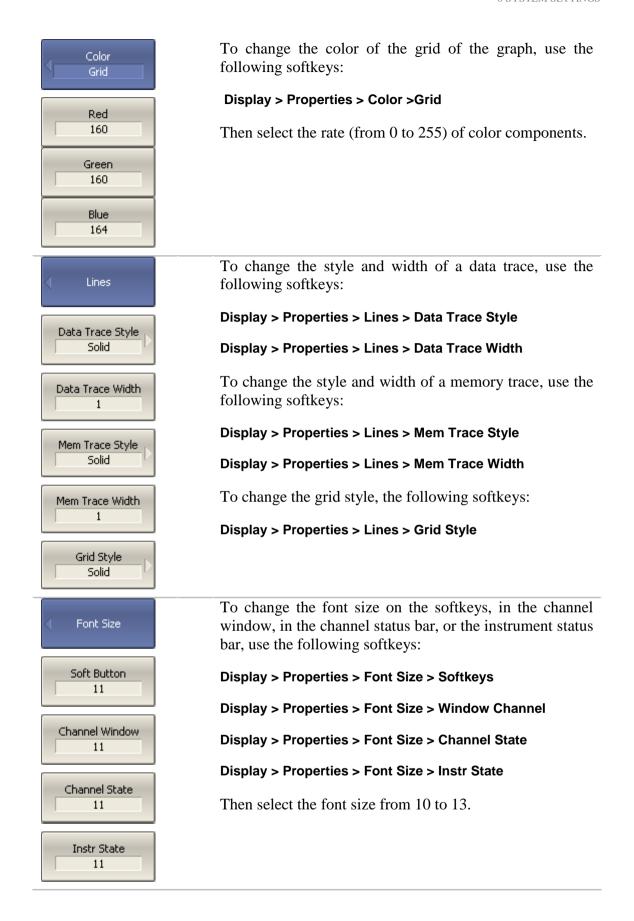
Background

To change the color of the background of the graph, use the following softkeys:

Display > Properties > Color > Background

Then select the rate (from 0 to 255) of color components.

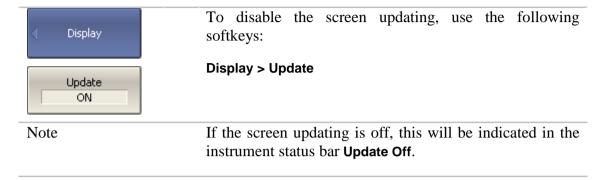




Display Properties	To invert the color of the graph area, use the following softkeys:
Invert Color	Display > Properties > Invert Color
Display Properties	To hide/show the menu bar, use the following softkeys: Display > Properties > Menu Bar
Menu Bar ON	
	To hide/show stimulus graticule (X axis), use the following softkeys:
Frequency Label ON	Display > Properties > Frequency Label
Graticule Active Trace	To set the response graticule label mode (Y axis), use the following softkeys:
OFF	Display > Properties > Graticule Label> OFF Active Trace All Traces
Active Trace	
All Traces	
	To restore the default factory settings, use the following softkeys:
Set Defaults	Display > Properties > Set Defaults

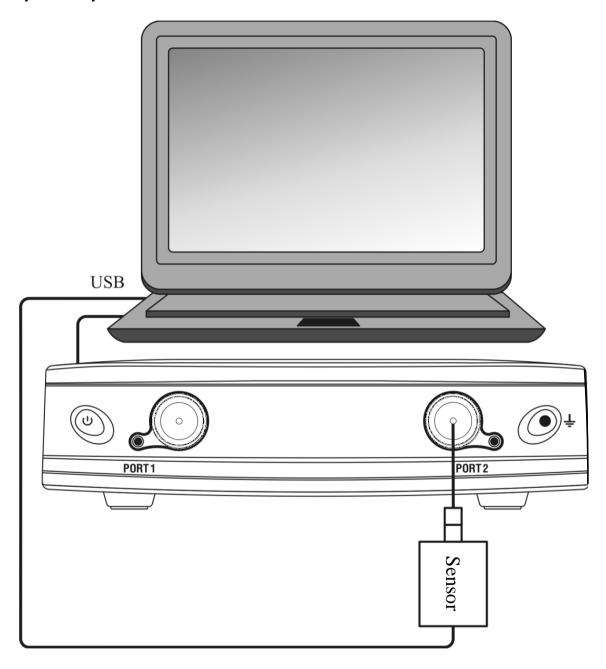
8.7 Screen Update Setting

Screen updating can be disabled to reduce the sweep time. This function can be useful during remote control over the Analyzer via COM/DCOM interfaces.



8.8 Power Meter Setting

An external power meter can be connected to the Analyzer to perform power calibration of the test ports. Connect the power meter to PC directly to USB port or via USB/GPIB adapter. Then install the power meter software. The list of the power meters supported by the Analyzer is shown in table 8.1.



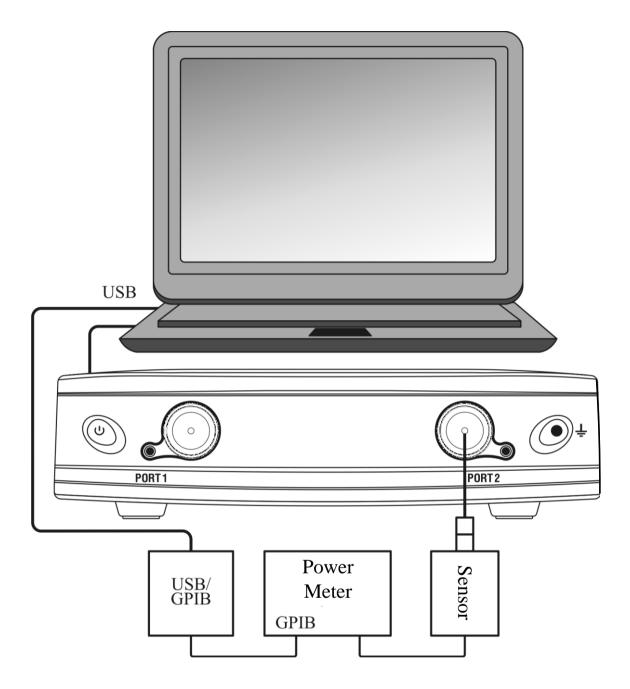
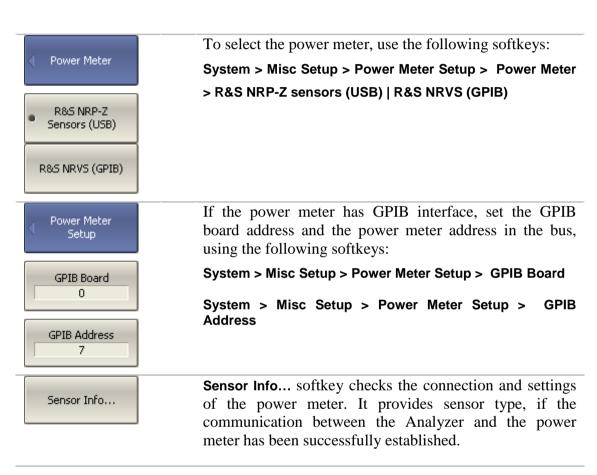


Figure 8.1 Power meter setup example

Table 8.1 Supported power meters

Tuble of pupported	1		
Power Meter	Name in Analyzer Program	USB Connection Type	Additional Software
Rohde&Schwarz NRP-Z series Sensors (without Power Meter)	R&S NRP-Z sensors	R&S NRP-Z4 Adapter	 Rohde&Schwarz NRP-Toolkit Rohde&Schwarz RSNRPZ Instrument driver

NRP-Z51 (recommended)			
Rohde&Schwarz NRVS Power Meter and NRV- Z51 or NRV-Z4 Sensors	R&S NRVS	GPIB/USB Adapter	GPIB/USB Adapter driverVISA visa32.dll Library



8.9 Stimulus Frequency Adjustment

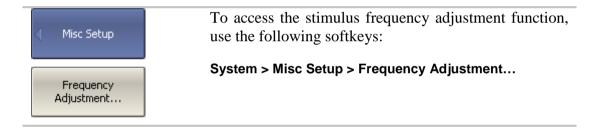
This function provides fine adjustment of the stimulus frequency by means of an external frequency counter. By setting the stimulus frequency adjustment coefficient from -128 to +127, you can perform relative adjustment of the frequency within $\pm 0.001\%$ (typical value). This setting will be saved in the nonvolatile memory of the Analyzer. The function adjusts the frequency of the internal reference frequency oscillator, so to adjust the frequency over all the operating frequency range, it is sufficient to perform the adjustment in one frequency point.

To adjust the stimulus frequency, proceed as follows:

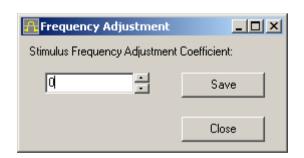
Switch the Analyzer on and warm it up to the operating temperature for 40 minutes;

Connect the frequency counter to the external reference (10 MHz) frequency connector oscillator or to one of the Analyzer test ports;

If you connect the frequency meter to a test port of the Analyzer, set this test port to the CW-frequency output operation.



In the pop-up dialog, set the stimulus frequency adjustment coefficient, which ensures the value measured by the frequency meter being closest to the output frequency of the Analyzer. Save this coefficient to the nonvolatile memory by clicking **Save** softkey.



9 MAINTENANCE AND STORAGE

9.1 Maintenance Procedures

This section describes the guidelines and procedures of maintenance, which will ensure fault-free operation of your Analyzer.

The maintenance of the Analyzer consists in cleaning of the instrument, factory calibrations, and regular performance tests.

9.1.1 Instrument Cleaning

This section provides the cleaning instructions required for maintaining the proper operation of your Analyzer.

To remove contamination from parts other than test ports and any connectors of the Analyzer, wipe them gently with a soft cloth that is dry or wetted with a small amount of water and wrung tightly.

It is essential to keep the test ports always clean as any dust or stains on them can significantly affect the measurement capabilities of the instrument. To clean the test ports (as well as other connectors of the Analyzer), use the following procedure:

- using compressed air remove or loosen the contamination particles;
- clean the connectors using a lint-free cleaning cloth wetted with a small amount of ethanol and isopropyl alcohol (when cleaning a female connector, avoid snagging the cloth on the center conductor contact fingers by using short strokes);
- dry the connector with low-pressure compressed air.

Always completely dry a connector before using it.

Never use water or abrasives for cleaning any connectors of the Analyzer.

Do not allow contact of alcohol to the surface of the insulators of the connectors.

When connecting male-female coaxial connectors always use a calibrated wrench.

	Never perform cleaning of the instrument if the power cable is connected to the power outlet.
WARNING	Never clean the internal components of the instrument.

9.1.2 Factory Calibration

Factory calibration is a regular calibration performed by the manufacturer or an authorized service center. We recommend you to send your Analyzer for factory calibration every three years.

9.1.3 Performance Test

Performance test is the procedure of the Analyzer performance verification by confirming that the behavior of the instrument meets the published specifications.

Performance test of the Analyzer should be performed in accordance with *Performance Test Instructions*.

The Analyzer software is provided with **System > Performance Test** submenu for automatic verification execution.

Performance test period is one year.

9.2 Storage Instructions

Before first use store your Analyzer in the factory package at environment temperature from 0 to +40 °C and relative humidity up to 80% (at 25 °C).

After you have removed the factory package store the Analyzer at environment temperature from +10 to +35 °C and relative humidity up to 80% (at 25 °C).

Ensure to keep the storage facilities free from dust, fumes of acids and alkalies, aggressive gases, and other chemicals, which can cause corrosion.

10 WARRANTY INFORMATION

- 1. The manufacturer warrants the Network Analyzer to conform to the specifications of this Manual when used in accordance with the regulations of operation detailed in this Manual.
- 2. The manufacturer will repair or replace without charge, at its option, any Analyzer found defective in manufacture within the warranty period, which is twelve (12) months from the date of purchase. Should the user fail to submit the warranty card appropriately certified by the seller with its stamp and date of purchase the warranty period will be determined by the date of manufacture.
- 3. The warranty is considered void if:
- a) the defect or damage is caused by improper storage, misuse, neglect, inadequate maintenance, or accident;
- b) the product is tampered with, modified or repaired by an unauthorized party;
- c) the product's seals are tampered with;
- d) the product has mechanical damage.
- 4. The batteries are not included or covered by this warranty.
- 5. Transport risks and costs to and from the manufacturer or the authorized service centers are sustained by the buyer.
- 6. The manufacturer is not liable for direct or indirect damage of any kind to people or goods caused by the use of the product and/or suspension of use due to eventual repairs.
- 7. When returning the faulty product please include the accurate details of this product and clear description of the fault. The manufacturer reserves the right to check the product in its laboratories to verify the foundation of the claim.

Manufacturer's contact information				

Appendix 1 — Default Settings Table

Default values defined in the process of the initial factory setup.

Parameter Description	Default Setting	Parameter Setting Object
Data Saving Type	State and Calibration	Analyzer
Touchstone Data Format	Real-Imaginary	Analyzer
Allocation of Channels	×1	Analyzer
Active Channel Number	1	Analyzer
Marker Value Identification Capacity (Stimulus)	7 digits	Analyzer
Marker Value Identification Capacity (Response)	4 digits	Analyzer
Marker Table	OFF	Analyzer
Reference Frequency Source	Internal	Analyzer
Trigger Signal Source	Internal	Analyzer
Reference Channel Error Correction	ON	Analyzer
System Correction	ON	Analyzer
Allocation of Traces	×1	Channel
Vertical Divisions	10	Channel
Channel Title Bar	OFF	Channel
Channel Title	Empty	Channel
«FAIL» Label Display (Limit Test)	OFF	Channel
Segment Sweep Frequency Axis Display	Frequency Order	Channel
Traces per Channel	1	Channel
Active Trace Number	1	Channel
Marker Coupling	ON	Channel
Sweep Type	Linear Frequency	Channel
Number of Sweep Points	201	Channel
Stimulus Start Frequency	20 kHz	Channel
Stimulus Stop Frequency	Maximum Analyzer frequency	Channel
Stimulus CW Frequency	20 kHz	Channel
Stimulus Start Power Level	-50 dBm	Channel

Stimulus Stop Power Level	5 dBm	Channel
Stimulus Power Level	0 dBm	Channel
Stimulus Power Slope	0 dBm	Channel
Stimulus IF Bandwidth	10 kHz	Channel
Sweep Measurement Delay	0 sec.	Channel
Sweep Range Setting	Start / Stop	Channel
Number of Segments	1	Channel
Points per Segment	2	Channel
Segment Start Frequency	20 kHz	Channel
Segment Stop Frequency	20 kHz	Channel
Segment Sweep Power Level	0 dBm	Channel
Segment Sweep IF Bandwidth	10 kHz	Channel
Segment Sweep Measurement Delay	0 sec.	Channel
Segment Sweep Power Level (Table Display)	OFF	Channel
Segment Sweep IF Bandwidth (Table Display)	OFF	Channel
Segment Sweep Measurement Delay (Table Display)	OFF	Channel
Segment Sweep Range Setting	Start / Stop	Channel
Averaging	OFF	Channel
Averaging Factor	10	Channel
Trigger Mode	Continuous	Channel
Table of Calibration Coefficients	Empty	Channel
Error Correction	OFF	Channel
Port Z Conversion	OFF	Channel
Port 1 Simulated Impedance	50 Ω/75 Ω	Channel
Port 2 Simulated Impedance	50 Ω/75 Ω	Channel
Port 1 De-embedding	OFF	Channel
Port 2 De-embedding	OFF	Channel
Port 1 De-embedding S-parameter File	Empty	Channel
Port 2 De-embedding S-parameter File	Empty	Channel
Port 1 Embedding	OFF	Channel
Port 2 Embedding	OFF	Channel
Port 1 Embedding User File	Empty	Channel
Port 2 Embedding User File	Empty	Channel
Measurement Parameter	S ₁₁	Trace
Trace Scale	10 dB / Div.	Trace
Reference Level Value	0 dB	Trace

Reference Level Position	5 Div.	Trace
Data Math	OFF	Trace
Phase Offset	0°	Trace
Electrical Delay	0 sec.	Trace
S-parameter Conversion	OFF	Trace
S-parameter Conversion Function	Z: Reflection	Trace
Trace Display Format	Logarithmic Magnitude (dB)	Trace
Time Domain Transformation	OFF	Trace
Time Domain Transformation Start	−10 nsec.	Trace
Time Domain Transformation Stop	10 nsec.	Trace
Time Domain Kaiser-Beta	6	Trace
Time Domain Transformation Type	Bandpass	Trace
Time Domain Gate	ON	Trace
Time Domain Gate Start	-10 ns	Trace
Time Domain Gate Stop	10 ns	Trace
Time Domain Gate Type	Bandpass	Trace
Time Domain Gate Shape	Normal	Trace
Smoothing	OFF	Trace
Smoothing Aperture	1%	Trace
Trace Display Mode	Data	Trace
Limit Test	OFF	Trace
Limit Line Display	OFF	Trace
Defined Limit Lines	Empty	Trace
Number of Markers	0	Trace
Marker Position	20 kHz	Trace
Marker Search	Maximum	Trace
Marker Tracking	OFF	Trace
Marker Search Target	0 dB	Trace
Marker Search Target Transition	Both	Trace
Marker Search Peak Polarity	Positive	Trace
Marker Search Peak Excursion	3 dB	Trace
Bandwidth Parameter Search	OFF	Trace
Marker Search Bandwidth Value	-3 dB	Trace
Marker Search Range	OFF	Trace
Marker Search Start	0	Trace
Marker Search Stop	0	Trace